Two-Sided Generalized Gumbel Distribution with Application to Air Pollution Data

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Abstract: We introduce a univariate generalized form of the Gumbel distribution via two-sided distribution structure. We obtain its some properties such as special cases, density shapes, hazard rate function and moments. We give the maximum likelihood estimators of this two-sided generalized Gumbel distribution with an algorithm. Finally, a real data application based on air pollution data is given to demonstrate that it has real data modeling potential.

Keywords: Gumbel Distribution, Two-Sided Distribution, Generalized Gumbel Distribution, Exponentiated Gumbel Distribution

1. Introduction

The Gumbel distribution, denoted by \( G_u \), is introduced by German statistician Emil J. Gumbel (1958) and it is introduced by the following cumulative distribution function (cdf) and probability density function (pdf)

\[
G(x; \mu, \sigma) = \exp \left[ -\exp \left( \frac{x-\mu}{\sigma} \right) \right]
\]

\[
g(x; \mu, \sigma) = \frac{1}{\sigma} \exp \left[ -\exp \left( \frac{x-\mu}{\sigma} \right) \right]
\]

respectively and where \(-\infty < x < \infty\), \(-\infty < \mu < \infty\), \(\sigma > 0\).

\( G_u \) distribution is frequently used for modelling in many areas such as environmental, engineering and actuarial sciences. It is also known as the extreme value distribution of type I. Also, the \( G_u \) distribution is a limit distribution of the generalized extreme value distribution (Von Mises, 1954). Kotz and Nadarajah (2000) explain this distribution in detail and with its applications. To increasing model flexibility of the \( G_u \) distribution there are several generalization of the \( G_u \) distribution in the literature such as the beta-\( G_u \) distribution (Nadarajah and Kotz, 2004), the generalized \( G_u \) distribution (Cooray, 2010), the Kumaraswamy-\( G_u \) distribution (Cordeiro et al., 2012), the \( G_u \)-Weibull distribution (Al-Aqtash et al., 2014) and the exponentiated generalized \( G_u \) distribution (Andrade et al. 2015). For more information on Gumbel and extreme value distributions, see Gumbel (1958), Johnson et al. (1995), Kotz and Nadarajah (2000), and Beirlant et al. (2006).

On the other hand, two-sided generalized a class of the distributions is introduced by Korkmaz and Genç (2015) by following cdf

\[
F(x; \alpha, \beta, \xi) = \begin{cases} 
\beta^{-\alpha} \left( G(x; \xi) \right)^{\alpha}, & -\infty < x \leq G^{-1}_{(\xi; \beta)}(\beta) \\
1-(1-\beta)^{-\alpha} \left( 1-G(x; \xi) \right)^{\alpha}, & G^{-1}_{(\xi; \beta)}(\beta) \leq x < \infty 
\end{cases}
\]

where \(-\infty < x < \infty\), \(\alpha > 0\) shape parameter, \(\beta \in (0,1)\) reflection parameter, \(\xi\) is parameter vector, \(G(x; \xi)\) is the cdf of the base distribution and \(G^{-1}_{(\xi; \beta)}(\cdot)\) its inverse. The corresponding pdf is
\[ f(x; \alpha, \beta, \xi) = \begin{cases} \alpha \beta \gamma^{1-a} g(x; \xi)(G(x; \xi))^{a-1}, & -\infty < x \leq G_{(x; \xi)}^{-1}(\beta) \\ \alpha(1-\beta) \gamma^{1-a} g(x; \xi)(1-G(x; \xi))^{a-1}, & G_{(x; \xi)}^{-1}(\beta) \leq x < \infty \end{cases} \]  

(4)

Since the standard two-sided power distribution (Van dorp and Kotz, 2002) is applied as a distribution class generator, the standard two-sided power distribution underlies of this generalized two-sided class. Since \( \alpha \) comes from the standard two-sided power distribution, this parameter also controls the kurtosis and tail of the distribution. This general two-sided class can contain alternative distributions for modeling not only positive data but also negative data with high kurtosis. Korkmaz and Genç (2015) also defines some properties of the generalized form of the distribution is studied in detail by the authors. In this paper we obtain the some properties of the generalized two-sided class using ordinary distributions such as exponential, Weibull, normal, Fréchet, half logistic, Pareto, and Kotz, 2002. Moreover, two-sided generalized normal distribution is defined by Korkmaz and Genç (2015) via two-sided distribution structure.

From (1), (2), (3) and (4) the cdf and pdf of the TSGG distribution are easily obtained as

\[ F(x; \theta) = \begin{cases} \beta \gamma^{-a} e^{-\alpha u}, & -\infty < x \leq \eta \\ 1-(1-\beta) \gamma^{-a} (1-e^{-u})^a, & \eta \leq x < \infty \end{cases} \]  

(5)

and

\[ f(x; \theta) = \begin{cases} \frac{\alpha \beta \gamma^{-a} u}{\sigma} e^{-\sigma u}, & -\infty < x \leq \eta \\ \frac{\alpha u (1-e^{-u})^{a-1}}{\sigma (1-\beta)} e^{-u}, & \eta \leq x < \infty \end{cases} \]  

(6)

respectively and where \( u = \exp(- (x-\mu) / \sigma) \),

\[ \text{TSGG}(\theta) = \beta LT_1(\alpha, \mu, \sigma) + (1-\beta) LT_2(\alpha, \mu, \sigma) \]  

(7)

where, \( LT_1(\alpha, \mu, \sigma) \) denotes the doubly truncated \( LT_1(\alpha, \mu, \sigma) \) distribution with truncation points \( a \) and \( b \), and similarly for \( LT_2(\alpha, \mu, \sigma) \). Hence TSGG has properties of both \( LT_1(\alpha, \mu, \sigma) \) distribution and the \( LT_2(\alpha, \mu, \sigma) \) distribution.

First and second derivatives of \( \log f(x) \) for the TSGG distribution

\[ \frac{d \log f(x)}{dx} = \begin{cases} -\frac{1}{\sigma} + \frac{\alpha u}{\sigma}, & x < \eta \\ -\frac{1}{\sigma} + \frac{u(1-\alpha e^{-u})}{\sigma(1-e^{-u})}, & x > \eta \end{cases} \]  

(8)
Respectively and where \( u = \exp\left(-\left(x - \mu\right)/\sigma\right) \).

These derivatives show that \( f(x) \) has a mode at 
\[ x^* = \mu + \sigma \log \alpha \] on the \((-\infty, \eta)\) support. On the other support it also may have a mode at solution point of the
\[ u + (1-u\alpha)e^{-u} - 1 = 0 \]
As a result we can say that TSGG distribution can be bimodal. Further
\[ \lim_{x \to \infty} f(x) = \lim_{x \to -\infty} f(x) = 0 \]
Plots of the pdf (6) for some parameter values are given in Figure 1.

3. Hazard Rate Function

The hazard rate function defined by
\[ h(t) = \frac{f(t)}{1 - F(t)} \]
and its important issue in the lifetime modeling. For TSGG distribution hazard rate function is given by
\[ h(t; \theta) = \begin{cases} \frac{\alpha u}{\sigma (\beta^{-1}(\theta^\alpha e^{-u} - 1), t \leq \eta} \\
\frac{\alpha u e^{-u}}{\sigma (1-e^{-u})}, \eta \leq t, \end{cases} \]

Figure 1. The pdf of the TSGG distribution for selected parameters value.
where \( u = \exp\left( -\frac{(t - \mu)}{\sigma} \right) \). We plot the hazard rate function of the TSGG distribution in Figure 2. From Figure 2 we see that TSGG distribution has increasing hazard rate as ordinary Gu distribution. We also note that contrary to the Gu distribution, we observe that the hazard rate function of the TSGG can be firstly unimodal then increasing shaped for some selected values of \( \alpha \) and \( \beta \). With this property, the TSGG distribution is much more advantageous than ordinary Gu distribution. Moreover

\[
\lim_{t \to -\infty} h(t) = 0 \quad \text{and} \quad \lim_{t \to \infty} h(t) = \frac{\alpha}{\sigma}.
\]

**Figure 2.** The hazard rate of the TSGG distribution for selected parameters value.
4. Moments

Using the moment definition and setting \( x = \mu - \sigma \log u \) we write the \( r \)th moment of the TSGG distribution.

\[
E(X^r) = \frac{\alpha}{(1 - \beta)^{r-1}} \int_0^{\log \beta} (\mu - \sigma \log u)^r \left(1 - e^{-u}\right)^{\alpha-1} e^{-u} du + \frac{\alpha}{\beta^{r-1}} \int_0^{\infty} (\mu - \sigma \log u)^r e^{-\alpha u} du
\]

(11)

Using the binomial expansion for \( (\mu - \sigma \log u)^r \) and \( (1 - e^{-u})^{\alpha-1} \) \( r \)th moment can be obtained by

\[
E(X^r) = \frac{\alpha \mu^r}{(1 - \beta)^{r-1}} \sum_{j=0}^{\infty} \sum_{k=0}^{r} (-1)^{j+k} \binom{r}{j} \binom{\sigma}{k} I(j,k) + \frac{\alpha \mu^r}{\beta^{r-1}} \sum_{k=0}^{r} (-1)^{k} \binom{r}{k} \binom{\sigma}{k} I(k)
\]

(12)

where \( I(j,k) \) and \( I(k) \) denotes these integrals with

\[
I(j,k) = \int_0^{\log \beta} (\log u)^k e^{-u(j+1)} du
\]

(13)

\[
I(k) = \int_{-\log \beta}^{\infty} (\log u)^k e^{-\alpha u} du
\]

(14)

respectively. Especially for \( r=1 \), using equations (1.6.10.2) and (1.6.10.3) in Prudnikov et al. (1986) we obtain the following cases for the calculating expected value

\[
I(j,0) = \frac{1 - \beta^{j+1}}{j+1},
\]

(15)

\[
I(j,1) = \frac{1}{j+1} \left[ Ei\left( (j+1) \log \beta \right) - \beta^{j+1} \log(\log \beta) - \log(j+1) \right]
\]

(16)

\[
I(0) = \alpha^{-1} \beta^\alpha,
\]

(17)

\[
I(1) = \frac{1}{\alpha} \left[ \beta^\alpha \log(\log \beta) - Ei(\alpha \log \beta) \right],
\]

(18)

where \( Ei(\cdot) \) denotes the exponential integral and is \( Ei(-ax) = -\int_x^\infty t^{-1} e^{-at} dt, a > 0 \) (Prudnikov et al., Eq. 1.3.2.14, 1986). Thus,

\[
E(X) = \frac{\alpha}{(1 - \beta)^{r-1}} \sum_{j=0}^{\infty} (-1)^j \binom{\alpha-1}{j} \frac{\mu(1 - \beta^{j+1})}{j+1} - \sigma I(j,1) + \frac{\alpha}{\beta^{r-1}} \left[ \frac{\mu \beta^\alpha}{\alpha} - \sigma I(1) \right].
\]

(19)

We sketch the skewness, \( \delta_1 = \left( \mu_3 - 3\mu_1 \mu_2 + 2\mu_1^3 \right) / \left( \mu_2 - \mu_1^2 \right)^{3/2} \), and kurtosis, \( \delta_2 = \left( \mu_4 - 4\mu_1 \mu_2 + 6\mu_1 \mu_2 - 3\mu_1^3 \right) / \left( \mu_2 - \mu_1^2 \right)^2 \), measurement in Figure 3 where \( \mu_x \equiv E(X') \).

We can observe empirically that the TSGG distribution can be left skewed, symmetric or right skewed. So it is much more flexible than the \( Gu \) distribution.
5. Maximum Likelihood Estimation

Let \( X_1, X_2, \ldots, X_n \) be a random sample of size \( n \) from the TSGG distribution and let \( X_{(i)} \leq X_{(2)} \leq \cdots \leq X_{(n)} \) denote the corresponding order statistics. Then the log-likelihood function is given by

\[
\ell (\theta) = n \log \alpha - n \log \sigma - \sum_{i=1}^{n} \frac{x_i - \mu}{\sigma} - \sum_{i=1}^{n} \exp \left( - \frac{x_i - \mu}{\sigma} \right)
\]

\[
+ (\alpha - 1) \log \left[ \prod_{i=1}^{r} \exp \left( - \exp \left( - \frac{x_{(i)} - \mu}{\sigma} \right) \right) \prod_{j=r+1}^{n} \left[ 1 - \exp \left( - \exp \left( - \frac{x_{(j)} - \mu}{\sigma} \right) \right) \right] \right] \beta^{-r} (1 - \beta)^{n-r}
\]

(20)

where \( x_{(r)} \leq \eta \leq x_{(r+1)} \) for \( r = 1, 2, \ldots, n \) and \( x_{(0)} = -\infty \), \( x_{(n+1)} = \infty \).

From Van dorp and Kotz (2002) and Korkmaz and Genç (2015), the estimating of the reflection point \( \eta \) is one of the \( x_{(1)} \leq x_{(2)} \leq \cdots \leq x_{(n)} \) order statistics. Accordingly, we have the maximum likelihood estimate (MLE) of the \( \tilde{\beta} \) and \( \alpha \) as

\[
\hat{\beta} = \exp \left( - \exp \left[ - \left( x_{(\tilde{r})} - \mu \right) / \sigma \right] \right)
\]

(21)

and by equating to zero the first derivative of the (20) respect to \( \alpha \)

\[
\hat{\alpha} = \frac{-n}{\log M (\tilde{r}, \mu, \sigma)}
\]

(22)

where \( \tilde{r} = \arg \max M (r, \mu, \sigma) , r \in \{1, 2, \ldots, n\} \) with
\[
M(r, \mu, \sigma) = \prod_{i=1}^{r} \exp \left\{ -\exp \left[ -\left( x_i - \frac{\mu}{\sigma} \right) \right] \right\} \prod_{i=r+1}^{n} \left\{ 1 - \exp \left[ -\exp \left[ -\left( x_i - \frac{\mu}{\sigma} \right) \right] \right] \right\}.
\]

For \( \mu \) and \( \sigma \), the associated likelihood estimating equations are found

\[
\frac{\partial \ell(\theta)}{\partial \mu} = \frac{n}{\sigma} - \frac{1}{\sigma} \sum_{i=1}^{n} u_i - \frac{(\alpha-1)}{\sigma} \left[ \sum_{i=1}^{r} u_i - \sum_{i=r+1}^{n} u_i e^{-u_i} \right]
\]

\[
\frac{\partial \ell(\theta)}{\partial \sigma} = -\frac{n}{\sigma} + \frac{1}{\sigma} \sum_{i=1}^{n} (u_i-1) \log u_i + \frac{(\alpha-1)}{\sigma} \left[ \sum_{i=1}^{r} \log u_i - \sum_{i=r+1}^{n} u_i e^{-u_i} \log u_i \right]
\]

where \( u_i = \exp\left[ -\left( x_i - \frac{\mu}{\sigma} \right) \right] \), \( i = 1, 2, ..., n \). We need some iterative procedure to find the estimates for \( \mu \) and \( \sigma \) parameters. We may explain this procedure with an algorithm:

Step 1: Set \( k = 0 \) and put an initial values \( \hat{\mu}^{(0)} \) and \( \hat{\theta}^{(0)} \) for \( \gamma, \theta \) in the log likelihood.

Step 2: Compute the following estimates

\[
\hat{\beta}^{(k+1)} = \exp \left\{ -\exp \left[ -\left( x_i - \frac{\mu^{(k)}}{\sigma^{(k)}} \right) \right] \right\}
\]

\[
\hat{\alpha}^{(k+1)} = -\frac{n}{\log M(\hat{\mu}^{(k)}, \sigma^{(k)})},
\]

where \( \hat{r} = \arg \max M(r, \mu^{(k)}, \sigma^{(k)}) \), \( r \in (1, 2, ..., n) \) with

\[
M(r, \mu^{(k)}, \sigma^{(k)}) = \prod_{i=1}^{r} \exp \left\{ -\exp \left[ -\left( x_i - \frac{\mu^{(k)}}{\sigma^{(k)}} \right) \right] \right\} \prod_{i=r+1}^{n} \left\{ 1 - \exp \left[ -\exp \left[ -\left( x_i - \frac{\mu^{(k)}}{\sigma^{(k)}} \right) \right] \right] \right\}.
\]

Step 3: Update \( \mu \) and \( \sigma \) by using (25) and (26) to find \( \hat{\mu}^{(k+1)} \) and \( \hat{\sigma}^{(k+1)} \)

Step 4: If \( \ell\left(\hat{\alpha}^{(k+1)}, \hat{\beta}^{(k+1)}, \hat{\mu}^{(k+1)}, \hat{\sigma}^{(k+1)}\right) - \ell\left(\hat{\alpha}^{(k)}, \hat{\beta}^{(k)}, \hat{\mu}^{(k)}, \hat{\sigma}^{(k)}\right) \) is less than a given tolerance, say \( 10^{-2} \), then stop. Else \( k = k + 1 \) and go to Step 2.

We note that the usual regularity conditions, which belong to the asymptotic normality of the MLEs, are not ensured for the \( TSGG \) distribution since the support of the pdf of the \( TSGG \) depends on parameters \( \beta, \mu, \sigma \) and the pdf is not differentiable at \( \eta \). In addition to the estimator of \( \beta \) is based on the order statistics. So, the observed information matrix, which used to obtain the asymptotic variances of the MLEs, can be found numerically via optimization procedure in packet programme such as \( R, Maple, Matlab \).

6. Data Analysis

In this section, we give a real data application. The computations of the MLEs of all parameters for all the distributions are obtained by using the \textit{optim} function in \textit{R} program with \textit{LBFGS-B} method. This function also gives the numerically differentiated observed information matrix. The data are from the New York State Department of Conservation corresponding to the daily ozone level measurements in New York in May-September, 1973. Recently, Nadarajah (2008), Leiva et al.(2010), Cordeiro et al. (2013) and Korkmaz and Genç (2014) analyzed these data. To see the performance of the \( TSGG \), we fit this data set to \( TSGG \). After fitting the \( TSGG \) distribution to this data set, we find the following MLE results:

\[
\hat{\alpha} = 0.1507(0.0141), \quad \hat{\beta} = 0.2443(0.0435), \quad \hat{\mu} = 18.3183(0.0274), \quad \hat{\sigma} = 4.7290(0.0278)
\]

and \( \ell\left(\hat{\theta}\right) = -538.8174 \) where standard errors are given in parentheses.

Also we give the value of the Kolmogorov-Smirnov goodness of fit test statistic as 0.0175 with a \textit{p-value} 0.5995.
Hence we accept the null hypothesis that the data set is come from the TSGG distribution. We give the fitted TSGG density and empirical cdf plots in Figure 4. These conclusions are also supported by Figure 4. Therefore, we show that the TSGG distribution has the real data modeling potential.

![Figure 4](image.png)

**Figure 4.** (a) Fitted the TSSG density of the ozone level data. (b) Empirical and fitted cdf’s.

### References


