

Case Report

Solving a Class of Nonlinear Delay Integro–differential Equations by Using Differential Transformation Method

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Abstract: In this paper, differential transformation method is used to find exact solutions of nonlinear delay integro–differential equations. Many theorems are presented that required for applying differential transformation method for nonlinear delay integro–differential equation. The validity and efficiency of the proposed method are demonstrated through several tests.

Keywords: Delay Integro–differential Equation, Delay Differential Equation, Differential Transformation Method, Closed Form Solution

1. Introduction

Finding the analytical solutions of functional equations has been devoted attention of mathematicians's interest in recent years. Several methods are proposed to achieve this purpose, such as [1]–[5]. The nonlinear integro–differential equations with variable delays reads

$$y'(t) = f(t, y(t), y(q_0 t), y(t - \tau_0), \int_{t_0}^t K(t, s, y(s), y(q_1 s), y(s - \tau_1)) ds), t \in I = [t_0, T], \quad (1)$$

subject to initial condition

$$y(t) = \phi(t), t \in [-\tilde{\tau}, t_0], \tilde{\tau} = \min\{\tau_0, \tau_1\}, \quad (2)$$

where f and ϕ are analytical function and the nonlinear kernel K is continuous on the domain

$$D = \{(t, s): t - \tilde{\tau} \leq s \leq t, t \in I\},$$

Here $q_i \in (0, 1)$, for $i = 0, 1$, are the coefficients of vanishing delay function $\theta(t) = q_i t$, which is used in the pantograph equation, and $\tau_i > 0$, for $i = 0, 1$, are the constants of non-vanishing delay $\theta(t) = t - \tau_i$, that is a classical case of delay functions.

This type of equations have widely occurred in many biological and control problems (see [6, 7] and their references therein). As we know, much work has been done on

developing and analyzing numerical methods for solving one-dimensional integral and integro–differential equations without delay. But in delay cases, a small amount of work has been done. Delay integro–differential equations are usually difficult to solve analytically so it is required to obtain an efficient approximate solution. Therefore, they have been of great interest by several authors. In literature, there exist few numerical techniques applied to solving delay integro–differential equation. The main of these literatures carried out by Hermann Brunnner, which most of the recent studies belong to him [8]–[14]. Asymptotic error expansions for linear multistep methods in [15] and Stability properties of a scheme for the approximate solution in [16] of a delay-integro-differential equation have been discussed by Baker and Ford, Brunner in [6], Brunner and et al in [12] applied a numerical method based on finite difference method and a collocation method to solving (1), and Koto in [17, 18] and W. H. Enright and Hu in [19] used Runge-Kutta method and θ –method to solving Eq. (1), respectively. In recent years, many papers have also studied the convergence and stability of numerical methods for (1) or equations of more general forms. For the convergence of numerical methods, we refer to [8]–[12], and for the stability we refer to [13]–[18] and their references therein.

The method that is developed in this paper depends on DTM, introduced by Borhanifar [20, 21] for solution of linear and nonlinear problems and Zhou [22] in a study about

electrical circuits. It is a semi–numerical–analytical technique that formulates Taylor series in a totally different manner. With this technique, the given differential equation and related initial conditions are transformed into a recurrence equation that finally leads to the solution of a system of algebraic equations as coefficients of a power series solution. This method is useful for obtaining exact and approximate solutions of linear and nonlinear differential equations. There is no need for linearization or perturbations, large computational work and round–off errors are avoided. It has been used to solve effectively, easily and accurately a large class of linear and nonlinear problems with approximations. It is possible to solve system of differential equations [23, 24, 25], differential–algebraic equations [26], difference equations [27], differential difference equations [28], partial differential equations [29, 30, 31, 32], Nonlinear partial differential equations [33], fractional differential equations [34, 35], time-fractional diffusion equation [36], pantograph equations [37], vibration problems of circular Euler-Bernoulli beams [38], Axisymmetric vibrations and buckling analysis [39], projectile motion in a quadratic resistant medium [40], one– dimensional Volterra integral and integro–differential equations [41, 42, 43] by using this method. In this work, we will extend one–dimensional differential transformation method (DTM), by presenting and proving some new theorems, to solve a class of nonlinear delay integro–differential equation which it's kernel function is also involve delay (vanishing and non–vanishing delays).

The remainder of this paper is organized as follows: The structure of differential transformation method is stated in

- (1-a) If $w(t) = u(t) \pm v(t)$, then $W(k) = U(k) \pm V(k)$.
- (1-b) If $w(t) = \lambda u(t)$, then $W(k) = \lambda U(k)$.
- (1-c) If $w(t) = \frac{d^m u(t)}{dt^m}$, then $W(k) = \frac{(k+m)!}{k!} U(k+m)$.
- (1-d) If $w(t) = u(t)v(t)$, then $W(k) = \sum_{\ell=0}^k U(\ell)V(k-\ell)$.
- (1-e) If $w(x) = x^m$ then $W(k) = \delta(k-m) = \begin{cases} 1 & k = m, \\ 0 & \text{otherwise} \end{cases}$
- (1-f) If $w(t) = u(t+a)$, then $W(k) = \sum_{\ell=k}^N \binom{\ell}{k} a^{\ell-k} U(\ell)$, for $N \rightarrow \infty$.
- (1-g) If $w(t) = \frac{d^n}{dt^n} [u(t+a)]$, then $W(k) = \frac{(k+n)!}{k!} \sum_{\ell=k+n}^N \binom{\ell}{k+n} a^{\ell-k-n} U(\ell)$, for $N \rightarrow \infty$.

Proof. See ([26], and their references).

Now we state the fundamental theorem of this paper.

Theorem 2. Assume that $W(k)$, $U_1(k)$ and $U_2(k)$, are the differential transforms of the functions $w(t)$, $u_1(q_1 t)$ and $u_2(q_2 t)$, respectively, and $q_1, q_2 \in (0, 1)$, then

- (2-a) If $w(t) = u_1(q_1 t)u_2(q_2 t)$, then $W(k) = \sum_{\ell=0}^k q_1^\ell q_2^{k-\ell} U_1(\ell)U_2(k-\ell)$.
- (2-b) If $w(t) = u(qt)v(t-\tau)$, then for $N \rightarrow \infty$

$$W(k) = \sum_{\ell=0}^k \sum_{s=k-\ell}^N \binom{s}{k-\ell} q^\ell (-\tau)^{s-k+\ell} U(\ell)V(s).$$

- (2-c) If $w(t) = u_1(t-\tau_1)u_2(t-\tau_2)$, then for $N \rightarrow \infty$

$$W(k) = \sum_{\ell=0}^k [(\sum_{s_1=\ell}^N \binom{s_1}{\ell} (-\tau_1)^{s_1-\ell} U_1(s_1)) (\sum_{s_2=k-\ell}^N \binom{s_2}{k-\ell} (-\tau_2)^{s_2-k+\ell} U_2(s_2))].$$

Proof. (2-a) By using Leibnitz formula, we get

Section 2. Hereby, some theorems are presented and proved. In Section 3, the proposed method is applied to solve several delay integro–differential equations. A conclusion is presented in Section 4.

2. Basic Idea of Differential Transformation Method

In this section, the basic definitions of differential transformation are introduced as follows:

An arbitrary function $u(t)$ that is analytical function can be expanded in Taylor series about a point $t = 0$ as

$$y(t) = \sum_{k=0}^{\infty} \frac{(t-t_0)^k}{k!} \left[\frac{d^k y(t)}{dt^k} \right]_{t=t_0}. \tag{3}$$

If $Y(k)$ is defined as

$$Y(k) = \frac{1}{k!} \left[\frac{d^k y(t)}{dt^k} \right]_{t=t_0}, \text{ where } k = 0, 1, \dots, \infty \tag{4}$$

then Eq. (3) reduces to

$$y(t) = \sum_{k=0}^{\infty} Y(k)(t-t_0)^k. \tag{5}$$

The $Y(k)$ defined in Eq. (4), is called the differential transform of function $y(t)$. The following theorems that can be deduced from Eqs. (4) and (5) are given below;

Theorem 1 Assume that $W(k)$, $U(k)$ and $V(k)$, are the differential transforms of the functions $w(t)$, $u(t)$ and $v(t)$, respectively, then

$$\frac{d^k w(t)}{dt^k} = \frac{d^k}{dt^k} [u_1(q_1 t)u_2(q_2 t)] = \sum_{\ell=0}^k \binom{k}{\ell} q_1^\ell \frac{d^\ell}{d\tilde{t}^\ell} u_1(\tilde{t}) q_2^{k-\ell} \frac{d^{k-\ell}}{d\hat{t}^{k-\ell}} u_2(\hat{t}),$$

where $\hat{t} = q_1 t$, and $\tilde{t} = q_2 t$, therefore

$$\left[\frac{d^k w(t)}{dt^k}\right]_{t=t_0} = \sum_{\ell=0}^k \binom{k}{\ell} [q_1^\ell \ell! U_1(\ell)] [q_2^{k-\ell} (k-\ell)! U_2(k-\ell)] = \sum_{\ell=0}^k k! q_1^\ell q_2^{k-\ell} U_1(\ell) U_2(k-\ell),$$

then from (6), we get

$$W(k) = \frac{1}{k!} \left[\frac{d^k w(t)}{dt^k}\right]_{t=t_0} = \sum_{\ell=0}^k q_1^\ell q_2^{k-\ell} U_1(\ell) U_2(k-\ell). \text{ where } k = 0, 1, \dots, \infty$$

(2-b) Analogously from to previous Theorems we get

$$\frac{d^k}{dt^k} w(t) = \frac{d^k}{dt^k} [u(qt)v(t-\tau)] = \sum_{\ell=0}^k \binom{k}{\ell} q^\ell \frac{d^\ell}{d\tilde{t}^\ell} u(\tilde{t}) \frac{d^{k-\ell}}{d\hat{t}^{k-\ell}} v(t-\tau),$$

where $\tilde{t} = qt$, therefore

$$\left[\frac{d^k}{dt^k} w(t)\right]_{t=t_0} = \sum_{\ell=0}^k \binom{k}{\ell} q^\ell \ell! (k-\ell)! U(\ell)V(k-\ell) = \sum_{\ell=0}^k k! q^\ell U(\ell)V(k-\ell), \tag{6}$$

where from Theorem 1-f:

$$V(k-\ell) = \sum_{s=k-\ell}^N \binom{S}{k-\ell} (-\tau)^{s-k+\ell} V(s). \tag{7}$$

By substituting the (7) in (6), we get

$$\left[\frac{d^k}{dt^k} w(t)\right]_{t=t_0} = k! \sum_{\ell=0}^k \sum_{s=k-\ell}^N \binom{S}{k-\ell} q^\ell (-\tau)^{s-k+\ell} U(\ell)V(s),$$

and therefore substituting these value in (4), the proof of (2-b) is completed.

(2-c) Analogously to part (2-a), we have

$$\frac{d^k}{dt^k} w(t) = \frac{d^k}{dt^k} [u_1(t-\tau_1)u_2(t-\tau_2)] = \sum_{\ell=0}^k \binom{k}{\ell} \frac{d^\ell}{dt^\ell} u_1(t-\tau_1) \frac{d^{k-\ell}}{dt^{k-\ell}} u_2(t-\tau_2),$$

therefore

$$\left[\frac{d^k}{dt^k} w(t)\right]_{t=t_0} = \sum_{\ell=0}^k \binom{k}{\ell} \ell! (k-\ell)! U_1(\ell)U_2(k-\ell) = k! \sum_{\ell=0}^k U_1(\ell)U_2(k-\ell), \tag{8}$$

where

$$U_1(\ell) = \sum_{s_1=\ell}^N \binom{S_1}{\ell} (-\tau_1)^{s_1-\ell} U_1(s_1), \text{ and } U_2(k-\ell) = \sum_{s_2=k-\ell}^N \binom{S_2}{k-\ell} (-\tau_2)^{s_2-k+\ell} U_2(s_2).$$

by substituting these value in (8), and using (4), the result of (3-b) is obtained, and therefore the proof is completed.

Theorem 3. Assume that $p, q \in (0,1)$, and $\tau_1, \tau_2 > 0$ then for $k = 1, 2, \dots, N$,

(3-a) If $w(t) = \int_{t_0}^t v_1(qs)v_2(s-\tau_2)ds$, then for $N \rightarrow \infty$

$$W(k) = \frac{1}{k} \sum_{\ell=0}^{k-1} \sum_{s=k-\ell-1}^N \binom{S}{k-\ell-1} q^\ell (-\tau_2)^{s-k+\ell+1} V_1(\ell)V_2(s),$$

(3-b) If $w(t) = u(pt) \int_{t_0}^t v_1(qs)v_2(s-\tau_2)ds$, then for $N \rightarrow \infty$

$$W(k) = \sum_{\ell=0}^k \sum_{\ell_0=0}^{k-\ell-1} \sum_{s=k-\ell-\ell_0-1}^N \binom{S}{k-\ell-\ell_0-1} \frac{1}{k-\ell} p^\ell q^{\ell_0} (-\tau_2)^{s-k+\ell+\ell_0+1} U(\ell) V_1(\ell_0) V_2(s).$$

(3-c) If $w(t) = u(t - \tau_1) \int_{t_0}^t v_1(qs)v_2(s - \tau_2)ds$, then $W(k) = \sum_{\ell=0}^k \mathcal{U}(\ell)\mathcal{Y}(k - \ell)$, where for $N \rightarrow \infty$,

$$\begin{aligned} \mathcal{U}(\ell) &= \sum_{s_0=\ell}^N \binom{S_0}{\ell} (-\tau_1)^{s_0-\ell} U(s_0). \\ \mathcal{Y}(k - \ell) &= \frac{1}{k - \ell} \sum_{\ell_0=0}^{k-\ell-1} \sum_{s=k-\ell-\ell_0-1}^N \binom{S}{k - \ell - \ell_0 - 1} q^{\ell_0} (-\tau_2)^{s-k+\ell+\ell_0+1} V_1(\ell_0) V_2(s). \end{aligned}$$

Proof. (3-a) Analogously, for $k = 1, 2, \dots, N$, we have

$$\frac{d^k}{dt^k} w(t) = \frac{d^{k-1}}{dt^{k-1}} [v_1(qt)v_2(t - \tau_2)] = \sum_{\ell=0}^{k-1} \binom{k-1}{\ell} q^\ell \frac{d^\ell}{d\hat{t}^\ell} v_1(\hat{t}) \frac{d^{k-\ell-1}}{dt^{k-\ell-1}} v_2(t - \tau_2),$$

where $\hat{t} = qt$, therefore

$$\left[\frac{d^k}{dt^k} w(t) \right]_{t=t_0} = \sum_{\ell=0}^{k-1} \binom{k-1}{\ell} q^\ell \ell! V_1(\ell) (k - \ell - 1)! V_2(k - \ell - 1), \tag{9}$$

where using Theorem. 1-(f)

$$V_2(k - \ell - 1) = \sum_{s=k-\ell-1}^N \binom{S}{k - \ell - 1} (-\tau_2)^{s-k+\ell+1} V_2(s). \tag{10}$$

by substituting (10) in (9), and using (4), we get

$$W(k) = \frac{1}{k!} \left[\frac{d^k}{dt^k} w(t) \right]_{t=t_0} = \frac{1}{k} \sum_{\ell=0}^{k-1} \sum_{s=k-\ell-1}^N \binom{S}{k - \ell - 1} q^\ell (-\tau_2)^{s-k+\ell+1} V_1(\ell) V_2(s),$$

and therefore the result of (4-a) is obtained.

(3-b) Let $y(t) = \int_{t_0}^t v_1(qs)v_2(s - \tau_2)ds$, then

$$\frac{d^k}{dt^k} w(t) = \frac{d^k}{dt^k} [u(pt)y(t)] = \sum_{\ell=0}^k \binom{k}{\ell} p^\ell \frac{d^\ell}{d\hat{t}^\ell} u(\hat{t}) \frac{d^{k-\ell}}{dt^{k-\ell}} y(t),$$

where $\hat{t} = pt$, therefore

$$\left[\frac{d^k}{dt^k} w(t) \right]_{t=t_0} = \sum_{\ell=0}^k \binom{k}{\ell} p^\ell \ell! U(\ell) (k - \ell)! \mathcal{Y}(k - \ell), \tag{11}$$

where using previous part (4-a), we have

$$\mathcal{Y}(k - \ell) = \frac{1}{k-\ell} \sum_{\ell_0=0}^{k-\ell-1} \sum_{s=k-\ell-\ell_0-1}^N \binom{S}{k - \ell - \ell_0 - 1} q^{\ell_0} (-\tau_2)^{s-k+\ell+\ell_0+1} V_1(\ell_0) V_2(s), \tag{12}$$

by substituting (12) in (11), and using (4), we get

$$W(k) = \sum_{\ell=0}^k \sum_{\ell_0=0}^{k-\ell-1} \sum_{s=k-\ell-\ell_0-1}^N \binom{S}{k - \ell - \ell_0 - 1} \frac{1}{k - \ell} p^\ell q^{\ell_0} (-\tau_2)^{s-k+\ell+\ell_0+1} U(\ell) V_1(\ell_0) V_2(s).$$

(3-c) Similar on (4-b), let $y(t) = \int_{t_0}^t v_1(qs)v_2(s - \tau_2)ds$, then

$$\frac{d^k}{dt^k} w(t) = \frac{d^k}{dt^k} [u(t - \tau_1)y(t)] = \sum_{\ell=0}^k \binom{k}{\ell} \frac{d^\ell}{dt^\ell} u(t - \tau_1) \frac{d^{k-\ell}}{dt^{k-\ell}} y(t),$$

then

$$\left[\frac{d^k}{dt^k} w(t) \right]_{t=t_0} = \sum_{\ell=0}^k \binom{k}{\ell} \ell! (k - \ell)! U(\ell) \mathcal{Y}(k - \ell),$$

therefore $W(k) = \sum_{\ell=0}^k U(\ell) \mathcal{Y}(k - \ell)$, where $U(\ell)$ obtained from Theorem. (1-f) as follow

$$U(\ell) = \sum_{s_0=\ell}^N \binom{S_0}{\ell} (-\tau_1)^{s_0-\ell} U(s_0),$$

and $\mathcal{Y}(k - \ell)$ is same as (12), and therefore the proof is completed.

3. Applications and Numerical Examples

In this section, we present the prototype examples to clarify the accuracy of the presented method. In these examples, we first obtain a recurrence relation for the differential transform of an integral equation and solve it by programming in MAPLE environment. These prototype examples are chosen such that there exist exact solutions for them.

Example 1. In the first example, consider the following non-linear integro-differential equation with multi

$$\sum_{\ell=0}^{k-1} (\ell + 1)U(\ell + 1)U(k - \ell) - \left(\frac{1}{2}\right)^k U(k) - \frac{3}{2} \sum_{\ell=0}^{k-1} \sum_{s_0=\ell}^{k-1} \frac{1}{k-\ell} \left(\frac{1}{2}\right)^{k-s-1} U(\ell)U(s)U(k - \ell - s - 1) = 0, \quad (14)$$

where $U(k)$ is the differential transform of $u(t)$.

Using Eqs.(14), by taking $N = 5$, the following system is obtained:

$$\begin{aligned} 2U(2) - 1 &= 0, \\ \frac{11}{4}U(2) + 3U(3) - \frac{15}{8} &= 0, \\ \frac{31}{8}U(3) + 2U(2)^2 + 4U(4) - \frac{13}{16} - U(2) &= 0 \\ \frac{79}{16}U(4) + 5U(2)U(3) + 5U(5) - \frac{39}{64}U(3) - \frac{7}{8}U(2) - \frac{1}{8} &= 0, \\ \frac{191}{32}U(5) + 6U(2)U(4) + 3U(3)^2 + 6U(6) - \frac{33}{80}U(4) - \frac{69}{128}U(3) - \frac{37}{160}U(2)^2 - \frac{13}{64}U(2) &= 0, \end{aligned} \quad (15)$$

Solving the above system and using the inverse transformation rule (5), we get the following series solution

$$u(t) = 1 + t + \frac{1}{2}t^2 + \frac{1}{6}t^3 + \frac{1}{24}t^4 + \frac{1}{120}t^5.$$

Note that when $N \rightarrow \infty$ by solving the obtained system, we get the following series solution

$$u(t) = 1 + t + \frac{1}{2!}t^2 + \frac{1}{3!}t^3 + \frac{1}{4!}t^4 + \dots + \frac{1}{N!}t^N.$$

The closed form of above series solution is $u(t) = e^t$, which is the exact solution of Eq. (13).

Example 2. In the second example, consider the following nonlinear delay integro-differential equation

$$\begin{aligned} (k + 1)U(k + 1) - \sum_{\ell=k}^N \binom{\ell}{k} (-1)^{\ell-k} U(\ell) - \frac{8}{3} \sum_{\ell=0}^{k-1} \sum_{s_0=\ell}^N \sum_{s=k-\ell-1}^N \binom{S_0}{\ell} \binom{S}{k-\ell-1} \left(-\frac{1}{2}\right)^{s_0-\ell} (-1)^{s-k+\ell+1} U(s_0)U(s) \\ = \delta(k - 1) - \frac{10}{3}\delta(k - 3) + \frac{4}{3}\delta(k - 4) - \frac{8}{9}\delta(k - 5), \end{aligned} \quad (18)$$

and the differential version of initial condition (17) is

$$U(1) - \sum_{k=0}^M (-1)^k U(k) = 0, \quad (19)$$

where $U(k)$ is the differential transform of $u(t)$.

Using Eqs.(17), by taking $M = 5$, and $N = 3$, the following system is obtained:

proportional delays

$$u'(t)u(t) - u\left(\frac{t}{2}\right) - \frac{3}{2}u\left(\frac{t}{2}\right) \int_0^t u(s)u\left(\frac{s}{2}\right)ds = 0, t \geq 0, \quad (13)$$

subject to initial condition $u(0) = 1$.

From initial condition, we get $u'(0) - 1 = 0$, then $u'(0) = 1$, therefore differential transform version of initial conditions $u(0) = 1, u'(0) = 1$ are $U(0) = 1, U(1) = 1$ respectively, and the differential transform version of Eq. (13) for $k = 1, 2, \dots, N$ is

$$\begin{aligned} &\frac{2}{3}U(2) + 3U(1) - \frac{11}{3} - \frac{4}{3}U(1)^2 + 2U(1)U(2) - \frac{5}{3}U(1)U(3) - \frac{2}{3}U(2)^2 + U(2)U(3) - \frac{1}{3}U(3)^2 = 0, \\ &\frac{13}{3}U(2) - 4U(1) + \frac{10}{3}U(1)^2 - 7U(1)U(2) + \frac{41}{6}U(1)U(3) + \frac{10}{3}U(2)^2 - 6U(2)U(3) + \frac{5}{2}U(3)^2 = 0, \\ &4U(4) + \frac{17}{3}U(3) - \frac{32}{9}U(2) + \frac{64}{9}U(1)U(2) - \frac{31}{3}U(1)U(3) - \frac{50}{9}U(2)^2 + \frac{121}{9}U(2)U(3) - \frac{22}{3}U(3)^2 - \frac{4}{3}U(1)^2 + \frac{10}{3} = 0, \quad (20) \\ &5U(5) - v\frac{10}{3}U(3) + \frac{23}{3}U(1)U(3) - \frac{85}{6}U(2)U(3) + \frac{43}{4}U(3)^2 - \frac{20}{9}U(1)U(2) + \frac{32}{9}U(2)^2 - \frac{4}{3} = 0, \\ &6U(6) - 2U(1)U(3) + \frac{22}{3}U(2)U(3) - \frac{17}{2}U(3)^2 - \frac{8}{9}U(2)^2 + \frac{8}{9} = 0, \end{aligned}$$

and using (19), we get

$$2U(1) - U(2) + U(3) - U(4) + U(5) - 1 = 0, \quad (21)$$

Solving the system (20) and differential transform version of initial condition (19), simultaneously, and using the inverse transformation rule (5), we get the following series solution

$$u(t) = 1 + t + t^2.$$

Note that for $M > 5$ and $N \rightarrow \infty$ we evaluate the same solution, which is the exact solution of Eq.(16) with the initial conditions (17).

Example 3. Finally, consider the following nonlinear delay integro-differential equation

$$\begin{aligned} &\sum_{\ell=0}^k (\ell + 1)U(\ell + 1)U(k - \ell) + \sum_{\ell=k}^N \binom{\ell}{k} \left(-\frac{1}{2}\right)^{\ell-k}U(\ell) - \frac{4}{k} \sum_{\ell=0}^{k-1} \sum_{s=k-\ell-1}^N \binom{s}{k - \ell - 1} \left(-\frac{1}{2}\right)^{s-k+\ell+1}U(\ell)U(s) \\ &= \frac{5}{4}\delta(k) - \frac{17}{2}\delta(k - 2) + \delta(k - 3) + 3\delta(k - 4) - \frac{5}{4}\delta(k - 5), \end{aligned} \quad (24)$$

and the differential version of initial condition (23) is

$$U(1) - \sum_{k=0}^M \left(-\frac{1}{2}\right)^k U(k) = \frac{5}{4}, \quad (25)$$

where $U(k)$ is the differential transform of $u(t)$.

Using Eqs.(23), by taking $M = 5$, and $N = 3$, the following system is obtained:

$$\begin{aligned} &U(1)^2 + 3U(1) + \frac{5}{4}U(3) - \frac{3}{4}U(4) - 4 = 0, \\ &\frac{5}{2}U(1)U(2) + 3U(2) + \frac{5}{2}U(4) - 4U(1) + U(1)^2 + \frac{1}{4}U(1)U(3) - \frac{1}{8}U(1)U(4) + \frac{17}{2} = 0, \\ &3U(1)U(3) + \frac{5}{3}U(2)^2 + 3U(3) - \frac{8}{3}U(2) - \frac{4}{3}U(1)^2 + 2U(1)U(2) + \frac{2}{3}U(1)U(4) + \frac{1}{6}U(2)U(3) \\ &\quad - \frac{1}{12}U(2)U(4) - 1 = 0, \\ &\frac{7}{2}U(1)U(4) + 4U(2)U(3) + 5U(5) + 3U(4) - 2U(3) - 2U(1)U(2) + 2U(1)U(3) + U(2)^2 \\ &\quad + \frac{1}{2}U(2)U(4) + \frac{1}{8}U(3)^2 - \frac{1}{16}U(3)U(4) - 3 = 0, \\ &6U(1)U(5) + \frac{23}{5}U(2)U(4) + \frac{12}{5}U(3)^2 + 6U(6) - \frac{8}{5}U(4) - \frac{8}{5}U(1)U(3) + 2U(1)U(4) - \frac{4}{5}U(2)^2 \\ &\quad + 2U(2)U(3) + \frac{1}{2}U(3)U(4) - \frac{1}{20}U(4)^2 + \frac{4}{5} = 0, \end{aligned} \quad (26)$$

and using (25), we get

$$\frac{1}{2}U(1) + \frac{1}{4}U(2) - \frac{1}{8}U(3) + \frac{1}{16}U(4) - \frac{1}{32}U(5) - \frac{1}{4} = 0, \quad (27)$$

Solving the system (26) and differential transform version of initial condition (25), simultaneously, and using the inverse transformation rule (5), we get the following series solution

$$u(t) = 1 + t - t^2.$$

Note that for $M > 5$ and $N \rightarrow \infty$ we evaluate the same solution, which is the exact solution of Eq.(22) with the initial

$$\begin{aligned} &u'(t)u(t) + u\left(t - \frac{1}{2}\right) - 4 \int_0^t u(s)u\left(s - \frac{1}{2}\right)ds = \frac{5}{4} - \frac{17}{2}t^2 + \\ &t^3 + 3t^4 - \frac{5}{4}t^5, t \geq 0, \end{aligned} \quad (22)$$

subject to initial condition $u(t) = 1$, for $t \in [-\frac{1}{2}, 0]$.

From initial condition, we get $u(0) = 1$, therefore by substituted $t = 0$, in Eq. (22) we get

$$u'(0) - u\left(-\frac{1}{2}\right) = \frac{5}{4}, \quad (23)$$

Similar on previous examples, the differential transform version of Eq. (22) for $k = 1, 2, \dots, M$ and for $N \rightarrow \infty$ is

conditions (23).

4. Conclusions

In this paper, we have shown that the differential transformation method can be used successfully for solving the nonlinear delay integro-differential equations. New theorems were presented with their proofs and as application some prototype examples were carried out. It is worth noting that DTM does not require complex computational work such as Adomian polynomials in Adomian decomposition and

Lagrange multipliers by solving stationary equations in variational iteration method.

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