

The Algebraical Superposition Technic for Transformation from S Domain to Time Domain

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Abstract: An algebraical superposition technic for transformation from frequency domain to time domain is presented. The establishing model process are; From the inverse Laplace transform integral formula, the integral formula can be expressed by the series with k $[-K, K]$ term., based on integral function distribution properties along integral path, the bidirectional series sum on k $[-K, K]$ term series can be expressed by a monomial trigonometric function series sum on k $[0, K]$. In the paper the solution process and main points are presented. The application examples are shown; the results are supported to the algebraical superposition technic. In using above algebraical superposition technic to analysis airspace dispersive propagation properties, i.e., to find out its time-domain parameters, the resultant formula contain time-domain factor and frequency-domain factor, that is first time to present in the paper, so it is called, 'time-frequency union technic'. In the paper simultaneity solve out wave number and wave impedance for waveguide TE₁₀ mode propagation, and get both time-frequency union values, and show the solving process and solving accuracy.

Keywords: Frequency Domain to Time Domain Transformation, Laplace Transformation, Algebraical Superposition Technic, Rectangular Waveguide TE₁₀ Mode, Time-frequency Union Value

1. Introduction

In scientific and technic zone for electronics and dynamics and controls, etc. It is often necessary to observe and research a system parameters varying to time. In mean time, it is often necessary to know a system parameters varying to frequency. The former is called as time domain parameters, and the later is called frequency domain parameters. It can be known from one to another by the transformation between times domain to frequency domain. The used time domain to frequency domain transformation method is often the Fourier Transform (FT) and Laplace Transform (LT). The condition using LT is loose, so its use is wider. The knowledge on Laplace Transform is easily found [1-3].

Implementing Laplace Transform from frequency domain to time domain an algebraical superposition technic is presented in the paper. It is from the inverse Laplace transform integral formula, the integral formula can be expressed by the series with k $[-K, K]$ term. When the amplitude and phase values for the series are even and odd symmetry to $k=0$ respectively, the bidirectional series sum on k $[-K, K]$ term

series can be expressed by a monomial trigonometric function series sum on k $[0, K]$. In the paper the solution process and main points are presented. The application examples are expressed; the results are supported to the algebraical superposition technic.

Furthermore, we research on the transformation of transmission parameters (frequency domain). In dispersive space domain has done. It is: in TE₁₀ mode waveguide [4-6] the transformation of transmission parameters. Its main process is: starting from the integral formula of inverse Laplace transform, it can be expressed by it's a set of equivalent series with k $[1, K]$ term.... After driving we find the last output sequence is consisted of two elements: the one is time factor, the two is frequency factor. In the inverse Laplace transform the results are not appeared. So it is called: the new idea and method of 'time-frequency union value'. The propagation wave number and the wave impedance of TE₁₀ mode waveguide are calculated in paper. The results are supported to above research.

In the paper, all calculation and program and graph are all performed by author himself

2. General Problem

2.1. Calculation Mode

Now, from Laplace transform formula research the calculation process of setting up, as follows

The first, from inverse Laplace transform formula [7-9].

$$f(t) = \frac{1}{2\pi j} \int_{\sigma-j\infty}^{\sigma+j\infty} F(s)e^{st} ds \quad s = \sigma + j\omega \quad \omega = 2\pi f \quad (1)$$

The corresponding Laplace transform formula is

$$F(s) = \int_{-\infty}^{\infty} f(t)e^{-st} dt \quad (2)$$

Above the integral for function $f(t)$ can be expressed by its series sum in the following:

$$f(t_i) = \Delta f \sum_{k=-K}^K F(s)e^{st_i} \quad k = -K, \dots, -2, -1, 0, 1, 2, \dots, K \quad (3)$$

Foremore, $F(s)$ in (3) often be complex and be expressed by its amplitude and phase ($F_m(k)e^{j\phi_k}$), its e^{st_i} can also be expressed by its real and imaginary part ($e^{\sigma t_i}e^{j\omega_k t_i}$), and $k[-K, K]$ is divided as three parts: $[-K, -1], 0, [1, K]$, as follows:

$$\begin{aligned} f(t_i) &= \Delta f \left\{ F_m(0)e^{j\phi_0}e^{\sigma t_i} + \left[\sum_{k=-K}^{-1} + \sum_{k=1}^K \right] F_m(k)e^{\sigma t_i}e^{j\omega_k t_i}e^{j\phi_k} \right\} \quad (4) \\ &= \Delta f e^{\sigma t_i} \left\{ F_m(0)e^{j\phi_0} + \left[\sum_{k=-K}^{-1} + \sum_{k=1}^K \right] F_m(k)e^{j(\omega_k t_i + \phi_k)} \right\} \end{aligned}$$

At last, when frequency domain function $F(s)$ distribution characteristics are: $F_m(k) = F_m(-k)$, $\phi_m(k) = -\phi_m(-k)$, By Euler equation $e^{j\varphi} + e^{-j\varphi} = 2\cos\varphi$ we obtain

$$\begin{aligned} f(t_i) &= \Delta f e^{\sigma t_i} \left\{ F_m(0)e^{j\phi_0} + 2 \sum_{k=1}^K F_m(k) \cos(\omega_k t_i + \phi_k) \right\} \quad (5) \\ i &= 0, 1, 2, \dots, N_t \end{aligned}$$

Above (5) is our request formula for calculation.

2.2. Kernel of Implementation

From equation (5) respective time domain sequence can be found, the kernel of implementation are:

(a) The analysis of respective frequency domain function: when the region of frequency domain and sampling space (Δf) are given, $F_m(k)$, $F_m(-k)$ and $\phi_m(k)$, $\phi_m(-k)$ are calculated which are used to judge ($F_m(k) = F_m(-k)$, $\phi_m(k) = -\phi_m(-k)$), if it is satisfied, the equation (5) can be used to find out the result.

(b) The time domain sequences sampling spacing and

calculation region for frequency and time domain are determined:

By Δf , N_f are respectively expressed for sampling spacing and sampling point number in frequency domain, f_h and f_s being the highest and sampling frequency respectively, Its well known that we have:

$$\Delta f = \frac{1}{t_s} = \frac{f_s}{N_f} \quad ; \quad f_s = (3-6)f_h = \frac{1}{\Delta t} \quad ; \quad \Delta t \leq \frac{1}{2f_h} \quad (6)$$

(c) Main point for time domain calculation: when calculation by equation (5), the integral path is a line that is parallel to imaginary axis and its real value being σ . The half axis line is equally divided, so obtained length Δf with K . Theoretically, K value approximate to ∞ , but in practice calculation it can be determined by the following way. The first K_i is given and a set of time domain data is obtained from equation (5). Next, K_{i+1} is given and another of time domain data is obtained. Comparing the two set of time domain data, if there are two digit values or more two digit values being equal, we can approximately think that K_{i+1} set of time domain data is 'convergence value' of finding time sequence.

(d) To get the 'convergence value' of the time sequence. It is necessary to calculate the 'convergence value' with algebraically superposit for hundreds or thousands or ten thousands or more times. To keep the accuracy of calculation data, we use the double accuracy for datas

(e) It is necessary to verify the time domain solution (time domain sequence). The verification method is: the solution sequence through transformation to get its frequency domain values (called calculation value). The frequency domain sequence from frequency domain function $F(s)$ is called as theory value. Comparing the calculation value to the theory value, the conclusion will come.

2.3. Application Examples

Two examples will be adopted; implementing the transform from frequency domain to time domain [7-12] above Kernel of implementation will be followed. On its individuality the simple word will express.

*** Example 1.

$$F(s) = \frac{\sqrt{s^2 + 6s + 7}}{(s+1)(s+4)}, \quad s = \sigma + j\omega, \quad \omega = 2\pi f \quad (7)$$

The solution of the example can not be obtained by general method, but can be obtained by equation (5). The main process are: σ and parameter for calculation using in frequency domain and time domain are determined, they are: $\sigma = -2.5$; $\Delta f = 500\text{Hz}$, $f_h = 3 \times 10^4\text{Hz}$; $\Delta t = 1 \times 10^{-5}\text{s}$, $N_t = 200$.

The first, $F_m(k)$, $F_m(-k)$ and $\phi_m(k)$, $\phi_m(-k)$ are numerated, and their distribution case are $F_m(k) = F_m(-k)$, $\phi_m(k) = -\phi_m(-k)$. which will make us to obtain $f(t)$ from

formula (5). And the frequency domain sequence is theory value of this example.

Next, the expectant time domain sequence can be got by equation (5). To obtain time domain sequence convergence value, in calculation, increasing K step by step, $K = 5000$ can be taken as convergence value. As comparing time domain sequence for $K = 5000$ to $K = 4000$, the two sequence values that have same value in 2-3 digits. It is shown in Figure 1 (a)

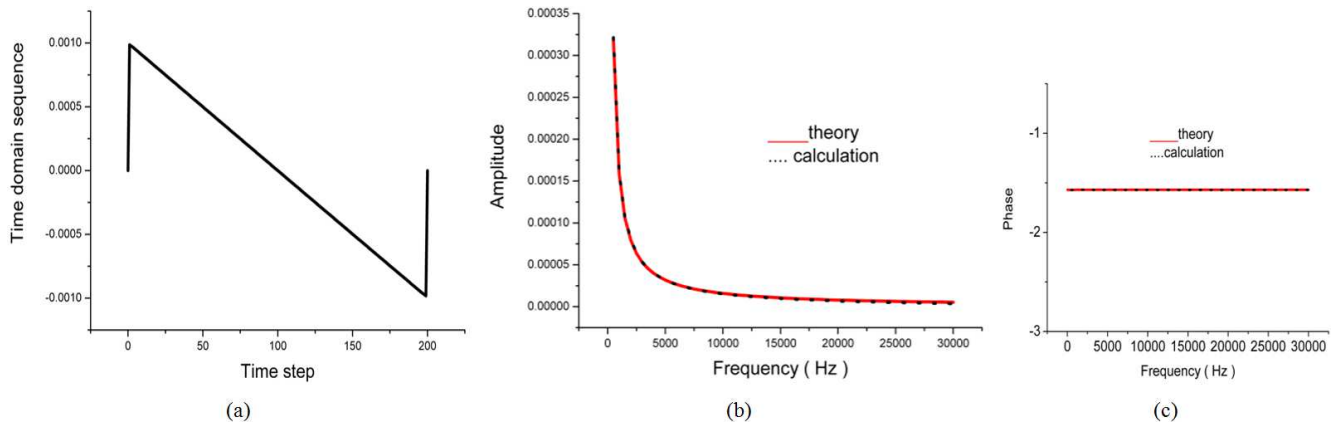


Figure 1. Variation curve figure for example 1.(a) Time domain sequence; (b) amplitude; (c) phase.

***Example 2.

$$F(s) = \frac{1}{\sqrt{s^5 + 4s^4 + 8s^3 + 8s^2 + 7s + 4}}, \quad s = \sigma + j\omega, \quad \omega = 2\pi f \quad (8)$$

This is a mixed fraction of rational and irrational polynomial; it can not be obtained by general method. It can be solved by formula (5). The parameters are chose: $\sigma = -2.0$; $\Delta f = 0.1\text{Hz}$, $f_h = 6\text{Hz}$; $\Delta t = 5 \times 10^{-2}\text{s}$, $Nt = 200$. [1] [2] [3]. After calculation for $F(s)$ it have $F_m(k) = F_m(-k)$, $\phi_m(k) = -\phi_m(-k)$ this frequency domain sequence ($k = 0, 1, 2, N_t$) is just the theory value of the formula (8)

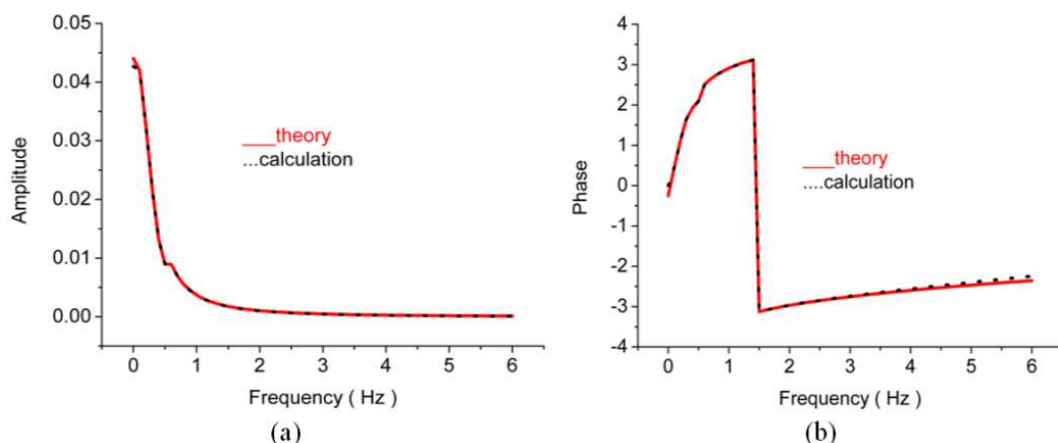


Figure 2. Comparison between theory and calculation.(a) Amplitude;(b) phase.

3. Dispersive Space

3.1. Mode

Research how to establish time domain sequence

Last, the spectrum of time domain sequence wanted is calculated, the spectrum sequence is just calculation value.

Comparison calculation value with theory value ($F(s)$) are respectively shown in Figure 1 (b) and (c). Two figures are respectively the calculation value amplitude and phase (radia) variation curve to frequency. In figures the two values (theory, calculation) are agreement well.

Implimentating time domain solution calculation, the time domain sequence for $K = 2000$ can be taken

As the convergence values, for the values have two or more digits with $K = 1500$. The spectrum of the time domain sequence is calculation value.

Comparison calculation value with theory value ($F(s)$) are shown in Figure 2 (a) and (b). The amplitude and phase are shown respectively in (a) (b) figures. The two are well agreement in $f = 0.1 \rightarrow 6.0\text{Hz}$. The phase value variation with frequency are much large (in (b)) i.e., they are went down abruptly at $f = 1.4\text{Hz}$, 1.5Hz (from 3.1 to -3, 1)

calculation mode from the example of limit frequency band. The example is a rectangular waveguide with disperse property. We know [4]: waveguide sizes are $a=0.02286\text{m}$, $b=0.01016\text{m}$, which working in x band for TE₁₀ (H₁₀) mode. Its effect working frequency is $f = 0.6633 \sim 1.3204 \times 10^{10}\text{Hz}$.

Its main frequency domain parameter is the propagation wave number Γ_{10} for TE₁₀ (H₁₀) mode

$$\Gamma_{10} = j\beta_{10}, \quad \beta_{10}^2 = k_0^2 - k_{c,10}^2 = \frac{\omega^2}{c^2} - \frac{\pi^2}{a^2},$$

$$\beta_{10}(s) = F(s) = \sqrt{\frac{\omega^2}{c^2} - \frac{\pi^2}{a^2}}, s = j\omega \quad \omega = 2\pi f \quad (9)$$

From above frequency domain parameter to find out its time domain sequence, the inverse Laplace transform formula is used as follows

$$\beta_{10}(t) = \frac{1}{2\pi j} \int_0^{j\infty} \beta_{10}(s) e^{st} ds = \frac{1}{2\pi j} \int_0^{j\infty} \sqrt{\frac{\omega^2}{c^2} - \frac{\pi^2}{a^2}} e^{j\omega t} j2\pi df$$

$$= \int_0^{j\infty} \sqrt{\frac{\omega^2}{c^2} - \frac{\pi^2}{a^2}} e^{j\omega t} df$$

In above equation $s = j\omega, \sigma = 0$. as it is often the air in waveguide region. The integral formula $\beta_{10}(t)$ can be expressed by series sum formula, and its working frequency region is considered, we obtain:

$$\beta_{10}(i) = \sum_{k=1}^K \sqrt{\frac{\omega_k^2}{c^2} - \frac{\pi^2}{a^2}} \exp(j\omega_k t_i) \Delta f \quad i = 0, 1, 2, \dots, N_t \quad (10)$$

Just is time domain sequence item.

When $\Delta f = 0.7143 \times 10^8 \text{ Hz}$, the point number of working frequency domain sequence is $k=92$. In above equation the main factor is: $\sqrt{\frac{\omega_k^2}{c^2} - \frac{\pi^2}{a^2}}$ and $\exp(j\omega_k t)$. The second is the function of $\omega_k t$, but the first is only the function of ω_k , it can be expressed by $\beta_{10}(f_k)$

$$\beta_{10}(f_k) = \sum_1^k \sqrt{\frac{\omega_k^2}{c^2} - \frac{\pi^2}{a^2}} \Delta f \quad (11)$$

So the formula (10) can be expressed as follows

$$\beta_{10}(i) = \beta_{10}(f_k) \exp(j\omega_k t_i) \quad i = 0, 1, 2, \dots, N_t \quad (12)$$

The formula (12) is just last formula for calculation.

3.2. Main point for Calculation

Analysis of formula (11) (12):

- Time domain sequence (12) contains two items: the first is formula (11), The second item $\exp(j\omega_k t)$ that is just time sequence item.
- Time sequence item can be calculated from the

second item of formula (12). Analysis and calculation show: the spectrum sequence peak value is located at $\omega_k(f_k)$, At other frequency point that is away from f_k , the spectrum sequence values are approximately a constant.

(c) As saying in (a), the spectrum calculation value for TE₁₀ mode of the rectangular waveguide is equal to the multiply of the second item (the spectrum of time domain sequence) with the first item (TE₁₀ mode wave number value in frequency domain). Therefore, the spectrum sequence calculation value can be thought as departure coefficient between calculation and theory value. Practical calculation show: these coefficient values are approximate 1 at several Δf frequency points apart from f_k .

(d) In analysis the frequency domain factor and time domain factor are expressed at one time in equation (12). This result is not appearing in general materials. Therefore, this analysis technique is called as new idea and new method of 'time-frequency union value'. The calculation results (expressed in 3.3) show: it is rational.

3.3. Calculation Results

This time the centre frequency: $f = 9.84778 \times 10^{10} \text{ Hz}$, Parameters for calculation:

$$\Delta t = 0.14 \times 10^{-10}, \quad N_t = 1000; \quad \Delta f = 0.7143 \times 10^8, \quad N_f = 92$$

The calculation result is: at centre frequency the spectrum sequence peak value is 1001. At each frequency points that depart from the centre point is over 5 frequency points, the spectrum sequence peak value is 1 approximately.

To avoid peak value 1001 appearing at work band k should be taken that is higher than up-limit work frequency, i.e., $f_k = f_{107} = 1.4205 \times 10^{11} \text{ Hz}$. The calculation results are shown in Figure 3. From it, we can see: at effect work frequency $f = 0.6633 \sim 1.3204 \times 10^{11} \text{ Hz}$ its spectrum variation case. i.e., the mode value of complex sequence variation are between 1.019 ~ 1.022. It is the error between theory and calculation is less than 2.5%.

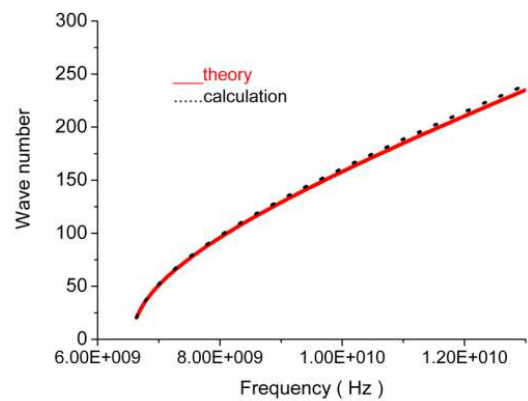


Figure 3. Comparison between theory and calculation of the wave number of waveguide TE₁₀ mode.

3.4. Wave Impedance Analysis and Calculation for Rectangular Waveguide TE10 Mode

Wave impedance equation for rectangular waveguide TE10 mode as follows [3]:

$$Z_{h_{10}}(f) = \frac{k_0}{\beta_{10}(f)} z_0 = \frac{k_0}{\beta_{10}(f)} \sqrt{\frac{\mu_0}{\epsilon_0}} = \frac{\omega \mu_0}{\beta_{10}(f)} \quad (13)$$

Above equation $\beta_{10}(f)$ is wave propagation number. After the same process to above process, the equation for the time domain sequence of wave impedance can be obtained in the following

$$Z_{h_{10}}(i) = Z_{h_{10}}(f_k) \exp(j\omega_k t_i) \quad i = 0, 1, 2, \dots, N_t \quad (14)$$

$$Z_{h_{10}}(f_k) = \sum_{k=1}^K \frac{\omega \mu_0}{\beta_{10}} \Delta f \quad (15)$$

The equation (15) is only the frequency domain sequence

The same process to the propagation wave number, this solving process is also called: new method of 'time-frequency joint value'.

In process for finding out time domain sequence of wave impedance, the calculation parameters are same as above. The calculation result is expressed in Figure 4. It can be seen: in $f = 0.6633 \sim 1.3204 \times 10^{10} \text{ Hz}$. The complex number sequence mode value variation region is $1.019 \sim 1.022$, i.e., the error between calculation and theory mode value is less than 2.5%.

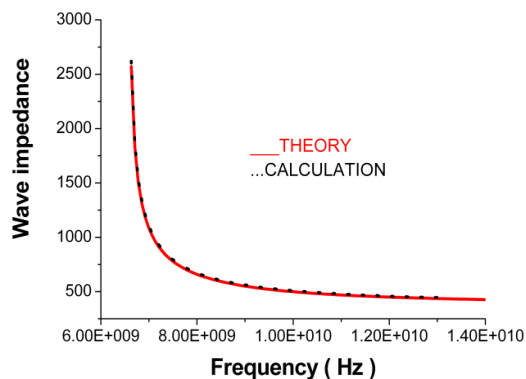


Figure 4. Comparison between theory and calculation value of the wave impedance of waveguide TE10 mode.

4. Conclusion

(1) The algebraical superposition technic presented is a simple and easily implementation. It is applicable for rational and irrational function transformation.

(2) When the algebraical superposition technic is used in the of dispersive space problem, i.e., the analysis for

propagation parameters of rectangular waveguide, The time domain solution obtained is the product of the time domain factor and the frequency factor. The extraordinary solution is first appear in the paper, is called 'Time-frequency Union Value'.

(3) 'time-frequency union technic' is a bright point in the paper

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