An Alternate Method for the Determination of the Raman Cross Sections of Optical Phonons in Uniaxial Crystals: Application to LiNbO_3

B. Mohamadou^{1,2,*}, E. Bouhari², R. Erasmus³

¹Center for Atomic Molecular Physics and Quantum Optics, University of Douala, Douala, Cameroon

²Department of Physics, Higher Teacher's Training College, The University of Maroua, Maroua, Cameroon

³School of Physics, University of the Witwatersrand, Johannesburg, South Africa

Email address:

Ballo_mohamadou@yahoo.fr (B. Mohamadou), ebouhari@gmail.com (E. Bouhari), Rudolph.erasmus@wits.ac.za (R. Erasmus)

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Abstract: The present paper is devoted to the derivation of an alternate and simple method based on the rotation of the crystal in view of the determination of the Raman cross-sections of optical phonon in uniaxial and biaxial crystals. The Raman polarisability tensor whose trace remains invariant under an orthogonal transformation is established as function of the crystal rotation position. The resulting angle dependent Raman scattered intensity is finally used to accurately describe the area under the peak which is measured from the polarised Raman spectra of the lithium niobate single crystal recorded under the backscattering scheme; The extracted parameters from the fit such as integrated areas are then plotted as functions of the crystal rotation angles. This allows to quantitatively determinate the relative phase and the relative values of the Raman tensor elements.

Keywords: Raman Polarisability, Raman Cross-Section, Rotating Crystal, Lithium Niobate

1. Introduction

Raman scattering efficiencies and their relative phases are important features in the study of the dynamics of superconductors such as $\text{SmBa}_2\text{Cu}_3\text{O}_{7-\delta}$ [1]. Alternatively, the values of Raman polarisabilities reveal to be as crucial parameters involved in the determination of the electro-optical (E/O) coefficients from Raman spectroscopic data [2]. Unfortunately, the experimental determination of such quantities is difficult and requires a lot of cautions. This mainly includes optical characterization of the sample, standard and optical devices used in the experiment. Several methods [3 and references therein] are used for the experimental determination of absolute or relative Raman scattering tensor elements. However owing to the constraints required by the absolute measurements, the comparative method is often preferred even though it must be accompanied with the use of internal or external standard. Many works devoted to the measurement of the Raman efficiency were performed absolutely or relatively in solvents [4]. Besides, the zinc-blend structure such as cuprous chloride [5] or gallium

phosphide [6] which exhibits a few Raman lines (not more than five peaks) has been studied experimentally as well as theoretically. More significantly absolute or relative measurements of the Raman polarisabilities performed on GaN has been carried out [7] by moving axially the sample or alternatively by translating the microscope objective. The advantage of the study focused on diatomic substances dwell on the simple character of their structure. Meanwhile, only few attempts were devoted to solid substances with more than two atoms per unit cell such as lithium niobate [8] (LiNbO_3 or LN) and lithium tantalate [8] (LiTaO_3 or LT) on the one hand or lithium meta gallate (LiGaO_2) [9] on the other hand. Both studies used the 992 cm^{-1} Raman line of benzene used as the reference sample. Since the first principle of band structure calculations leading to the prediction of Raman efficiencies for dielectric compounds with more complex structures are extremely difficult to point-out, only the experimental counterpart remains the way to be explored.

The purpose of the present work is: (i) the description of a new and simple comparative method based on the rotation of the studied crystal leading consequently to the determination of Raman efficiencies and their relative phases and (ii) the

derivation of the general form of the Raman tensor leading to a new selection rule (angle dependent) e.g. for any angular position of the crystal, the integrated intensities of the Raman spectrum can be clearly analysed. The determination of the relative phases as well as the theoretical derivation of Raman polarisability tensors are new features which reveal the advantage of this method over other comparative methods [8]. Rotating crystals also have the advantage of moving only the sample support instead of simultaneously rotating the polariser and the analyser [1]. Additionally, this method can also be extended to other Raman active point groups such as C_{2v}, C_{4v}, and C_{6v} for example. To check the validity of the present work, the derived equations of section 2 will be applied to the LN crystal (C_{3v}) in section 4 by comparing our Raman efficiency results to those already published by [8].

2. Theoretical Foundations of the Method

In this section, we derive a generalisation of the Raman tensor for any angular position of polarisation filter and then establish the corresponding Raman intensity. The polarisation filters is aimed to evidence the Raman line corresponding to a given basis functions of the irreducible representations of the crystal point group or the nonzero matrix elements of the associated Raman tensor. We propose a different approach mainly based on the crystal rotation and on the use of the laboratory Cartesian axes rather than the simultaneous rotation of the polarizer and the analyzer described by [1] within the crystallographic axes. The starting point of the present approach rely on the dependence on the polarisation of the strength of a given Raman line in C_{3v} crystal point group for general direction of photon and phonon propagation and polarisation as first given by Loudon [14]:

$$S \propto \left[\begin{aligned} &e_i^x e_s^x (c\kappa^y + a\kappa^z) + e_i^y e_s^y (-c\kappa^y + a\kappa^z) \\ &+ e_i^z e_s^z b\kappa^z + (e_i^y e_s^z + e_i^z e_s^y) d\kappa^y \\ &+ (e_i^z e_s^x + e_i^x e_s^z) d\kappa^x + (e_i^x e_s^y + e_i^y e_s^x) d\kappa^x \end{aligned} \right]^2 \quad (1)$$

In this expression e_i and e_s are the polarisation unit vectors of the incident and scattered light respectively, κ is the phonon polarisation indicating the TO or LO character of a given optical phonon and a , b , c and d are the Raman polarisability tensor elements. The laboratory cartesian z axis is parallel to the c crystallographic axis, x is perpendicular to one of the three glide planes and y is perpendicular to both x and z axes. Relation (1) can be casted into a compact form by accounting for implicitly the phonon polarisation and is widely used in the literature following such tensorial dot product (relations 2, 3).

The Raman integrated intensity of the optical mode with frequency ω_m is described by the Raman cross section S_{si}^m in the form [9]:

$$S_{si}^m = \frac{dI_{sm}}{I_i l d\Omega} = \frac{\hbar(\omega_i - \omega_m)^4 (n_m + 1)}{32\pi^2 c^4 \omega_m} \left| \vec{e}_s^* P_m \vec{e}_i \right|^2 \quad (2)$$

where S_{si}^m is the Raman efficiency, the subscripts s and i refer to the incident and scattered beam respectively, dI_{sm} is the scattered absolute intensity, I_i is the laser incident intensity, ω_i and ω_m are respectively the laser and phonon energies and $l, d\Omega$ are respectively the scattering length and the solid angle. P_m is the polarisability tensor associated to the vibrational mode m ; $\vec{e}_i$ and $\vec{e}_s$ are the polarisation unit vectors of the incident and scattered light respectively. $\vec{e}_s^*$ is the transpose matrix of $\vec{e}_s$

Relation (1) can be rewritten:

$$S_{si}^m = \frac{dI_{sm}}{I_i l d\Omega} = G(\omega) \left| \vec{e}_s^* P_m \vec{e}_i \right|^2 \quad (3)$$

with

$$G(\omega_m) = \frac{\hbar(\omega_i - \omega_m)^4 (n_m + 1)}{32\pi^2 \epsilon_0^2 c^4 \omega_m} \quad (4)$$

Taking into account the new state of the polarisation filter after the rotation of the crystal leads to:

$$S_{si}^m = \frac{dI_{sm}}{I_i l d\Omega} = G(\omega) \left| \vec{e}_s^* (\theta) P_m \vec{e}_i (\theta) \right|^2 \quad (5)$$

where $\vec{e}_i (\theta)$, $\vec{e}_s (\theta)$ are respectively the corresponding the final states of the polarisation unit vectors after a θ angle of rotation.

It can be easily shown that rotating crystal at θ angle is strictly equivalent to moving the polarisers at $(-\theta)$. This means that if M is the direct rotation matrix of the crystal, M^{-1} will be the direct rotation matrix of the polarisation vectors. It then follows:

$$\vec{e}_{i,s} (\theta) = M^{-1} \vec{e}_{i,s} \quad (6)$$

$$\vec{e}_s^* (\theta) = \vec{e}_s^* M \quad (7)$$

Inserting (5) and (6) into (4), finally yields:

$$S_{si}^m = \frac{dI_{sm}}{I_i l d\Omega} = G(\omega) \left| \vec{e}_s^* P_m (\theta) \vec{e}_i \right|^2 \quad (8)$$

with

$$P_m (\theta) = M P_m M^{-1} \quad (9)$$

where $P(\theta)$ is the polarisability tensor resulting from the crystal rotation.

M is the crystal rotation matrix around a given principal

dielectric axis of the crystal. For a θ crystal rotation angle around the x axis, M is defined:

$$M = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \cos \theta & -\sin \theta \\ 0 & \sin \theta & \cos \theta \end{pmatrix} \quad (10)$$

Considering (9) one can be self-convinced that matrix M is real and orthogonal, so $M^{-1}=M^*$. Consequently relation (8) results from a unitary transformation.

For example, LN and LT belong to the C_{3v} point group in which case the Raman tensor of polar A_1 , $E(x)$, $E(y)$ modes are given by [10]:

$$A_1(z) = \begin{pmatrix} a & 0 & 0 \\ 0 & a & 0 \\ 0 & 0 & b \end{pmatrix}, \quad E(x) = \begin{pmatrix} 0 & c & d \\ c & 0 & 0 \\ d & 0 & 0 \end{pmatrix},$$

$$E(y) = \begin{pmatrix} c & 0 & 0 \\ 0 & -c & d \\ 0 & d & 0 \end{pmatrix} \quad (11)$$

It is important to note that the Raman tensor elements arise from the first derivatives of the complex-valued dielectric function with normal coordinates. Consequently the Raman polarisabilities in (10) are complexes and may have an absolute phase as is the more familiar case of effective charges. Using (5), (6), together with (9) and (10) and considering the backscattering geometry $x(\dots)\bar{x}$, (8) can then be written:

$$A_1(\theta) = \begin{pmatrix} a & 0 & 0 \\ 0 & a \cos^2 \theta + b \sin^2 \theta & (1/2)(a-b) \sin 2\theta \\ 0 & (1/2)(a-b) \sin 2\theta & a \sin^2 \theta + b \cos^2 \theta \end{pmatrix} \quad (12)$$

$$E_1(\theta) = \begin{pmatrix} 0 & c \cos \theta - d \sin \theta & c \sin \theta + d \cos \theta \\ c \cos \theta - d \sin \theta & 0 & 0 \\ c \sin \theta + d \cos \theta & 0 & 0 \end{pmatrix} \quad (13)$$

$$E_2(\theta) = \begin{pmatrix} c & 0 & 0 \\ 0 & -c \cos^2 \theta - d \sin 2\theta & -(1/2)c \sin 2\theta + d \cos 2\theta \\ 0 & -(1/2)c \sin 2\theta + d \cos 2\theta & -c \sin^2 \theta + d \sin 2\theta \end{pmatrix} \quad (14)$$

Expressions (12), (13), and (14) are the generalised form of (11) in the backscattering geometry $x(\dots)\bar{x}$. Contrary to (11), the angle dependent of the fully symmetric A_1 Raman tensor (equation 12) possess off-diagonal elements meaning that the Raman structures belonging to the A_1 symmetry specie will be observed for crossed polarisers together with the $E(y)$ modes (relation 14). This interesting fact might be used for further numerical treatment of the Raman spectra as for example the test of the redundancy of the fit parameters. For other backscattering geometries e.g. $y(\dots)\bar{y}$ or $z(\dots)\bar{z}$ the analogous generalised form of (11) can be derived by performing the corresponding cyclic permutation of the rotation matrix M .

From the experimental point of view, the scattered absolute intensity is proportional to the area under the peak in the Raman spectrum per integration time t :

$$S_{si}^m \propto \frac{\sum_{si}^m}{t} \quad (15)$$

where

$\sum_{si}^m$ and t are respectively the area under the peak and the time of integration.

Considering that all the spectra were acquired with the same integration time and using (7) and (14), one gets:

$$\sum_{si}^m \propto G(\omega_m) \left| \vec{e}_s^* P_m(\theta) \vec{e}_i \right|^2 \quad (16)$$

II.1. Case a: A_1 mode

Using (8), relation (15) can be written:

$$\sum_{yy}^{A_1(\theta)} \propto G(\omega_m) \left[|a|^2 \cos^4(\theta) + |b|^2 \sin^4(\theta) + (1/2)|a||b| \cos \varphi_{ba} \sin^2(2\theta) \right] \quad (17)$$

$$\sum_{zz}^{A_1(\theta)} \propto G(\omega_m) \left[|a|^2 \sin^4(\theta) + |b|^2 \cos^4(\theta) + (1/2)|a||b| \cos \varphi_{ba} \sin^2(2\theta) \right] \quad (18)$$

for initial parallel polarisation unit vectors

$\vec{e}_i(0,1,0)$ $\vec{e}_s^*(0,1,0)$ (Polarisation filter(yy)) and

$\vec{e}_i(0,0,1)$ $\vec{e}_s^*(0,0,1)$ (Polarisation filter(zz)) respectively;

$$\sum_{yz}^{A_1(\theta)} = \sum_{zy}^{A_1(\theta)} \propto G(\omega_m) (1/4) \left[|a|^2 + |b|^2 - 2|a||b| \cos \varphi_{ba} \right] \sin^2(2\theta) \quad (19)$$

for initial crossed polarisation unit vectors $\vec{e}_i(0,1,0)$

$\vec{e}_s^*(0,0,1)$ (polarisation filters(yz) or equivalently (zy) if the symmetry character of the Raman tensor is assumed).

II.2. Case b: $E(x)$ mode

All the scattered intensities are equal to zero owing to the rules selection.

II.3. Case c: $E(y)$ mode

Similarly to the A_1 mode, (15) yields:

$$\sum_{yy}^{E_2(\theta)} \propto G(\omega_m) \left[|c|^2 \cos^4(\theta) + |d|^2 \sin^2(2\theta) + 2|c||d| \cos^2(\theta) \sin(2\theta) \cos(\varphi_{dc}) \right] \quad (20)$$

$$\sum_{zz}^{E_2(\theta)} \propto G(\omega_m) \left[|c|^2 \sin^4(\theta) + |d|^2 \sin^2(2\theta) - 2|c||d| \sin^2(\theta) \sin(2\theta) \cos(\varphi_{dc}) \right] \quad (21)$$

for initial parallel polarization filters;

$$\sum_{yz}^{E_2(\theta)} = \sum_{zy}^{E_2(\theta)} \propto G(\omega_m) \left[(1/4) |c|^2 \sin^2(2\theta) + |d|^2 \cos^2(2\theta) - (1/2) |c||d| \sin(4\theta) \cos(\varphi_{dc}) \right] \quad (22)$$

for initial crossed polarisation filters.

The absolute Raman intensities of other backscattering geometries can be derived from an analogous treatment. In appendix A are listed the expressions of the angle dependent Raman cross sections corresponding to the three backscattering arrangements along the principal directions of the C_{3v} crystal point group. As can be observed the limiting cases e.g. $\theta = 0$ or 90° correspond to the modes which can be observed following the backscattering geometries yielding the same selection rules as published by [13].

By virtue of the proportional relation (15) between the Raman integrated intensity and the area under the peak, (17-22) will be used for the determination of the fundamental areas that are proportional to the Raman tensor elements a , b , c , d of the bare modes in the fit procedure since only these areas are really the spectroscopic measured data. More precisely at a given rotation angle of the crystal, a Raman peak is considered as being the result of the interference of the fundamental areas associated to the Raman tensor components a , b , c and d .

It is important to note that the interference terminology seek here its true sense since the combination of the Raman tensor components of a given mode at the same frequency are temporally and spatially coherent.

3. Experiment

The sample was kindly provided by the LMOPS laboratory. It was oriented following the (100), (010), (001) dielectric axes. The Raman spectrum has been recorded at room temperature. A Labram Yobin-Ivon spectrometer operating at single spectrograph mode was used for both confocal micro-Raman and luminescence experiments. Note that this type of spectrograph operating mode present a higher throughput and offers rapid analysis time but its disadvantage is that it cannot be used for very small Raman shifts close to the laser line (in our case typically those with frequency shifts less than 100 cm^{-1}).

Radiation of an argon ion laser (514.5 nm) is focused through a microscope objective (50X/NA0.7) on the crystal surface. A back-scattering scheme is used to detect the Raman signal through a confocal pinhole, allowing the extraction of the scattered light from an extremely small volume (diameter is $1.6 \mu\text{m}$ and depth is $4 \mu\text{m}$ with the microscope objective x100) of the crystal. So, the detection of Raman or luminescence signals from a very small focal area can be performed, where extremely high intensities are available even at small input powers. The sample is tied on the rotation stage allowing the crystal to move degree per degree around the x principal dielectric axis. Initial parallel polarisations, e.g. a polarisation filter (yy) leads therefore to the measurement of both $a(\text{TO})$ and $c(\text{TO})$ Raman peaks corresponding to the A_1 and E symmetry species respectively. The spectra were recorded with an angular step of 10° without making use of internal or external reference sample.

4. Results and Discussion

Figure 1 presents the room temperature Raman spectra recorded at 0° , 40° and 90° angular positions of the crystal

when the crystal is rotated around the x dielectric axis. Despite of the recording temperature (300 K), all the E modes are clearly observed particularly in the angular range 0° - 60° without their overlapping notified by [6]. On the contrary, it can be observed the intensity exchange between the a and b Raman tensor elements corresponding to the A_1 modes. Such behaviours are merely the consequence of the angle dependent relations of the selection rules.

Figure 1. Raman Spectra of LiNbO₃ single crystal recorded as function of rotation angles for parallel polarisations filter following the initial backscattering geometry $x(yy)x$.

For the limiting cases e.g. case of 0° and 90° corresponding to $x(yy)\underline{x}$ and $x(\underline{zz})\underline{x}$ geometrical configurations, one can retrieve the classical selection rule giving at 0° the spectrum of the $a(\text{TO})$ and $c(\text{TO})$ in the $x(yy)\underline{x}$ on the one hand and at 90° the $b(\text{TO})$ of the A_1 modes on the other hand (17 and 20). At angles different from 0 or 90° , we observed a progressive enhancement of the Raman lines intensities belonging to the E symmetry type until a maximum value which will be specified by the fit of the integrated areas. Figure 1 reveals also the conservation of the phonon polarisation vector meaning that the rotation of the crystal do not alter the TO or LO character of the modes contrary to the ninety degree geometry which can provide spectra of oblique modes due to the coupling of polar modes.

All the recorded spectra were fitted with Lorentz functions for the symmetric Raman profile or with the Fano function [12] for the asymmetric one. This latter case is only applied to the 633 cm^{-1} Raman line for the present study. The parameters deduced from the fits are the resonant TO frequency, the damping and the height of the peak and are in turn used for the calculation of the area of the studied peak which was carried out by approximating the Raman peaks to isosceles triangles. Table 1 displays the normalised areas of the structures located at 253 , 276 and 633 cm^{-1} for the A_1 modes and at 154 , 369 , 432 and 580 cm^{-1} for the E modes. The spectra were then normalised by dividing their computed areas by the area under the $b(\text{TO})$ mode. Are also presented in the parentheses the analogous values normalised by the area of lowest frequency A_1 modes (253 cm^{-1}) as published by [13, 15]. As can be observed there are not noticeable difference. Some minors discrepancies can be attributed to the fact that [13] has neglected the population factor and can also be due to crystal quality and experimental

conditions.

The second step of the fit was devoted to the calculation of the areas associated with the Raman tensor elements a, b, c and d according to (17-22). By using mathematical handlings, we have reduced the 3 parameters (a, b, φ_{ba}) for A_1 modes and (c, d, φ_{dc}) for E modes to 2 parameters by solving exact values for the phase differences $(\varphi_{ba}, \varphi_{dc})$. Finally, the polarisabilities of the studied Raman lines are deduced from the value of the reference efficiency given by [8]

Table 1. Relative Raman Tensor elements of optical phonon for LiNbO_3 normalised at the same frequencies and obtained in this work *d* equivalent values given by [13, 15].

$A_1\text{-cm}^{-1}$	Rel. Raman-Tensor			$E_2\text{-cm}^{-1}$	Rel. Raman-tensor		
253	0.20(0.29)	0	0	154	0.17(0.16)	0.17(0.16)	1.00(0.16)
	0	0.20(0.29)	0		0.17(0.16)	-0.17(-0.16)	1.00(0.43)
	0	0	1.00		1.00(0.43)	1.00(0.43)	0
276	0.39(0.20)	0	0	369	0.69(0.11)	0.69(0.11)	1.00(0.24)
	0	0.39(0.20)	0		0.69(0.11)	-0.69(-0.11)	1.00(0.24)
	0	0	1.00(0.45)		1.00(0.24)	1.00(0.24)	0
633	0.64(0.57)	0	0	432	1.33(0.11)	1.33(0.11)	1.00(0.15)
	0	0.64(0.57)	0		1.33(0.11)	-1.33(-0.11)	1.00(0.15)
	0	0	1.00(0.88)		1.00(0.15)	1.00(0.15)	0
				580	1.25(0.21)	1.25(0.21)	1.00(0.38)
					1.25(0.21)	-1.25(-0.21)	1.00(0.38)
					1.00(0.38)	1.00(0.38)	0

Figure 2. (a) Fit of the areas of the TO phonon at 633 cm^{-1} of the A_1 symmetry type following (16). (b) Areas of the 369 cm^{-1} line associated to the TO phonon of the E mode fitted according to (20) (c) As for case (a) associated to 253 cm^{-1} line; (d) As for case (b) associate to 433 cm^{-1} line.

As stated above, the measurement was done without external reference. Since one of the aims of the present work is the validation of the rotating crystal method, we choose as reference line in our measured spectra, the structure at 369.5 cm^{-1} which appears for the whole range of the angle measurements. As a consequence, Fresnel, refraction, absorption and others corrections were assumed to implicitly compensate each other and can be therefore dropped out. In fact a reference must be chosen to fulfil the conditions required by the comparative method as adopted [8] and [9] and also within this work. In table 2 we presented the calculated Raman polarisabilities for the above mentioned examples (figure 2) in comparison with the published results concerning the LiNbO₃ crystal under the radiation of the 488 nm line of an argon ion laser. As can be observed, our preliminary results are in good agreement with [8].

Table 2. Comparison of present results with those of [8].

Component vibration	Frequency (cm ⁻¹)	Phase difference	Raman efficiency (10 ⁻⁷ cm ⁻¹ sr ⁻¹)	
E(TO) ^a	369,5	$\varphi_{dc} = 75^\circ$	$ c = c $	$ d = 1,17$
E(TO) ^b	374.0	-	$ c = 0,014$	$ d = 1,33$
A ₁ (TO) ^a	633.3	$\varphi_{ba} = 114,6^\circ$	$ a = 8,30$	$ b = 12,93$
A ₁ (TO) ^b	639.0	-	$ a = 6,57$	$ b = 14,42$

a: present results, b: reference[8] results

5. Conclusion

The present work has pointed out a general method to experimentally determine the magnitude and the phase difference between the Raman tensor elements of all Raman active crystal point group. In addition to the generalisation of selection rule being angle dependent, the method has been successfully applied to the LN Raman spectra in the $x(\dots)x$ geometrical configurations. The accuracy of the fit may be improved by increasing the number of measurements. It should be more interesting to record the angle dependent Raman spectra of the A_1 symmetry specie following the initial geometrical configuration $x(yz)x$. Though this configuration do not allow an unambiguous determination of the fit parameters, nevertheless it should be useful to check the coherency of the fit using (18). Contrary to the case of (17) and (19) which describes the angular behaviour of the A_1 modes, relation (22) allows an unambiguous determination of the fit parameters and could consequently predict the result of the fit through (20) which concerns the angular behaviour of the absolute Raman intensity of the E modes (parallel polarisation filter). Advantageously, (20) and (22) could lead independently to the absolute determination of the phase difference of the Raman polarisabilities of the E modes.

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Appendix

configuration	Limit cases	Raman intensities for $A_1(z)$, $E(x)$, $E(y)$ modes
X(yy)X	$A_1(a)[TO] + E(-c)[TO]$	$I_{\parallel yy}^{A_1(z)} = a ^2 \cos^4 \theta + b ^2 \sin^4 \theta + (1/2) a b \cos \varphi_{ba} \sin^2 2\theta$ $I_{\parallel yy}^{E(y)} = c ^2 \cos^4 \theta + d ^2 \sin^2(2\theta) - 2 c d \cos^2(\theta) \sin(2\theta) \cos(\varphi_{dc})$
X(yz)X	$E(d)[TO]$	$I_{\perp yz}^{A_1(z)} = (1/2) \left(a ^2 + b ^2 - 2 a b \cos \varphi_{ba} \right) \sin^2 2\theta$ $I_{\perp yz}^{E(y)} = (1/4) c ^2 \sin^2(2\theta) + d ^2 \cos^2(2\theta) + (1/2) c d \sin(4\theta) \cos(\varphi_{dc})$
X(zz)X	$A_1(b)[TO]$	$I_{\parallel zz}^{A_1(z)} = a ^2 \sin^4 \theta + b ^2 \cos^4 \theta + (1/2) a b \cos \varphi_{ba} \sin^2 2\theta$ $I_{\parallel zz}^{E(y)} = c ^2 \sin^4(\theta) + d ^2 \sin^2(2\theta) + 2 c d \sin^2(\theta) \sin(2\theta) \cos(\varphi_{dc})$
Y(xx)Y	$A_1(a)[TO] + E(c)[LO]$	$I_{\parallel xx}^{A_1(z)} = a ^2 \cos^4 \theta + b ^2 \sin^4 \theta + (1/2) a b \cos \varphi_{ba} \sin^2 2\theta$ $I_{\parallel xx}^{E(x)} = d ^2 \sin^2(2\theta), \quad I_{\parallel xx}^{E(y)} = c ^2 \cos^4 \theta$
Y(xz)Y	$E(d)[TO]$	$I_{\perp xz}^{A_1(z)} = (1/2) \left(a ^2 + b ^2 - 2 a b \cos \varphi_{ba} \right) \sin^2 2\theta$ $I_{\perp xz}^{E(x)} = d ^2 \cos^2(2\theta), \quad I_{\perp xz}^{E(y)} = (1/4) c ^2 \sin^2(2\theta)$
Y(zz)Y	$A_1(b)[TO]$	$I_{\parallel zz}^{A_1(z)} = a ^2 \sin^4 \theta + b ^2 \cos^4 \theta + (1/2) a b \cos \varphi_{ba} \sin^2 2\theta$ $I_{\parallel zz}^{E(x)} = d ^2 \sin^2(2\theta), \quad I_{\parallel zz}^{E(y)} = c ^2 \sin^4 \theta$
Z(yx)Z	$E(c)[TO]$	$I_{\perp yx}^{E(x)} = c ^2 \cos^2(2\theta)$ $I_{\perp yx}^{E(y)} = c ^2 \sin^2(2\theta)$
Z(xy)Z	$E(c)[TO]$	$I_{\perp xy}^{E(x)} = c ^2 \cos^2(2\theta)$ $I_{\perp xy}^{E(y)} = c ^2 \sin^2(2\theta)$
Z(xx)Z	$A_1(a)[LO] + E(c)[TO]$	$I_{\parallel xx}^{A_1(z)} = a ^2$ $I_{\parallel xx}^{E(x)} = c ^2 \sin^2(2\theta), \quad I_{\parallel xx}^{E(y)} = c ^2 \cos^2(2\theta)$
Z(yy)Z	$A_1(a)[LO] + E(-c)[TO]$	$I_{\parallel yy}^{A_1(z)} = a ^2$ $I_{\parallel yy}^{E(x)} = c ^2 \sin^2(2\theta), \quad I_{\parallel yy}^{E(y)} = c ^2 \cos^2(2\theta)$

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