
New combined method for solving the single level capacitated production planning model with set up cost, finite horizon and discrete stochastic demand

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Abstract: This paper studies the single level capacitated production planning problem with finite horizon (N periods). In each period, Set-up cost, variable cost and inventory cost exist. Also, it is assumed that the demand in each period is a discrete random variable with known probability function. In each period, if demand is bigger than inventory then we will have lost sales. In this case, we have to pay the cost of lost sales otherwise at the end of the period we will have extra products for the next period. At the end of horizon we have to sale the surplus products. In this case, price of one unit of products will be less than variable cost of production. An analytical method is proposed for solving this problem. This method can optimize the expected value of costs. In this method, expected value of costs is estimated by Monte Carlo simulation. Two examples have solved by using the proposed method. Comparison of the answers with solutions of other heuristic methods indicates the advantage of the proposed method.

Keywords: Capacitated Production Planning, Stochastic Demand, Set Up Cost, Finite Horizon

1. Introduction

The literature in production planning (PP) under uncertainty is vast. The problems can be categorized into two groups: (i) environmental uncertainty and (ii) system uncertainty. Uncertainty in this paper lies in group (i). [10] Reviewed the models of PP under uncertainty. [4], [6] considered the stochastic PP when the horizon planning is infinite. [7] Modeled the forecasts of discrete demand as bands and defined them by lower and upper bounds on demand. [1] Proposed a deterministic approximation for the sequential stochastic PP without setup costs. [5] Presented a multi-period hierarchical PP model with two planning levels, i.e. aggregate and detailed, and with uncertain demand. [9] Developed a multi-period model for hierarchical PP and scheduling with random demand and production failure. [8] Studied the capacitated PP with stochastic seasonal demand. [2] Studied the capacity planning under demand uncertainty without setup cost when the plant capacity is flexible. However, this paper studies the single level capacitated PP

problem with finite horizon, stochastic demand and set-up cost. In section 2, problem and its mathematical model have been described. In section 3, two present methods have been introduced [11]. Both methods are heuristic. They solve the problem by transforming the stochastic problem to deterministic problem. Then deterministic problems are solved based on an analytical method that has been developed in [3]. A new combined method is developed in section 4. In this method an analytical method has combined with Monte Carlo simulation. Advantage of the new proposed method has been shown by solving two examples in section 5. Section 6 has been devoted to conclusions and recommendations.

2. Problem and Its Mathematical Model

Here, we have a single level PP problem with finite horizon. This horizon comprises N periods. In each period,

Set-up cost, variable cost and inventory cost exist. Demand in each period is a discrete random variable with known probability function. Production in each period is limited to the production capacity. So, in each period if demand is bigger than the inventory then we will have cost of lost sales. Also, at the end of horizon we have to sale the surplus products. Subject to these suppositions, minimizing the expected value of costs is vital. The mathematical model of problem is stochastic integer linear programming. Some of the variables of model are zero or one and other variables may be continuous or discrete.

This model is as below:

$$\begin{aligned} \text{Min } Z = & E\left[\sum_{i=1}^N (f_i z_i + p_i x_i + h_i y_i)\right. \\ & \left. + cc_i \text{Max}(0, D_i - x_i) + \left(\sum_{i=1}^N x_i - \sum_{i=1}^N D_i\right) s_N\right] \\ \text{s.t. } & y_0 = y_N = 0 \\ & x_i + y_{i-1} - y_i = D_i \\ & x_i - c_i z_i \leq 0 \quad z_i \in \{0,1\} \\ & x_i \geq 0, y_i \geq 0 \\ & i = 1, 2, \dots, N \end{aligned}$$

where

D_i = discrete random variable of demand in period i

p_i = unit variable production cost in period i

f_i = set up cost in period i

h_i = unit holding cost in period i

c_i = production capacity in period i

N = number of periods of planning horizon

cc_i = unit cost of lost sale

s_N = price of one product at the end of horizon

The model variables are as below:

x_i = production quantity in period i

y_i = inventory at the end of period i

$z_i = 0$ if we do not produce in period i

$z_i = 1$ if we produce in period i

3. Present Methods

One of the simple ways to solve the stochastic problems is transforming them to deterministic problems. This action can be done by replacing demand with the average of demand. This method is proposed by Hashemin [11].

In this case, objective function can be written as:

$$\text{Min} \sum_{i=1}^N (f_i z_i + p_i x_i + h_i y_i)$$

So, in this deterministic model, we have not lost sales.

Also we will not have surplus products at the end of planning horizon. Then, the above mentioned model can be solved with the method proposed by Fatemi Ghomi and Hashemin [3]. Here, this method will be called the first method of reference [11].

Hashemin [11] has proposed a better value to be replaced with demand average. If cc_i is big and h_i is small then, we prefer that D_i to be replaced with value that is larger than \bar{D}_i . Also, if cc_i is small and h_i is big then, we prefer that D_i to be replaced with value that is smaller than \bar{D}_i . In other words, this value must be defined by flexible relation. This suitable value (\hat{D}_i) is value that minimized the

$$\begin{aligned} & E[\text{Max}\{0, x_i - D_i\}[(N-i+1)h_i + p_i - s_N]] \\ & + E[\text{Max}\{D_i - x_i, 0\}cc_i] \end{aligned}$$

Such that $\text{Min}\{D_i\} \leq x_i \leq \text{Max}\{D_i\}$ and x_i has integer value.

Then, this model can be solved with the method proposed by Fatemi Ghomi and Hashemin [3] too. Here, this method is called the second method of reference [11].

Here for completing the description of present methods, we discuss the proposed method by Fatemi Ghomi and Hashemin [3]. In this model, it is assumed that demand is deterministic in each period and back ordering is not permitted. In many PP problems, variables x_i may be integer. It is evident that solving these problems is difficult because the mathematical model of these problems is integer linear programming (ILP) with zero-one variables. Consequently, another analytical method is proposed. The feasible sets $\{z_1, z_2, \dots, z_N\}$ can be recognized. It should be noted that there must be $c_1 \geq D_1$ and $z_1 = 1$, in all feasible sets. By replacing the values of z_i in mathematical model, it is transformed to a simpler mathematical model. Then, this model must be solved for each feasible set. Implementation of this method can be difficult. Hence, based on reasonable assumptions, an attempt is made to develop a simpler method to solve the sub-problems. These assumptions which may exist in many problems are as follows:

- I. The same variable production cost for all periods.
- II. The same holding inventory cost for all periods.

Under the above assumptions, the objective function of the problem would be as follows:

$$\text{Min} \left(\sum_{i=1}^N f_i z_i + p \sum_{i=1}^N x_i + h \sum_{i=1}^N y_i \right)$$

Because the set of values $\{z_1, z_2, \dots, z_N\}$ is known for each feasible production plan, then $\sum_{i=1}^N f_i z_i$ is constant for each production plan. Also, because the equivalence

$y_0 = y_N = 0$ exists, there would be $\sum_{i=1}^N x_i = \sum_{i=1}^N D_i$. Hence,

the next term of objective function, $p \sum_{i=1}^N x_i$, would also be

constant; and $\sum_{i=1}^N y_i$ should be minimized for each feasible

production plan. To do this task, the constraints are divided into two following groups:

$$\begin{aligned} & \forall z_i = 1 \\ \text{Group 1: } & x_i + y_{i-1} - y_i = D_i \\ & x_i \leq c_i \\ & \forall z_i = 0 \\ \text{Group 2: } & y_{i-1} - y_i = D_i \\ & x_i = 0 \end{aligned}$$

Therefore, if $z_N = 1$ then, $x_N = \text{Min}\{c_N, D_N\}$, $y_{N-1} = \text{Max}\{0, D_N - c_N\}$ and if $z_N = 0$, then $y_{N-1} = D_N$.

The $(N-1)$ th constraint belongs to either group 1 constraints or group 2 constraints:

I) If $(N-1)$ th constraint belongs to group 1's, then $x_{N-1} + y_{N-2} - y_{N-1} = D_{N-1}$. y_{N-1} and D_{N-1} are Known; so the value of x_{N-1} can be determined such that y_{N-2} be minimized. So, $x_{N-1} = \text{Min}\{D_{N-1} + y_{N-1}, c_{N-1}\}$ and $y_{N-2} = \text{Max}\{0, D_{N-1} + y_{N-1} - c_{N-1}\}$. In general if $z_i = 1$ then, $y_{i-1} = \text{Max}\{0, D_i + y_i - c_i\}$.

II) If $(N-1)$ th constraint belongs to group 2's, then $y_{N-2} = D_{N-1} + y_{N-1}$. In general, if $z_i = 0$, then $y_{i-1} = D_i + y_i$.

Repeating the above operations for all periods gives the values of x_i and y_i .

4. Proposed Method

Proposed method generates the values of random variable $D_i, i=1,2,\dots,N$. Then, by replacing D_i with these values, the obtained model, is solved by using the method proposed by Fatemi Ghomi and Hashemin [3]. So, values of $x_i, i=1,2,\dots,N$ are defined. For each solved model (in other words, for each set of obtained $x_i, i=1,2,\dots,N$) we generate the values of random variable $D_i, i=1,2,\dots,N$ again. Then, we can compute the expected value of total costs. Finally, $x_i, i=1,2,\dots,N$ which has the minimum expected value of total costs are introduced as the best solution.

For implementation of proposed method, an algorithm is developed as below:

It is assumed that number of all cases of demand values of periods is M . Also, suppose that the primal value of $METC$ is $+\infty$. In this algorithm $METC$ will show the

Minimum Expected Value of Total Cost.

Step 1: set $L = 1$.

Step 2: generate the values of random variable $D_i, i=1,2,\dots,N$.

Step 3: by replacing D_i with these values, solve the obtained model by using the method proposed by Fatemi Ghomi and Hashemin [3] and define the values of $x_i, i=1,2,\dots,N$.

Step 4: compute the expected value of total cost and set $ETC =$ The expected value of total cost.

Step 5: if $ETC < METC$ then set $METC = ETC$.

Step 6: if $L = M$ stop. In this case value of $METC$ is the minimum value for expected value of total cost and values of $x_i, i=1,2,\dots,N$ is optimum otherwise set $L = L + 1$ and generate the values of random variable $D_i, i=1,2,\dots,N$ again (other case). Then go to step 3.

If the size of problem is small we can generate all the value of random variable $D_i, i=1,2,\dots,N$. Therefore we can obtain the optimum solutions. In large scale problems, these values can be generated by Monte Carlo simulation. In this case, we can't make sure that solutions are optimum but we know that by increasing the number of simulation runs we can obtain better solutions.

5. Examples

Example 1: consider the problem with

$$\begin{aligned} f_i &= 2.5 & P_i &= 4 & h_i &= 0.3 & cc_i &= 1.5 \\ c_i &= 15 & s_6 &= 1 & i &= 1,2,\dots,6 \end{aligned}$$

Probability functions of demands in six periods are shown in Table 1 and Table 2.

Table 1. Probability Functions of Periods 1,2,3 in Example 1

D_1	$P(D_1)$	D_2	$P(D_2)$	D_3	$P(D_3)$
6	0.175	4	0.1	2	0.15
7	0.175	5	0.3	3	0.2
8	0.3	6	0.3	4	0.3
9	0.175	7	0.1	5	0.2
10	0.175	8	0.2	6	0.15

Table 2. Probability Functions of Periods 4,5,6 in Example 1

D_4	$P(D_4)$	D_5	$P(D_5)$	D_6	$P(D_6)$
9	0.1875	5	0.15	3	0.2
10	0.1875	6	0.2	4	0.2
11	0.25	7	0.3	5	0.2
12	0.1875	8	0.2	6	0.2
13	0.1875	9	0.15	7	0.2

Solutions of present methods are compared with solution of proposed method in Table 3.

Table 3. Solutions of present methods and proposed method in example 1

Methods	i	1	2	3	4	5	6	Expected value of Total Cost
First Method	\bar{D}_i	8	6	4	11	7	0	185.1845
	X_i	8	10	0	11	12	0	
Second Method	\hat{D}_i	7	5	3	10	6	4	169.3261
	X_i	15	0	0	10	10	0	
Proposed Method	D_i	6	4	2	9	5	5	148.9991
	X_i	12	0	0	9	8	0	

Example 2: consider the problem with

$$f_i = 25 \quad P_i = 4 \quad h_i = 0.3 \quad cc_i = 15$$

$$c_i = 120 \quad s_6 = 1 \quad i = 1, 2, \dots, 6$$

Probability functions of demands in six periods are shown in Table 4 and Table 5.

Table 4. Probability Functions of Periods 1,2,3 in Example 2

D_1	$P(D_1)$	D_2	$P(D_2)$	D_3	$P(D_3)$
40	0.1	60	0.1	20	0.1
50	0.1	70	0.1	30	0.2
60	0.1	80	0.3	40	0.5
70	0.2	90	0.4	50	0.1
80	0.5	100	0.1	60	0.1

Table 5. Probability Functions of Periods 4,5,6 in Example 2

D_4	$P(D_4)$	D_5	$P(D_5)$	D_6	$P(D_6)$
80	0.1	10	0.1	30	0.2
90	0.1	20	0.3	40	0.4
100	0.2	30	0.4	50	0.2
110	0.5	40	0.1	60	0.1
120	0.1	50	0.1	70	0.1

Solutions of present methods are compared with solution of proposed method in Table 6.

Table 6. Solutions of present methods and proposed method in example 2

Methods	i	1	2	3	4	5	6	Expected value of total cost
First Method	\bar{D}_i	75	83	36	104	28	45	2406.846
	X_i	75	119	0	104	73	0	
Second Method	\hat{D}_i	80	90	40	110	30	50	2230.408
	X_i	90	120	0	110	80	0	
Proposed Method	D_i	80	90	50	110	30	40	2018.39
	X_i	10	120	0	110	70	0	

6. Conclusions and Recommendations

The new proposed method reduces the expected value of

total cost. It is evident that in large scale problems by increasing the number of simulation we can obtain better solutions.

Using the proposed method is recommended when the demand of periods are continuous random variables.

Solving the multi level problems with proposed method can be studied in future researches.

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