Modeling and Simulation Study of the Population Dynamics of Commensal-Host-Parasite System

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Abstract: This paper deals with the modeling and simulation study of Commensal-host species system together with the inclusion of parasite population. The model comprises of three populations viz. Host, Commensal and Parasite. The Commensal population gets benefit from Host population but the former do not do any harm to the latter. The parasite population gets benefit and also do harm to Host population. However, the Commensal population only harms the parasites. The mathematical model is comprised of a system of three first order non-linear ordinary differential equations. Mathematical analysis of the model is conducted. Positivity and boundedness of the solution have been verified and thus shown that the model is physically meaningful and biologically acceptable. Scaled model is constructed so as to reduce the number of model parameters. Equilibrium points of the model are identified and stability analysis is conducted. Simulation study is conducted in order to support the mathematical analysis. In the present model the Commensal population lies higher and the parasite population lies below respectively the host population. This fact is well supported by the mathematical analysis as well as simulation study. The results of analysis and simulation are presented and discussed lucidly in the text of the paper.

Keywords: Commensalism, Parasite, Stability, Eco-epidemiology, Numerical Simulation

1. Introduction

It has been the general observation that populations can sometimes undergo drastic changes in their abundance. These changes are not only unexpected but also are equally difficult to explain in simple manner either theoretically or empirically [1-2]. Many species have been driven to extinct and many others are at the verge of extinction due to several reasons such as overexploitation, predation, and the like [3]. In nature populations may interact in different ways with one another during their lifetime and even they may undergo from one type of interaction to another.

The species populations in an ecosystem will interact in different ways and these interactions can be regarded as positive (+), negative (-) or neutral (0). For instance the interactions such as mutualism and commensalism are positive interactions while those such as intra and inter-specific competitions, parasitism and predation are

considered as negative interactions.

Mathematical representations have been developed to address all these kinds of interactions.

In general, in case of a two-species interaction the mathematical formulation can be expressed by a system of two equations as

$$\frac{dN_i}{dt} = r_i N_i \left[1 - \left(\frac{N_i}{k_i} \right) + a_{ij} \left(\frac{N_j}{k_j} \right) \right] \quad (1)$$

Here in (1) $i, j = 1, 2$ but $i \neq j$. The parameters r_i and k_i represent the intrinsic growth rate and carrying capacity of the species i respectively. The variables N_i and N_j represent the population densities of the species i and j respectively. The quantity a_{ij} is the interaction coefficient between species i and j .

Some classical forms of the models addressing two interacting populations are represented by these types of system of equations depending on the signs of the interaction

coefficients a_{ij} . In general, the positive sign of interaction coefficient indicates commensalism and mutualism while the negative sign of that indicates competition and predation. Also, the negative interaction includes all predator-prey and parasite-host relationships [4, 5]. In general, the Host-Parasite interaction or parasitism is referred to as negative.

According to equation (1), in absence of the species j , the species i will grow logistically and reaches its equilibrium value or carrying capacity k_i over the time from any positive initial density and continues to persist for ever. From this the following two facts can be observed: (i) the interactions between the species i with j are facultative. That is, species i can exist with or without being associated to species j and (ii) density-dependent mechanisms of species i alone govern the dynamics of the species i .

However, it is well known that some symbiont is biologically incapable of existing without a partner: Let it be a mutualistic or a parasite or a predator. If the species i cannot persist alone in absence of species j , then the former's population size N_i is expected to decrease exponentially down to zero. To account the absence of species j , the equation (1) is modified by setting $N_j = 0$ as

$$\frac{dN_i}{dt} = r_i N_i \left[1 - \left(\frac{N_i}{k_i} \right) \right] \quad (2)$$

The literature on the mathematical modeling of the negative interactions is very abundant [6-9]. But the modeling of positive interactions, particularly commensalistic ones have generated interest among researchers in recent years.

Historically, the mutualistic interaction model that is described by Monod function form is elucidated by the following systems of ordinary differential equations:

$$\frac{dN_1}{dt} = r_1 N_1 \left[1 - \frac{N_1}{k_1 + a_{12} N_2} \right] \quad (3)$$

$$\frac{dN_2}{dt} = r_2 N_2 \left[1 - \frac{N_2}{k_2 + a_{21} N_1} \right] \quad (4)$$

Now based on these mutualistic model equations (3) – (4), in the present work it is proposed to derive an ecological model that describes commensalism.

Recall that commensalism (0, +) is a relation in which one of the species known as the Commensal gets benefit without harming or affecting the other called the host.

The reduction of mutualism to commensalism leads to setting of conditions on interaction coefficients as $a_{12} = 0$ and $a_{21} > 0$. Thus, the mutualistic model becomes a commensal model and the system (3) and (4) reduces to the form as

$$\frac{dN_1}{dt} = r_1 N_1 \left[1 - \frac{N_1}{k_1} \right] \quad (5)$$

$$\frac{dN_2}{dt} = r_2 N_2 \left[1 - \frac{N_2}{k_2 + a_{21} N_1} \right] \quad (6)$$

This model represents increase of N_2 population when N_1 increases. That is, the growth of N_2 population is somehow proportional to N_1 . However, the growth of N_2 will neither

harm nor influence in any manner that of N_1 .

The main objective of the present research is to study the dynamical behavior of a negative interaction between species assuming that the growth of commensal follows Monod functional response [10-11].

The paper is structured in a systematic manner. In section 2, the basic assumptions and mathematical formulations of the model are presented. In section 3, the results on two-dimensional sub-communities are briefly presented. The modeling is extended to three-dimensional communities and incorporated mathematical analysis and other results including stability analysis of equilibrium points. Finally, numerical examples are carried out and concluding remarks of the study with a brief discussion is presented in Section 4.

2. Basic Assumptions and Model Formulation

Mathematical ecology and epidemiology are major fields of study that have been separately treated by different researchers [3, 12-13]. Since transmissible disease in ecological situation cannot be ignored, it is very important from both the ecological and the mathematical points of view that the dynamics of ecological populations be studied subjected to epidemiological factors. A large number of studies have been conducted in this field of research [14-15]. In the common life, the disease may spread among the host and the commensal. Mathematical model plays an ever more important role in the study of eco-epidemiology. Furthermore, it provides understanding of the underlying mechanisms that influence the spread of disease and in the process it also suggests control strategies [6, 16-20].

The present study is conducted in a systematic way. Initially, simple mathematical models for a two-dimensional Commensal-host and host-parasite systems are framed separately. Finally, the model is extended to three-dimensional case which is of prime importance of this study [21]. The model equations for two species host-Commensal, host-parasite systems and then for three species system will be presented in terms of system of first order non-linear differential equations.

Let us start with considering the interaction between two species in which commensal would be benefited without harming the host. Both the commensal and host populations would follow logistic functional growths if the two populations live separately. However, in presence of host the logistic growth of commensal population would be influenced by Monod response function. The population dynamics of such commensal-host system can be mathematically modeled as

$$\frac{dx}{dt} = r_1 x \left(1 - \frac{x}{k_1} \right) + \left(\frac{\beta_1 xy}{\alpha_1 + x} \right) \quad (7)$$

$$\frac{dy}{dt} = r_2 y \left(1 - \frac{y}{k_2} \right) \quad (8)$$

Let us continue with considering the interaction between

two species in which parasite would be benefited by harming the host. The host population grows following logistic function and the parasite population decreases proportional to its size if the two populations live separately. However, if both the host and parasite populations live together their growths will be influenced by Monod response functions. The population dynamics of such host-parasite system can be mathematically modeled as

$$\frac{dy}{dt} = r_2 y \left(1 - \frac{y}{k_2}\right) - \left(\frac{\beta_2 y z}{\alpha_2 + y}\right) \quad (9)$$

$$\frac{dz}{dt} = -\partial z + \left(\frac{\beta_3 y z}{\alpha_3 + y}\right) \quad (10)$$

In this study, considering and carefully studying the mathematical modeling of two dimensional systems of commensal-host and host-parasite, the concept is extended to the three dimensional commensal-host-parasite systems.

Hence, the three dimensional commensal-host-parasite systems can be mathematically modeled using first order nonlinear ordinary differential equations as follows:

$$\frac{dx}{dt} = r_1 x \left(1 - \frac{x}{k_1}\right) + \left(\frac{\beta_1 xy}{\alpha_1 + x}\right) + \gamma g(x, z) \quad (11)$$

$$\frac{dy}{dt} = r_2 y \left(1 - \frac{y}{k_2}\right) - f(y, z) \quad (12)$$

$$\frac{dz}{dt} = -\mu z + k(z, y) - \alpha h(z, x) \quad (13)$$

Here in (11-13), the functions $f(y, z)$ and $k(z, y)$ represent the interactions between host and parasite populations where as $g(x, z)$ and $h(z, x)$ represent the interactions between commensal and parasite populations with varying coefficients of interactions.

Majority of the models assume that the parasite population increases the death rate of the host population and enhance the commensal population. This fact is visualized in the model equations too.

Table 1. Notations and descriptions of the model parameters.

Notation	Description
r_1, k_1	Growth rate and carrying capacity of commensal population
(r_1/k_1)	Self inhibition coefficient of commensal population
r_2, k_2	Growth rate and carrying capacity of host population
(r_2/k_2)	Self inhibition coefficient of host population
β_1	The interaction coefficient of commensal-host populations
β_2, β_3	The interaction coefficients of host-parasite populations
μ	Total death rate of parasites
α_1	Response rate between host and commensal
α_2, α_3	Response rates between host and parasite
γ	Interaction coefficient between commensal and parasite

The model variables $X(t)$, $Y(t)$ and $Z(t)$ represent the sizes of commensal, host and parasite populations respectively at any time t .

The three model equations for (dx/dt) , (dy/dt) and (dz/dt) are constructed using several components, both variables and parameters, and each of which represents specific biological assumptions.

The simple schematic interactions among the model variable is shown in the figure below.

Figure 1. Interaction and flow diagram of the three species system.

3. Two Dimensional Sub-systems

Now the commensal-host and parasite-host models are stated in what follows.

The ecological system under consideration consists of three species namely (i) Commensal population $x(t)$ (ii) host population $y(t)$ and (iii) parasite population $z(t)$.

The Commensal-Host system: The host commensal model with type I functional response and carrying capacities is expressed as [21]

$$\frac{dx}{dt} = r_1 x \left(1 - \frac{x}{k_1}\right) + \beta xy \quad (14)$$

$$\frac{dy}{dt} = r_2 y \left(1 - \frac{y}{k_2}\right) \quad (15)$$

However, this model does not include any other external forces like parasites. To fill the gap the present study modifies this model by including parasite population.

The classical Lotka – Volterra model describes exponential growth of host and exponential decay of parasite populations. Also, the model equations accommodate Holling type I functional responses. Recall that, Holling type I functional response is linear. The simple form of the Lotka – Volterra model is given in terms of ODEs as [6, 22]

$$\frac{dy}{dt} = y(1 - \epsilon z) \quad (16)$$

$$\frac{dz}{dt} = z(-\partial + \epsilon ky) \quad (17)$$

The classical Lotka – Volterra model is structurally unstable since the model allows the population to grow indefinitely and this is very unnatural and unrealistic. However, it can be used as groundwork for constructing more realistic representations [23]. To overcome this instability carrying capacity is required to be incorporated. The, interaction between host-parasite system can be modified with the inclusion of carrying capacity as

$$\frac{dy}{dt} = r_2 y \left(1 - \frac{y}{k_2}\right) - \epsilon y z \quad (18)$$

$$\frac{dz}{dt} = -\partial z + \epsilon k y z \quad (19)$$

In the modified model the response function is still linear. But type II response is more realistic than type I functional

response. Thus, the model can be further modified by replacing type I functional response by type II response as

$$\frac{dy}{dt} = r_2 y \left(1 - \frac{y}{k_2}\right) - \epsilon f(y, z) \quad (20)$$

$$\frac{dz}{dt} = -\partial z + \beta g(y, z) \quad (21)$$

The model (20) can be interpreted that the infected hosts are immediately eradicated as it is represented by the functional response $-\epsilon f(y, z)$ in the host equation. This implies that the infected hosts have no ability to recover from the disease.

Now, in the present work the two species systems (14), (15), (20) and (21) are combined and formulated a three species system with the incorporation of the following features: (i) carrying capacities and functional responses are assigned to both the species: Commensal and Host (ii) no recovery is possible for the Host species once they get infected. It is also possible that the commensal species will change their behavior in a long run of time and act as parasites. However, this possibility is not considered here in the present study and the authors plan to take it up as their next study.

3.1. The Three Dimensional Systems

It is well known that Epidemiology and Ecology are two major and different fields of research. There are many epidemiological models and many ecological models, but certainly few models of the eco-epidemiology [1-3, 12-13, 23-24].

The presence of logistic and functional response terms in the host equation can be interpreted as the natural growth rate and mortality rate due to parasites respectively. Here arise three cases: (i) if the logistic term dominates the functional response term the host population grows with positive growth rate (ii) if both the logistic and the functional response terms are equal then growth rate of the host population becomes zero. That is the host population size remains constant and

(iii) if the functional response term is allowed to dominate logistic term then the host population grows with negative growth rate and eventually the population size extinct. This situation is not desirable. This possibility can be avoided by decreasing parasite population through the inclusion of parasite-commensal interaction [10- 11].

A three dimensional host-commensal-parasite system is formulated here to describe the host-parasite interactions. The model also includes the logistic growth rates for host and commensal populations. The total mortality rate of parasites due to natural death, increment of commensal and reduction of hosts is also accommodated.

In view of the above, it is clear that the introduction of commensal population into host-parasite system plays a significant and complex role in the dynamical advancement of host-parasite interaction [11].

The objective of this study is to identify the influence of commensal on the dynamics of host-parasite interaction in the context of eco-epidemiology. The model, including all the aforementioned assumptions, for commensal-host-parasite interaction is constructed by combining systems (14), (15), (20) and (21). It can be expressed as a system of differential equations as follows:

$$\frac{dx}{dt} = r_1 x \left(1 - \frac{x}{k_1}\right) + \left(\frac{\beta_1 xy}{\alpha_1 + x}\right) + \gamma xz \quad (22)$$

$$\frac{dy}{dt} = r_2 y \left(1 - \frac{y}{k_2}\right) - \left(\frac{\beta_2 yz}{\alpha_2 + y}\right) \quad (23)$$

$$\frac{dz}{dt} = -\mu z + \left(\frac{\beta_3 yz}{\alpha_3 + y}\right) - \alpha z x \quad (24)$$

Here in this system, the initial conditions of the model variables are $x_0 > 0, y_0 > 0, z_0 > 0$.

To reduce the number of model parameters and to determine which combinations of parameters control the behavior of the system, the system (22), (23) and (24) is dimensionalize with the following scaled parameters:

$$\begin{aligned} r &= \left(\frac{r_1}{r_2}\right); r_1 \ll r_2; 0 < r < 1; m = \left(\frac{1}{k_1}\right); \beta = \left(\frac{\beta_1}{r_1 \alpha_1}\right); h_1 = \left(\frac{1}{\alpha_1}\right); \\ \delta &= \left(\frac{\gamma}{r_1}\right); h_2 = \left(\frac{1}{k_2}\right); k = \left(\frac{\beta_2}{r_2 \alpha_2}\right); m_1 = \left(\frac{1}{\alpha_2}\right); \sigma = \left(\frac{\mu}{r_1}\right); \epsilon = \left(\frac{\beta_3}{r_1 \alpha_3}\right); \\ m_2 &= \left(\frac{1}{\alpha_3}\right); \theta = \left(\frac{\alpha}{r_1}\right) \end{aligned}$$

After manipulation the system (22), (23) and (24) takes the form in terms of scaled quantities as

$$\frac{dx}{dt} = x - mx^2 + \left(\frac{\beta xy}{1+h_1 x}\right) + \delta xz \quad (25)$$

$$r \frac{dy}{dt} = y - h_2 y^2 - \left(\frac{kyz}{1+m_1 y}\right) \quad (26)$$

$$\frac{dz}{dt} = -\sigma z + \left(\frac{\epsilon yz}{1+m_2 y}\right) - \theta zx \quad (27)$$

Further, all the model parameters and hence the scaled

parameters are supposed to be positive constants.

3.2. Dynamical Behavior of the System

Since the state variables x, y and z represent population sizes, positivity implies that the population sizes never become negative. The boundedness may be interpreted as a natural restriction to the growth of populations as consequences of limited resources.

Here, some basic dynamical properties of the system are discussed subjected to positive initial conditions.

Let R^+ denote the set of all non-negative real numbers and $R^3_+ = \{X \in R^3: X = (x, y, z) \text{ and } x, y, z \in R^+\}$. When the functions on the right-hand of the model equations (22), (23) and (24) are denoted by a vector as $F = (f_1, f_2, f_3)$ then clearly $F \in C(R^3_+)$.

The fundamental theorem of existence and uniqueness assures the existence and uniqueness of the solution for the model system together with the given initial conditions.

3.2.1. Positivity of the Solution

Here the positivity of each population size such as $x(t)$, $y(t)$ and $z(t)$ is verified. These system variables must have the positive values in order to be biologically meaningful. The positivity of these biological or system variables is tested and the results are presented in the form of a lemma as follows:

Lemma 1 Every solution of system (22), (23) and (24) together with the positive initial conditions exists in the interval $[0, \infty)$ and they are non-negative. That is, $x(t), y(t)$ and $z(t) \geq 0$ for all $t \geq 0$.

Proof For $t \in [0, T]$, as the system is continuous and locally Lipschitzian C , then the solution $x(t)$, $y(t)$ and $z(t)$ of the system with given initial conditions exists and unique on $[0, T]$ where $0 < T < +\infty$.

Verifying the positivity of $x(t)$: The commensal equation of the system (22) is solved analytically and its solution is obtained as

$$x(t) = x_0 \exp \left[\int \left\{ r_1 \left(1 - \frac{x}{k_1} \right) + \left(\frac{\beta_1 y}{\alpha_1 + x} \right) + \gamma z \right\} dt \right]$$

The exponential function is always non-negative and the initial commensal population x_0 is assumed to be positive. Therefore, $x(t) > 0$ for all $t \geq 0$.

Verifying the positivity of $y(t)$: The host equation of the system, (23) and is solved analytically and its solution is obtained as

$$y(t) = y_0 \exp \left[\int \left\{ r_2 \left(1 - \frac{y}{k_2} \right) - \left(\frac{\beta_2 z}{\alpha_2 + y} \right) \right\} dt \right]$$

The exponential function is always non-negative and the initial host population y_0 is assumed to be positive. Therefore, $y(t) > 0$ for all $t \geq 0$.

Verifying the positivity of $z(t)$: The parasite equation of the system (24) is solved analytically and its solution is obtained as

$$z(t) = z_0 \exp \left[\int \left\{ \left(\frac{\beta_3 y}{\alpha_3 + y} \right) - \alpha x - \mu \right\} dt \right]$$

The exponential function is always non-negative and the initial host population z_0 is assumed to be positive. Therefore, $z(t) > 0$ for all $t \geq 0$.

Hence, all the solutions of the system (22), (23) and (24) are positive for all $t \geq 0$ under the considered positive initial conditions.

3.2.2. Boundedness of the System

In this section, all the solutions of system (22), (23) and (24) are shown to be bounded. The boundedness of the

system is presented in the form of a lemma as follows:

Lemma 2 All solutions of the system (22), (23) and (24) with positive initial conditions are bounded as $x \leq (1/m)[1 + \beta k_2 + \delta c]$, $y \leq k_2$ and $z \leq c$. Here c is strictly a positive constant.

Proof: Boundedness of the host population: To show that the host population is bounded it is appropriate to start with the scaled host equation from the model system.

Thus,

$$r \frac{dy}{dt} = y - h_2 y^2 - \left(\frac{kyz}{1 + m_1 y} \right)$$

It is true that the term $[kyz/(1 + m_1 y)]$ is positive since each member of it is a positive quantity. Thus, without loss of generality the host population equation can be re-expressed as:

$$r \frac{dy}{dt} \leq y - h_2 y^2$$

Performing of some simple algebraic manipulations and also using partial fractions reduces it to: $\left[\frac{h_2}{1 - h_2 y} + \frac{1}{y} \right] dy \leq \left(\frac{1}{r} \right) dt$

Application of integration reduces it to: $\log \left[\frac{y}{1 - h_2 y} \right] \leq \left(\frac{1}{r} \right) t + \log c_1$

Here the quantity c_1 is an arbitrarily integral constant and must be positive. Applications of anti-logarithm lead the inequality to: $[y/(1 - h_2 y)] \leq c_1 e^{t/r}$ or Equivalently $y[1 + c_1 h_2 e^{t/r}] \leq c_1 e^{t/r}$

$$y \leq \frac{c_1 e^{t/r}}{[1 + c_1 h_2 e^{t/r}]}$$

$$y \leq \frac{c_1}{[e^{-(1/r)t} + c_1 h_2]}$$

Now $e^{-(1/r)t} \rightarrow 0$ as $t \rightarrow \infty$. Thus, the inequality for y takes the form as: $y \leq \frac{1}{h_2}$.

But $h_2 = \left(\frac{1}{k_2} \right)$. That is $y \leq k_2$. Therefore the host population $y(t)$ is bounded above by its carrying capacity k_2 .

Boundedness of the parasite population: To show that the parasite population is bounded it is appropriate to start with the scaled parasite equation from the model system.

Thus,

$$\frac{dz}{dt} = -\sigma z + \left(\frac{\epsilon y z}{1 + m_2 y} \right) - \theta z x$$

It is true that the term $(\theta z x)$ is positive since each member of it is a positive quantity. Thus, without loss of generality the parasite population equation can be re-expressed as:

$$\frac{dz}{dt} \leq -\sigma z + \left(\frac{\epsilon y z}{1 + m_2 y} \right)$$

$$\left(\frac{1}{z}\right) \frac{dz}{dt} \leq -\sigma + \left(\frac{\varepsilon y}{1+m_2 y}\right)$$

But, $\left(\frac{\varepsilon y}{1+m_2 y}\right) = \left(\frac{\beta_3}{r_1}\right) \left(\frac{y}{\alpha_3+y}\right) \leq \left(\frac{\beta_3}{r_1}\right)$ since $\left(\frac{y}{\alpha_3+y}\right) \leq 1$.

Thus, the inequality can be re-expressed as

$$\left(\frac{1}{z}\right) \frac{dz}{dt} \leq -\sigma + \left(\frac{\beta_3}{r_1}\right)$$

On applying integration, it can be obtained that

$$\log z \leq \left[-\sigma + \left(\frac{\beta_3}{r_1}\right)\right] t + \log c.$$

This equivalent to: $z \leq c e^{\left[-\sigma + \left(\frac{\beta_3}{r_1}\right)\right] t}$.

Here the quantity c is an arbitrarily integral constant and must be strictly positive due to logarithmic function.

Now there arise three cases, namely the exponent may be negative or positive or zero. These cases as analyzed as follows:

- (i) If $\left[-\sigma + \left(\frac{\beta_3}{r_1}\right)\right] < 0$ then as $t \rightarrow \infty$ the exponential term takes a value zero and thus to get $z \leq 0$. But this, having negative parasite population, is biologically not feasible. Hence this possibility is not considered.
- (ii) If $\left[-\sigma + \left(\frac{\beta_3}{r_1}\right)\right] > 0$ then as $t \rightarrow \infty$ the exponential term takes a value ∞ and thus to get $z \leq \infty$. But this, having ∞ parasite population, is biologically not feasible. It is an unbounded case. Hence this possibility is not considered.
- (iii) If $\left[-\sigma + \left(\frac{\beta_3}{r_1}\right)\right] = 0$ then as $t \rightarrow \infty$ the exponential term takes a value 1 and thus reduces to $z \leq c$. Hence this possibility is not considered. Thus the parasite population z is bounded above by an arbitrarily positive constant c .

Boundedness of the commensal population: To show that the commensal population is bounded it is appropriate to start with the scaled commensal equation from the model system. Thus,

$$\frac{dx}{dt} = x - mx^2 + \left(\frac{\beta xy}{1+h_1 x}\right) + \delta xz$$

$$\frac{dx}{dt} = x \left[1 - mx + \left(\frac{\beta y}{1+h_1 x}\right) + \delta z\right]$$

It has been already shown that the population sizes of host and parasite are bounded. That is, $y \leq k_2$ and $z \leq c$. Here it can be observed that $\delta z \leq \delta c$ and $\left(\frac{\beta y}{1+h_1 x}\right) < \beta y \leq \beta k_2$. In view of these observations the commensal equation takes the form as:

$$\frac{dx}{dt} \leq x[1 - mx + \beta k_2 + \delta c]$$

$$\frac{dx}{dt} \leq x[q - mx]$$

Here $q = [1 + \beta k_2 + \delta c]$ is strictly a positive quantity. Applying partial fraction and integrating: $\log \left[\frac{x}{q-mx}\right] \leq qt + \log c_2$

Here the quantity c_2 is an arbitrarily integral constant and must be strictly positive due to logarithmic function.

$$\left[\frac{x}{q-mx}\right] \leq c_2 e^{qt}$$

$$x \leq \frac{c_2 q e^{qt}}{1 + m c_2 e^{qt}}$$

$$\text{Thus, } x \leq \frac{c_2 q}{e^{-qt} + m c_2}$$

It can be observed that $e^{-qt} \rightarrow 0$ as $t \rightarrow \infty$ and thus $x \leq \frac{q}{m}$. That is, the commensal population is bounded above by $x \leq \left(\frac{1}{m}\right) [1 + \beta k_2 + \delta c]$.

Therefore, the solution of the model system (22-24) is bounded. That is $x(t) \leq \left(\frac{1}{m}\right) [1 + \beta k_2 + \delta c]$, $y(t) \leq k_2$ and $z(t) \leq c$.

3.3. Existence of Equilibrium Points

The scaled system of model equations now can be expressed as:

$$\frac{dx}{dt} = x \left[1 - mx + \left(\frac{\beta y}{1+h_1 x}\right) + \delta z\right]$$

$$r \frac{dy}{dt} = y \left[1 - h_2 y - \left(\frac{kz}{1+m_1 y}\right)\right]$$

$$\frac{dz}{dt} = z \left[-\sigma + \left(\frac{\varepsilon y}{1+m_2 y}\right) - \theta x\right]$$

The equilibrium points of the system can be obtained by setting $\frac{dx}{dt} = \frac{dy}{dt} = \frac{dz}{dt} = 0$ in the model equations.

This leads to the following optional relations:

$$x = 0 \tag{28}$$

$$\text{or, } \left[1 - mx + \left(\frac{\beta y}{1+h_1 x}\right) + \delta z\right] = 0 \tag{29}$$

$$y = 0 \tag{30}$$

$$\text{or, } \left[1 - h_2 y - \left(\frac{kz}{1+m_1 y}\right)\right] = 0 \tag{31}$$

$$z = 0 \tag{32}$$

$$\text{or, } \left[-\sigma + \left(\frac{\varepsilon y}{1+m_2 y}\right) - \theta x\right] = 0 \tag{33}$$

The solutions of these optional relations can be the equilibrium points. There are eight possible combinations of the relations. These combinations and their solutions or equilibrium points are as mentioned below:

Table 2. Possible combinations of the solution of the systems.

Combination of relations	Equilibrium point
(28) (30) (32)	E_0
(28) (30) (33)	E_0
(28) (30) (32)	E_1
(28) (31) (32)	E_2
(29) (31) (32)	E_3
(29) (31) (33)	E_4
(29) (31) (33)	E_5
(29) (30) (33)	Not biological

It can be observed that the first two combinations lead to the same equilibrium point E_0 while the last combination leads to biologically infeasible solution. Thus, six equilibrium points are possible. Now the coordinates of these six possible equilibrium points as given below:

- (1) $E_0(0, 0, 0)$ Trivial steady state
- (2) $E_1\left(\frac{1}{m}, 0, 0\right)$ Only the commensal population exists
- (3) $E_2\left(0, \frac{1}{h_2}, 0\right)$ Only the host population exists
- (4) $E_3\left(x_3, \frac{1}{h_2}, 0\right)$ Both commensal and host populations exist.

$$A_0 = k_0 n_3 - n_1 k_1 + n_2; n_1 = \theta \sigma h_2 m_1^2, n_2 = \theta^2 k \beta m_1 (1 + \sigma), n_3 = \theta^2 \sigma k \beta,$$

$$A_1 = n_4 - n_1 n_5; n_4 = \theta^2 \beta \sigma m_1^2, n_5 = m_1 (\theta \sigma - \sigma^2 h_2),$$

$$A_2 = k_0 k_1 + n n_5 + n_3; k_0 = 2 \theta \sigma m_1 - \theta \sigma h_2 - \theta \sigma h_2 m_1 + m^2 k \sigma + k \theta m_1 - k m \varepsilon.$$

$$A_3 = n k_1, n = \theta \sigma + k m \sigma + k \theta, k_1 = \theta \sigma - h_1 \sigma^2 + h_1 \sigma \varepsilon.$$

Variation matrix

To analyze the stability of the equilibrium points the community matrix called Jacobian matrix is determined as follows:

Let $\frac{dx}{dt} = h(x, y, z)$, $\frac{dy}{dt} = f(x, y, z)$ and $\frac{dz}{dt} = g(x, y, z)$. Also, the components of the Jacobian matrix are given

$$\text{by: } J = \begin{pmatrix} \frac{\partial h}{\partial x} & \frac{\partial h}{\partial y} & \frac{\partial h}{\partial z} \\ \frac{\partial f}{\partial x} & \frac{\partial f}{\partial y} & \frac{\partial f}{\partial z} \\ \frac{\partial g}{\partial x} & \frac{\partial g}{\partial y} & \frac{\partial g}{\partial z} \end{pmatrix}$$

But in case of the present model the functions are given by $h = x - mx^2 + \frac{\beta xy}{1+h_1 x} + \delta xz$,

$f = \left(\frac{1}{r}\right) \left[y - h_2 y^2 - \left(\frac{kyz}{1+m_1 y}\right) \right]$ and $g = -\sigma z + \frac{\varepsilon yz}{1+m_2 y} - \theta zx$ and thus the Jacobian matrix takes the components as

$$J = \begin{pmatrix} 1 - 2mx + \frac{\beta y}{(1+h_1 x)^2} + \delta z & \frac{\beta x}{1+h_1 x} & \delta x \\ 0 & \left(\frac{1}{r}\right) \left[1 - 2h_2 y - \frac{kz}{(1+m_1 y)^2} \right] & -\frac{ky}{1+m_1 y} \\ -\theta z & \frac{\varepsilon z}{(1+m_2 y)^2} & -\sigma - \theta x + \frac{\varepsilon y}{1+m_2 y} \end{pmatrix} \quad (34)$$

3.4. Analysis of the System

Here the stability of the model at the equilibrium point (22), (23) and (24) is analyzed. The local stability of the steady state is determined based on the nature of the eigenvalues of the variation matrix.

Theorem 1 The trivial equilibrium point $E_0(0, 0, 0)$ is unstable.

Proof The eigenvalues of the variation matrix (J_{E_0}) at E_0 are given by;

$$\det(J_0 - \lambda I) = 0. \text{ Thus, } \lambda_1 = 1 > 0, \lambda_2 = \frac{1}{r} > 0 \text{ and}$$

This can be interpreted as a disease free equilibrium

point. Here, $x_3 = \frac{h_2(h_1 - m) + \sqrt{h_1^2(m - h_1)^2 + 4m h_1 h_2(h_2 + \beta)}}{2 m h_1 h_2}$.

Note that the expression for x_3 is valid as long as the parameters satisfy the condition $m \leq h_1$.

- (5) $E_4(0, y_4, z_4)$ Both host and parasite populations exist.

- (6) Here $y_4 = \left(\frac{\sigma}{\varepsilon - \sigma m_2}\right)$ and $z_4 = \left(\frac{1}{k}\right) \left[1 + \left(\frac{\sigma m_1}{\varepsilon - \sigma m_2}\right) \right] \left[1 - \left(\frac{\sigma h_2}{\varepsilon - \sigma m_2}\right) \right]$. Note that the expression for y_4 is valid if $\varepsilon > \sigma m_2$. Similarly, the expression for z_4 is valid if $\varepsilon > \sigma(m_2 + h_2)$.

- (7) $E_5(x_5, y_5, z_5)$ All the three viz., commensal, host and parasite populations exist.

$$\text{where } x_5 = \frac{\varepsilon y_5}{\theta(1+m_2 y_5)} - \frac{\sigma}{\theta}, z_5 = \frac{(1+m_1 y_5)(1-h_2 y_5)}{k}$$

$A_0 y_5^3 + A_1 y_5^2 + A_2 y_5 + A_3 = 0$, where the values of $A_i, i = 0, 1, 2, 3$. But to solve this it is tedious, thus each coefficient is considered as a constant and they are defined as follows:

$$\det(J_1 - \lambda I) = 0 \Rightarrow (1 + \frac{\beta}{h_2} - \lambda)(-1 - \lambda)(-\sigma + \frac{\varepsilon}{h_2 + m_2} - \lambda) = 0$$

$\Rightarrow \lambda_1 = 1 + \frac{\beta}{h_2}, \lambda_2 = \frac{-1}{r}, \lambda_3 = -\sigma + \frac{\varepsilon}{h_2 + m_2}$. Since $\lambda_1 > 0$, the equilibrium point E_2 is unstable.

Theorem 4. The equilibrium point $E_3(x_3, \frac{1}{h_2}, 0)$ is locally asymptotically stable if $H > 1$ and $B > \frac{\varepsilon}{h_2 + m_2}$, otherwise it is unstable.

Proof: The Jacobian matrix at equilibrium E_3 gives us the eigenvalues; $\lambda_1 = 1 - H$, $\lambda_2 = -1$ and $\lambda_3 = -\sigma - \theta \frac{R - l_1}{2} + \frac{\varepsilon}{h_2 + m_2}$ where $H = m(R - l_1) + \frac{\beta}{h_2(1 + h_1(\frac{R - l_1}{2}))^2}$, $l_1 = \frac{m - h_1}{mh_1}$.

$$R = \frac{\sqrt{h_1^2(m - h_1)^2 + 4mh_1h_2(h_2 + \beta)}}{mh_1h_2}, B = \sigma + \theta \frac{R - l_1}{2}$$

Now, $\lambda_1 < 0$, when $H < 1$, this implies that $H > 1$ when $m > h_1$. Moreover, $\lambda_3 < 0$ whenever $\frac{\varepsilon}{h_2 + m_2} < B$ and also $m > h_1$.

Thus E_3 is stable when these conditions are satisfied otherwise unstable.

Theorem 5. The equilibrium point $E_4(0, y_4, z_4)$ is stable.

Proof: The characteristic equation of the variation matrix ($J E_4$) is given by;

$$(1 + \beta p_3 + \delta v - \lambda) \left(1 - 2h_2 p_3 - \frac{kv}{p_1} - \lambda\right) \left(-\sigma + \frac{\varepsilon \sigma}{\varepsilon - \sigma m_1 + m_2 \sigma} - \lambda\right) = 0 \quad (35)$$

$$p_3 = \frac{\beta \sigma}{\varepsilon - \sigma m_1}, p_1 = \left(1 + m_1 \left(\frac{\sigma}{\varepsilon - \sigma m_2}\right)\right)^2, v = \left(\frac{\delta}{k}\right) \left(\frac{\varepsilon^2 - \varepsilon \sigma m_1 - \sigma \varepsilon h_2}{(\varepsilon - \sigma m_2)^2}\right).$$

$$\Rightarrow \lambda_1 = 1 + p_3 + \delta v, \lambda_2 = 1 - 2h_2 p_3 - \frac{kv}{p_1}, \lambda_3 = -\sigma + \frac{\varepsilon \sigma}{\varepsilon - \sigma m_1 + m_2 \sigma};$$

$\lambda_1 < 0$, when $m_1 > \frac{\varepsilon}{\sigma}$, $\lambda_2 < 0$ when $R > 1$ and $\varepsilon > \sigma(m_2 + h_2)$ where $R = 2h_2 p_3 + \frac{kv}{p_1}$,

$\lambda_3 < 0$, when $m_1 < m_2$.

Therefore $E_4(0, y_4, z_4)$ is stable.

Theorem 5. The interior point $E_5(x_5, y_5, z_5)$ is stable when $\zeta > \frac{\sigma}{\theta \varepsilon - m_2 \sigma}$.

Proof: The variational matrix of E_5 at the equilibrium point takes form as

$$J = \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ 0 & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{pmatrix}; \text{ Where, } a_{11} = 1 - 2mx_5 + \left(\frac{\beta y^*}{(1 + h_1 x_5)^2}\right), a_{12} = \left(\frac{\beta x_5}{1 + h_1 x_5}\right)$$

$$a_{13} = \delta x_5, a_{22} = \left(\frac{1}{r}\right) \left(1 - 2h_2 y_5 - \frac{kz_5}{(1 + m_1 y_5)^2}\right), a_{23} = -\left(\frac{ky_5}{1 + m_1 y_5}\right), a_{31} = -\theta z_5, a_{32} = \left(\frac{\varepsilon z_5}{(1 + m_2 y_5)^2}\right), a_{33} = -\sigma - \theta x_5 + \frac{\varepsilon y_5}{1 + m_2 y_5};$$

The characteristic equation gives;

$$\lambda^3 + p\lambda^2 + q\lambda + r = 0; \quad (36)$$

Where $p = (a_{11} + a_{22} + a_{33}) > 0$, $q = a_{11}a_{33} + a_{11}a_{22} + a_{22}a_{33} - a_{13}a_{31} > 0$ and

$$r = a_{22}a_{31}a_{13} - a_{12}a_{23}a_{31} > 0 \text{ when } \zeta = \hat{y} > \left(\frac{\sigma}{\theta \varepsilon - m_2 \sigma}\right).$$

Therefore, all the roots of equation (36) will have negative real roots if $\zeta = \hat{y}$ and by Hurwitz Routh criteria of sufficient condition for stability, $E_5(x_5, y_5, z_5)$ is stable.

4. Numerical Simulations

Numerical examples or simulation study is used to confirm and support the results of mathematical or theoretical analysis.

That is, in order to verify the theoretical predictions of the

model the numerical simulations are carried out. For that purpose a set of biologically valid parametric and initial values are used.

All parameter values chosen here are realistic and at the same time they obey the stability conditions.

The pictorial representation of the simulation study of population dynamics of host-parasite model in absence of commensal population is given in Figure 2.

Figure 2. Dynamics of host-parasite populations in absence of commensal.

In Figure 2 the parametric values used are, $h_2 = 0.020$, $k = 0.500$, $m_1 = 0.200$, $\sigma = 0.9$, $\varepsilon = 0.08$, $m_2 = 0.60$.

Figure 2 shows the population dynamics of two dimensional host-parasite systems in absence of the commensal population. It is expected that the host population grows logistically but decays due to parasites. Similarly, the parasite population decays naturally but grows due to host. In the figure three phases of population dynamics are observed: (i) Phase 1 is the time interval from origin to the time of occurrence of maximum value for y (ii) Phase 2 is the time interval from the occurrence of maximum value for y to that for z and (iii) Phase 3 is the time interval from the occurrence of maximum value for z . In phase 1, both host and parasite populations increase. In phase 2, the host population decreases while the parasite population increases. In phase 3, both host and parasite populations decrease.

The following observations can be made from Figure 2:

- (i) The parasite population is increasing since the availability of host population is also increasing. This fact is being supported by the population curves in the figure 2 in Phase 1.
- (ii) The host population is decreasing since the parasite population is increasing. This fact is being supported by the population curves in the figure 2 in Phase 2.
- (iii) The parasite population is decreasing since the availability of host population is also decreasing. This fact is being supported by the population curves in the figure 2 in Phase 3. And once the parasite population decreases the host population would be sustain to alive.

Figure 3. Extinction of parasite population or disease free situation.

In Figure 3 the parametric values used are $m=0.084$, $\beta = 0.219$, $h_1 = 0.185$, $\delta = 0.242$, $\sigma = 0.169$, $r = 0.191$, $h_2 = 0.344$, $k = 0.371$, $m_1 = 0.64$, $m_2 = 0.461$, $\theta = 0.478$, $\varepsilon = 0.382$

Here as the time progresses population size of the parasite

extinct and the population sizes of both host and commensal converge to their respective carrying capacities. It is a disease free situation. But, extinction of any population is not desirable. Thus, the parametric values used here are not satisfactory.

Figure 4. Parasite populations lying near to zero or less disease situation.

In Figure 4 the parametric values used are $m=0.219$, $\beta = 0.247$, $h_1 = 0.264$, $\delta = 0.146$, $r = 0.107$, $h_2 = 0.275$, $k = 0.292$, $m_1 = 0.421$, $\sigma = 0.219$, $\varepsilon = 0.933$, $m_2 = 0.635$, $\theta = 0.719$

Here as the time progresses population size of the parasite

stays closer to zero and the population sizes of both host and commensal converge to their respective carrying capacities. It is not a disease free situation but, less disease situation.

Figure 5. Abnormal population of parasite or high disease situation.

In Figure 5 the parametric values used are $m=0.9$, $\beta = 0.691$, $h_1 = 0.096$, $\delta = 0.079$, $r = 0.298$, $h_2 = 0.466$, $k = 0.483$, $m_1 = 0.640$, $\sigma = 0.764$, $\varepsilon = 0.876$, $m_2 = 0.854$, $\theta = 0.371$.

Here as the time progresses population size of the parasite increases higher and the population sizes of both host and

commensal converge to their respective carrying capacities. In this case the host population is dominated by both commensal and parasites. That is the dependents are more. Also, the disease is more in the system. However, this dynamics appears not interesting.

Figure 6. Balancing sizes of populations.

In Figure 6 the parametric values used are $m=0.882$, $\beta = 0.107$, $h_1 = 0.14$, $\delta = 0.837$, $r = 0.202$, $h_2 = 0.135$, $k = 0.882$, $m_1 = 0.826$, $\sigma = 0.404$, $\varepsilon = 0.798$, $m_2 = 0.258$, $\theta = 0.674$.

Initially the population sizes fluctuate more but as the time progresses they converge to their optimum or stable values. Ultimately the population sizes maintain some balance among themselves. Hence, the dynamics shown in this simulation are highly accepted. The figure also supports that the interior equilibrium point is stable.

5. Conclusions

In the present study the population dynamics of a three dimensional commensal-host-parasite system have been taken up for investigation. A mathematical model for this three-dimensional system is developed by studying carefully and incorporating the futures of two-dimensional systems. The positivity and boundedness of the model variables are verified and hence shown that the newly developed three-dimensional system is biologically valid. To reduce the model parameters and to highlight the more important parameters, the scaled parameters have been introduced and the scaled model equations are constructed. Six equilibrium points have been identified and following Jacobian matrix method their stability is tested. Though the calculation of

interior equilibrium point involves very complex algebraic operations, it appeared that it is stable. However, the simulation study conducted promises that the interior equilibrium point is stable. In this paper, the model presented here only involves commensal, host and parasite, and only considers the case that the Monod type responses function.

It is interesting to consider the interaction between multi-commensal, multi-hosts and multi-parasites and the other interaction of the parasites in the model, and study the dynamical behaviors of the multi-hosts and multi-parasites system. Beside this, in the model harvesting rates as well as recovery of the population is not assumed. These assumptions will be considered in a future study.

In the present model the commensal has all the three positive growth rates due to nature, host and parasite; the host grows naturally but decays due to parasite; the parasite grows due to host but decays naturally and due to Commensal. In other words it can be put as;

Commensal has no negative growth rate; Host has one negative growth rate and the Parasite has two negative growth rates. Hence the following results:

(i) The population size of Commensal always lies above that of both the host and parasite. This fact is well supported by the simulations of the figures (3) to (6).

(ii) Though the Commensal population lies higher, the host and parasite compete for the second position.

(iii) In case if parasite dominates host i.e., more disease situation, the parasite appears in the second position i.e., Commensal-parasite-host pattern occurs. In general, this situation is not that much appreciated.

(iv) In case if there is either no or less disease i.e., no or less parasites, the host appears in the second position i.e., Commensal-host-parasite pattern occurs. This fact is seen in the simulated figures (3), (4) and (6). This pattern of the species is most expected and appreciated.

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