Performance Analysis of FFH/MFSK Using Division Combining Receiver in GPS System

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Abstract: In this paper, a new kind of nonlinear combining receiver of fast frequency hopping/multiple frequency shift keying (FFH/MFSK) modulation in GPS system is proposed. The performance of the receiver is analyzed in the effects of partial band noise jamming over additive white Gaussian noise channel and Ricean fading channel. The diversity of the system is performed using multiple hops per data bit. The non-central F distribution is found in the random variable of the division combining algorithm under the partial-band noise jamming in the additive white Gaussian noise channel. The mathematical results of the bit error ratio of the division combining system are achieved in both fading and non-fading channels. The numerical results are achieved by the simulation environment of the signal transmission while the signal to noise ratio was relatively small and the partial band noise jamming factor is relatively large. It was shown that the GPS system using division combining receiver has better performance under the strong partial band interference than the system without diversity and system with self-normalized combining receiver. This performance gain is because that the interference signal is scattered into several hops and partly diminished by the operation of division algorithm. As its simple structure to be implemented and anti-interference property, the proposed combining algorithm is useful for GPS signal transmission in the strong partial band noise jamming environment.

Keywords: FFH, MFSK, Division Combining, Fading Channel

1. Introduction

In this paper the transmission characteristic of the proposed FFH/MFSK receiver in the GPS system named division combining receiver \cite{1,2} is analyzed. According to the signal transition environment of GPS channel, the performance is analyzed with multiple hops per data bit under the fading channel \cite{3,4} with partial band noise jamming (PBNJ) and AWGN. The error probability density function (pdf) is derived by the diversity level from one (no diversity) to three. It was shown that when the signal to jamming ratio is relatively low, the proposed MFSK system performances better than the system without diversity and self-normalized combining receiver \cite{5,6} while the diversity level increases. This performance gain is because of the interference signal which is scattered into several hops and partly diminished by the division operations of the system. The combining algorithm is interpreted in the section two and the system performance is analyzed in the following sections. Then the numerical results are shown for comparing the proposed algorithm with the self-normalized combining algorithm which is commonly used in the FFH GPS systems.

2. System Model

The structure of the proposed receiver in GPS system is shown in Figure 1. The signal in the GPS antenna is fed to the BPF filter and then disposed by the FFH/MFSK receiver. After that, the signal is combined with division algorithm to shape the decision signal $z$ and finish the demodulation of the GPS system.
The GPS signal is assumed to transmit in L hop/bit FHH/MFSK mode with total bandwidth W, and the baseband frequency f₁, f₂, and f₃ (f₁<f₂<f₃) which leads to M=3, are transmitted at the rate of Rₑ=1/Tₑ. |fᵢ-fⱼ|=B which is the cell bandwidth [7, 8] equal to hopping rate Rₑ. The received signal was passed through the ratio frequency band pass filter and then down converted with the frequency synthesizer (FS) controlled by the PN generator [9, 10] coincident with the transmitting end. The dehopped signal r(t) is fed into three square-law envelope detectors whose outputs are sampled and compared to make a bit decision. It was assumed that the two adjacent frequency interference are relatively of great disparity, the abscissa axis of the BER curve is chosen from -10dB to 10dB to avoid the chance of specific value zₙ, z₂ₙ and z₃ₙ to be a very large number or a quite small number. The performance in the AWGN and the fading channel is discussed below.

3. Performance Analysis

A. Performance under the PBNJ in the AWGN channel

Without loss in generality, it was assumed that fᵢ was transmitted in the subsequent analysis. The random variables x₁ₙ, x₂ₙ and x₃ₙ can be represented as follows. [12]

\[ x₁ₙ = \sigma₁²\left( \frac{2S}{\sigma₁} \cos \thetaᵣ + v₁ₙ \right)² + \left( \frac{2S}{\sigma₁} \sin \thetaᵣ + v₂ₙ \right)² \]

\[ x₂ₙ = \sigma₂²\left[ v₁ₙ + v₂ₙ \right] \]

\[ x₃ₙ = \sigma₃²\left[ v₁ₙ + v₂ₙ \right] \]

Where

\[ \sigmaᵢ² = \begin{cases} N₀\delta B, & \text{with probability } 1-\gamma \\ \left( N₀ + Nᵢ / \gamma \right)B, & \text{with probability } \gamma \end{cases} \]

S is the signal power and θᵣ is the uniform phase random variables v₁ₙ, i=1,2,3,4,5,6 are independent Gaussian random variables with zero means and unit variance. Thus, zₙ can be expressed as

\[ zₙ = \frac{\left( \frac{2S}{\sigma₁} \cos \thetaᵣ + v₁ₙ \right)² + \left( \frac{2S}{\sigma₁} \sin \thetaᵣ + v₂ₙ \right)²}{v₁ₙ² + v₂ₙ²} \]

As noticed in paper [1], zₙ is a non-central F distributed random variable with two degrees of freedom with non-central parameter \(2S/\sigma₁²\). According to the structure of the algorithm, the value of zₙ has no relationship with the value of xₙ, so zₙ will not be contaminated while the xₙ is interfered by the noise signal. Such the probability density function of zₙ can be obtained [13] as below.

\[ f_{zₙ}(zₙ) = e^{-\frac{λ}{2}} \sum_{n=0}^{∞} \frac{λ (n+1) zₙ^n}{n!} U(zₙ) \]
Where λ=2S/σ₂ is the non-central parameter of z₁ik, U(.) is the unit step function. And the probability density function of z₂k and z₃k can also be obtained.

\[ f_{z_{ik}} = \frac{\lambda}{n!} \sum_{n=0}^{\infty} \frac{\lambda^n}{n!} U(z_{ik}) \quad i = 2,3 \]  

The probability density function of z₁, z₂ and z₃ can be get numerically by L-fold convolutions of \[ f_{z_{1k}}, f_{z_{2k}} \text{ and } f_{z_{3k}} \]. When L=2, the probability density functions are as follows.

\[ f_{z_{ik}}(z_{ik}) = \int_{0}^{\infty} f_{z_{ik}}(z_{ik}) f_{z_{ik}}(z_{ik} - z_{ik}) dz_{ik} \quad (8) \]

Where i=1 or 2 in equation (8). While L is above 2, the probability density functions of \[ f_{z_{1k}}, f_{z_{2k}} \text{ and } f_{z_{3k}} \] can also be obtained.

Given that \( l \) of L hops are jammed, Pr (e|l) is defined as the conditional probability of error. The probability of bit error is given by

\[ \text{Pr}(e) = \sum_{l=0}^{L} \binom{L}{l} \gamma^{l} (1 - \gamma)^{L-l} \text{Pr}(e|l) \]  

The function of (10) can be evaluated numerically. Notice that the total signal-to-noise ratio (SNR) = (\( \alpha^2 + 2\sigma^2 \)) / \( (N_1 + N_2) \) B and the total signal-to-jamming ratio (SJR) = (\( \alpha^2 + 2\sigma^2 \)) / \( (\gamma \ N_1 + N_0) \) B. In the following discussion, it was assumed that the direct component and the diffuse component of the signal have the equal power.

B. Performance under the PBNJ in the fading channel

As in A, it was assumed that f1 was transmitted. Given the signal amplitude \( \sqrt{2S} \), the conditional pdf of \( x_{1k} \) is \[ (8) \]:

\[ f_{x_{1k}}(x_{1k} | S) = \frac{1}{2\sigma_k^2} \exp\left(-\frac{x_{1k}^2 + 2S}{2\sigma_k^2}\right) \cdot I_0\left(\frac{2\sqrt{2}x_{1k}}{\sigma_k^2}\right) \]  

Where \( \alpha^2 \) is the average power of the direct component of the signal, and \( 2\sigma^2 \) is the average power of the diffuse component of the signal. The total average power of the signal is equal to \( \alpha^2 + 2\sigma^2 \) and remains constant from hop to hop.

The unconditional pdf \[ (14) \] of \( x_{1k} \) and \( x_{ik} \) is:

\[ f_{x_{1k}}(x_{1k}) = \frac{1}{2(\sigma_k^2 + 2\sigma^2)} \exp\left(-\frac{1}{2}(\frac{x_{1k}^2 + 2\sigma^2}{\sigma_k^2 + 2\sigma^2})\right) \cdot I_0\left(\frac{\sqrt{2}x_{1k}}{\sigma_k^2 + 2\sigma^2}\right) \]  

\[ f_{x_{ik}}(x_{ik}) = \frac{1}{2\sigma_k^2} \exp\left(-\frac{x_{ik}^2}{2\sigma_k^2}\right) \]  

In equation (13), parameter i indicates the number of the hops L, L=2,3,...,n. Then the pdf of \( z_{1k} \) and \( z_{ik} \) can be calculated as below:

\[ f_{z_{1k}}(z_{1k}) = \int_{0}^{\infty} f_{x_{1k}}(z_{1k} - x_{1k}) f_{x_{2k}}(\frac{1}{x_{2k}}) \cdot \frac{1}{x_{2k}} dx_{2k} \]  

\[ f_{z_{ik}}(z_{ik}) = \int_{0}^{\infty} f_{x_{ik}}(z_{ik} - x_{ik}) f_{x_{ik}}(\frac{1}{x_{ik}}) \cdot \frac{1}{x_{ik}} dx_{ik} \]  

After this the close-form of the probability density functions of \( z_{1k} \) and \( z_{ik} \) are:

\[ f_{z_{1k}}(z_{1k}) = \frac{\alpha^2 \sigma_k^4 z_{1k} + (\sigma_k^4 + 2\sigma^2 \sigma_k^2)(\sigma_k^2 + 2\sigma^2 + \sigma_k^2 z_{1k})}{(\sigma_k^4 + 2\sigma^2 + \sigma_k^2)^3} \]  

\[ f_{z_{ik}}(z_{ik}) = \frac{\alpha^2 \sigma_k^4 z_{ik} + (\sigma_k^4 + 2\sigma^2 \sigma_k^2)(\sigma_k^2 + 2\sigma^2 z_{ik} + \sigma_k^2 z_{ik})}{(\sigma_k^4 + 2\sigma^2 z_{ik} + \sigma_k^2)^3} \]  

The probability of bit error in the fading channel can be get through equation (9) and (10).

4. Numerical Results

The following figure 2 and figure 3 show the bit errors of the FFH/MFSK system in the AWGN channel with the PBNJ interference. Figure 2 shows the performance of the GPS system with \( E_b/N_0=13.35 \) dB. One can see that in the presence of strong PBNJ (\( E_b/N_0 \) from -10 to 3 dB), the diversity receiver performances better than the receiver without the diversity when the jamming factor \( \gamma \) is 0.5 and 0.1. The performance becomes much better when \( \gamma \) decreases.
Figure 3 shows the comparison between division combining and self-normalized combining receiver in the AWGN channel with the jamming factor $\gamma=0.1$ at different PBNJ ratio. The results show the proposed receiver has better performance at the same diversity level with the increasing of $E_b/N_0$. When the diversity level increase, both two kinds of receiver have better BER performance.

Figure 4 and figure 5 show the system performance under the PBNJ in frequency non-selective slowly Ricean fading channel with different partial band noise jamming factor $\gamma$ while the $E_b/N_0$ ratio is 0 dB.

It can be observed that in the Ricean fading channel, the bit error performance becomes insensitive to the $E_b/N_0$ ratio when the jamming factor $\gamma$ gets larger. However, in the presence of strong PBNJ, the division combining receiver has better performance than the receiver without the diversity and the self-normalized combining receiver. While the jamming factor $\gamma$ is relatively small as in figure 5, the diversity system gets better algorithms gain with the increasing of $E_b/N_0$ ratio.

5. Conclusion

In this paper the performance of division combining receiver of FFH/MFSK in GPS system is analyzed in the presence of strong interference ($E_b/N_0<10$ dB) while the hop $L=3$. The results show that the diversity receiver has better performance than the system without diversity and self-normalized combining receiver [15] in the AWGN channel and Ricean fading channel under partial-band-noise jamming. It was shown the proposed combining algorithm performances better than the self-normalized combining method at the lower $E_b/N_0$ ratio ($<10$ dB) with the same $E_b/N_0$ ratio while the $L$ increases. The division combining receiver has simpler structure than the self-normalized combining receiver and has easy way to be implemented. It will be useful for GPS signal transmission in the strong partial-band-noise jamming environment. However, when the dividing hops increase the computation complexity of the algorithm will also increase a lot. Meanwhile all of the random variety $z_1, z_2, \ldots, z_L$ will depends on the quantity of $x_{ik}$ which may be randomly interfered by the partial band jamming. So without loss of generality, the random $i$ of the $x_{ik}$ can be chosen for dispatching the interference to every hop of the random variety in the further research works.

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