Highly Sensitive MEMS Based Capacitive Pressure Sensor Design Using COMSOL Multiphysics & Its Application in Lubricating System

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Abstract: Capacitive pressure sensors are making themselves the leader among its market competitors since they consume less power with less temperature sensitivity. This paper includes the design and development possibilities to increase the sensor sensitivity by optimizing the device dimension and including different types of materials. The figure of merits (FOMs) such as displacement, capacitance, electric potential with variation in temperature and pressure are thoroughly analyzed. This paper includes the unique developments, possible challenges with respect to design, modelling, simulation and analysis of MEMS based capacitive pressure sensors. As the range of application level of different sensors is increasing, it is indispensable to review the technological advancement and future possibilities of MEMS capacitive pressure sensors. This paper also focuses on the available reviews of various types of capacitive pressure sensor principles, geometrical design; physics based modelling, parameters analysis to consider, materials that can be used in fabrication process. The 3-D simulation is performed using COMSOL Multiphysics 5.0. During device development all the standards are followed according to the simulation standard set by COMSOL.

Keywords: MEMS, Pressure sensor, COMSOL Multiphysics, Sensitivity

1. Introduction

In the present era the application of pressure sensor in medicals, aerospace, automobiles, commercial and industrial applications have radically increasing [1-4]. The automotive and health segments are the foremost application sectors, which jointly held more than 45% share of the worldwide pressure sensor market in 2014. Due to the continuous and progression in the micro scale fabrication expertise, micromachined pressure sensors development have reached the point where low pressure to exceptionally high pressure sensors have developed continuously. In the present state of affairs polymer and silicon replaces long-established diaphragm pressure sensor made up of metals. This leads to trim down the material and fabrication cost thereby reduces the product cost/unit. Micromachined pressure sensor is developing importance due to its miniature size, lightweight, integratable to the integrated circuit (IC) fabrication process and smart interface features. It also shows high consistency [5-12].

Micromachined pressure sensors are tinny editions of their macroscopic competitors [1]. Sensors having diaphragm were developed to measure the effects on deformation on diaphragms due to application of pressure. The shape of the diaphragm is of the form of a square or circle. Silicon and silicon compounds are broadly used in the fabrication of micro pressure sensor [13]. In the present era the application of polymer material has increased due to a variety of advantages like structural stability, more elastic, good electrical and thermal characteristics but having some limitation in high temperature applications. Silicon material has taken the maximum market for pressure sensor fabrication, which can be processed by surface and bulk micromachining. The material properties and fabrication procedure are easy for silicon compared to other available materials. Single crystal or polysilicon diaphragm membrane is used as pressure sensing material for maximum numbers of works. The increase in sensitivities of silicon membrane due
to reduction in the thickness of the diaphragm or by adding impurities of P⁺⁺ as explained in [13]. The pressure level is decided according to the thickness of the diaphragm membrane, thinner is suitable for low-pressure application and vice versa. The effect of resistance due to change in temperature is one more crisis with the silicon; it has non-linear doze off in materials resistance with increase in temperature. In most of the MEMS capacitive pressure sensor, sensor structure is made up of silicon substrate and diaphragm membrane is made up off polysilicon or polymer materials like polyimide, kapton polyimide, SU-8 and Liquid crystal polymers [14].

Capacitive pressure sensors measure the capacitance between two or more conductors in a dielectric medium may be air or water. Real world capacitive pressure sensor design includes moving charges, potential surfaces and partially conducting surfaces [15-32]. For the accurate calculation of field and current to produce a capacitive pressure sensor, Maxwell equation is used. Maxwell built a capacitor with two parallel plates having area A, two partially conducting dielectric of thickness L, dielectric constant ε and conductivity σ. The range of application of capacitive pressure sensor is vast but silicon integrated circuit uses the capacitance based cantilever mems to calculate small displacement [33-58].

2. Device Design and Simulation

![Figure 1. 2-D cross sectional view of comb based capacitive pressure sensor.](image1)

COMSOL Multiphysics 5.0 is a simulation tool that uses the finite element method for the solution of complex physics problems. This simulation tool includes different equations according to different physics problems into a model. A unique model can use and include various physics conditions to allow the solutions of the problem that are frequently seen in the real world. A number of these mixed circumstances also exist as predefined physics boundaries, such as the piezo-electric devices, which is a mixture of solid mechanics and acoustic piezoelectric.

This is a unique capacitive pressure sensor structure which resembles to a comb having fingers like extensions which measures the capacitance accurately and precisely. Effort is given during design of diaphragm by selecting the thickness and shape of the diaphragm. Thickness of the diaphragm is made thinner in order to calculate the sensitivity correctly. In this design the diaphragm is isolated from the moving plate by a small cylindrical coupling in order to increase the pressure sensitivity. The complete device design and simulation work is carried out using COMSOL 5.0 simulation software [59]. The dimension of the device is made to be 200µm x 200µm. The thickness of the diaphragm (both square and circular) was made 3µm, 2µm and 1µm respectively. The capacitance of the device is carried out at a pressure range of 0 to 10 bars. This design is applicable for lubricating system to calculate the oil pressure inside a system. By calculating the pressure and capacitance the status of the lubricating system can be observed.

Between the two moving surfaces a lubrication film is formed which is made up of lubricating oil. If the amount of the lubrication oil varies due to friction or other effects, it directly affects the formation of the thin film by changing the viscosity. When the oil viscosity is not in the required range, the lubrication gets affected. In this design the diaphragm is connected with the movable plate which will calculate the small pressure created in the oil. The bottom and top plates are arranged as a comb like structure which will calculate the capacitance. When pressure is applied on the top plate, it will create a displacement and hence capacitance changes by reducing the separation between the two plates. This capacitance change is measured in terms of voltages. The moving plate of the device is tightly attached at the middle of
the diaphragm with the help of a mechanical cylindrical coupling. The size of this coupling is small which is about 1µm in radius. The thickness of a diaphragm and thickness of fringes in a comb plate is taken as 2µm. The diaphragm is made square and circular for two cases to study the behaviours.

<table>
<thead>
<tr>
<th>Diaphragm (Circular)</th>
<th>Diaphragm (square)</th>
<th>Comb plate</th>
</tr>
</thead>
<tbody>
<tr>
<td>Material</td>
<td>Aluminium (Al)</td>
<td>Aluminium (Al)</td>
</tr>
<tr>
<td>Density</td>
<td>2800 Kg/m³</td>
<td>2800 Kg/m³</td>
</tr>
<tr>
<td>Young's Modulus</td>
<td>180 GPa</td>
<td>180 GPa</td>
</tr>
<tr>
<td>Poisson's ratio</td>
<td>0.38</td>
<td>0.38</td>
</tr>
<tr>
<td>Device dimensions</td>
<td>50×2 µm</td>
<td>100×100×2 µm</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

### Table 1. Material and Dimension details of the device.

The meshing structure of the proposed model is given in figure 3 (a) and figure 3 (b) respectively. Figure 3 (a) shows the cross sectional view of the proposed model and figure 3 (b) reflects the three dimensional view of the proposed model with square type diaphragm. The fixed and moving plates with comb like structures are also under meshing in this figure. The operation of the device also depends on the meshing structure. This meshing can improve the device performance. This meshing style is different in COMSOL which may be rectangular or triangular.

![Figure 3](image)

3. Results and Discussions

The design of comb like structure is unique for this model having comb plates are made up of gold. The capacitance of the model depends upon the distance of separation between top and bottom plate. With the increase in separation distance between the plates, the capacitance decreases and vice versa. The diaphragm is made up of aluminium, which is mechanically coupled with a small cylindrical structure at the centre of the movable plate. Due to the pressure on the diaphragm, the movable plate moves towards the fixed plate by changing the capacitance. The proposed device has a 0 to 10 bar of pressure range. The mesh diagram for the proposed model is shown below.

![Figure 4](image)

The meshing structure of the proposed model is given in figure 3 (a) and figure 3 (b) respectively. Figure 3 (a) shows the cross sectional view of the proposed model and figure 3 (b) reflects the three dimensional view of the proposed model with square type diaphragm. The fixed and moving plates with comb like structures are also under meshing in this figure. The operation of the device also depends on the meshing structure. This meshing can improve the device performance. This meshing style is different in COMSOL which may be rectangular or triangular.

![Figure 4](image)

Figure 4 illustrates the potential present in the device. To calculate the lubrication of the oil, the change in capacitance between the two plates is taken into account. Here the moving and the fixed capacitance are in different potentials. The moving plate has a potential of 1V where as the fixed plate has a potential of 0V. Due to the application of pressure on the diaphragm, the moving plate moves towards the fixed plate by changing the potential between 1 and 0.
Figure 5. Displacement profile in (a) square membrane (b) Circular membrane.

Figure 5. (a) illustrates the displacement profile of the square membrane when pressure is applied to it. From the figure it can be concluded that the displacement is not uniform if the diaphragm is rectangular rather it is uniformly distributed if it is circular in shape as shown in figure 5. (b). Again Figure 6. explains the variation in capacitance for different materials at different temperatures. From the graph it can be observed that some of the materials show almost same capacitance with variation of temperature. However, gold gives higher capacitance value and noticeable change in capacitance with temperature variation. For this reason we have used gold for our device to make the comb plates and fingers.

Figure 6. Variation in capacitance at different temperature for different materials.

Figure 6. represents the variation in capacitance for different materials. From the figure it is cleared that gold gives higher capacitance value and noticeable change in capacitance with variation of temperature. However, gold gives higher capacitance value and noticeable change in capacitance with temperature variation. For this reason we have used gold for our device to make the comb plates and fingers.

Figure 7. Variation in deflection at different pressure for different materials.

Figure 7. represents the deflection vs. differential pressure for different materials. From the figure it is cleared that polyimide material gives higher deflection compared to other materials. Again the sensitivity of the device with different diaphragm thickness is simulated thoroughly. After simulation it is found that with decrease in the thickness of the diaphragm, the sensitivity increases. Similarly with increase in area the sensitivity also increases.

4. Conclusion

The introduction of this model gives a noteworthy improvement results in oil state monitoring as the instrument provides a separate diaphragm for pressure sensing and the deflection in the diaphragm creates a stress by moving the movable plate of the capacitor which is helpful in calculating the deflection by change in pressure. The capacitance of the model depends upon the distance of separation between top and bottom plate. With the increase in separation distance between the plates capacitance reduces and increases with increase decrease in plate separation. The diaphragm is made up of aluminium which is coupled with a mechanical cylindrical structure at the centre of the movable plate. Due to the pressure on the diaphragm, the movable plate moves towards the fixed plate by changing the capacitance. The proposed device has the pressure range of 0 to 10 bar.

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