



Efficiency Comparisons of Different Estimators for Panel Data Models with Serially Correlated Errors: A Stochastic Parameter Regression Approach

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Abstract: This paper considers panel data models when the errors are first-order serially correlated as well as with stochastic regression parameters. The generalized least squares (GLS) estimators for these models have been derived and examined in this paper. Moreover, an alternative estimator for GLS estimators in small samples has been proposed, this estimator is called simple mean group (SMG). The efficiency comparisons for GLS and SMG estimators have been carried out. The Monte Carlo studies indicate that SMG estimator is more reliable in most situations than the GLS estimators, especially when the model includes one or more non-stochastic parameter.

Keywords: First-Order Serial Correlation, Mixed-Stochastic Parameter Regression, Negative Variances, Pooled Least Squares, Simple Mean Group, Swamy's Test

1. Introduction

In panel data models, the pooled least squares estimator is the best linear unbiased estimator (BLUE) under the classical assumptions as in the general linear regression model. These assumptions are discussed in [1, 2]. An important assumption for panel data models is that the individuals in the database are drawn from a population with a common regression parameter vector. In other words, the parameters of a classical panel data model must be non-stochastic. In particular, this assumption is not satisfied in most economic models, see, e.g., [3, 4]. In this paper, panel data models are studied when this assumption is relaxed. In this case, the model is called stochastic parameter regression (SPR) model. This model has been examined in several publications such as [5-13]. Some statistical and econometric publications refer to this model as Swamy's model, e.g., [14-18].

In SPR model, Swamy [5] assumed that the individuals in the database are drawn from a population with a common regression parameter, which is a non-stochastic component, and a stochastic component, that will allow the parameters to differ from unit to unit. This model has been developed by

many researchers, see, e.g., [19-21].

Generally, the SPR models have been applied in several fields, especially in finance and economics, and they constitute a unifying setup for many statistical problems. For example, Boot and Frankfurter [22] used the SPR model to examine the optimal mix of short and long-term debt for firms. Feige and Swamy [23] applied this model to estimate demand equations for liquid assets, while Boness and Frankfurter [24] used it to examine the concept of risk-classes in finance. Recently, Westerlund and Narayan [25] used the stochastic parameter approach to predict the stock returns at the New York Stock Exchange.

The main objective of this paper is to provide the researcher with some guidelines on how to select the appropriate estimator of panel data models when the parameters are stochastic and mixed-stochastic. To achieve this objective, the conventional estimators of these models in small samples are examined. Also, an alternative consistent estimator of these models has been proposed under an assumption that the errors are first-order serially correlated.

The rest of the paper is organized as follows. Section 2 provides generalized least squares (GLS) estimators in case

of the parameters of the model are stochastic. Section 3 presents an appropriate estimator when the parameters are mixed-stochastic. In section 4, an alternative estimator of these models has been proposed. Section 5 contains the results of Monte Carlo simulation studies. Finally, section 6 offers the concluding remarks.

2. The Model with Stochastic Parameters

Let there be observations for N cross-sectional units over T time periods. Suppose the variable y for the i th unit at time t is specified as a linear function of K strictly exogenous variables, x_{kit} , in the following form:

$$y_{it} = \sum_{k=1}^K \beta_{ki} x_{kit} + u_{it} = x_{it} \beta_i + u_{it}, i = 1, \dots, N; t = 1, \dots, T, \quad (1)$$

where u_{it} denotes the random error term, x_{it} is a $1 \times K$ vector of exogenous variables, and β_i is the $K \times 1$ vector of regression parameters. Stacking (1) over time:

$$y_i = X_i \beta_i + u_i, \quad (2)$$

where $y_i = (y_{i1}, y_{i2}, \dots, y_{iT})'$, $X_i = (x'_{i1}, x'_{i2}, \dots, x'_{iT})'$, $\beta_i = (\beta_{i1}, \dots, \beta_{iK})'$, and $u_i = (u_{i1}, \dots, u_{iT})'$.

Model assumptions:

$$E(\varepsilon_{it} \varepsilon_{js}) = \begin{cases} \sigma_{\varepsilon_i}^2 & \text{if } t = s; i = j \\ 0 & \text{otherwise} \end{cases} \quad i, j = 1, \dots, N; t, s = 1, \dots, T,$$

it is assumed that in the initial time period the errors have the same properties as in subsequent periods. So, assume that: $E(u_{i0}^2) = \sigma_{\varepsilon_i}^2 / (1 - \phi_i^2)$; $\forall i$.

Assumption 3: The exogenous variables are non-stochastic (in repeated samples), and then assume independent with other variables in the model. And the value of $\text{rank}(X_i' X_i) = K$; $\forall i = 1, \dots, N$, where $K < T, N$.

Assumption 4: The vector of regression parameters is specified as: $\beta_i = \bar{\beta} + \mu_i$, where $\bar{\beta} = (\bar{\beta}_1, \dots, \bar{\beta}_K)'$ is a vector of non-stochastic parameter and $\mu_i = (\mu_{i1}, \dots, \mu_{iK})'$ is a vector of random variables with zero means and constant variance-covariances:

$$\hat{\beta}_{SPRSC} = (X' \Lambda^{*-1} X)^{-1} X' \Lambda^{*-1} Y;$$

$$\text{var}(\hat{\beta}_{SPRSC}) = (X' \Lambda^{*-1} X)^{-1} = \left\{ \sum_{i=1}^N [\Gamma^* + \sigma_{\varepsilon_i}^2 (X_i' \Omega_{ii}^{-1} X_i)^{-1}]^{-1} \right\}^{-1}, \quad (4)$$

where $\Lambda^* = V + Z(I_N \otimes \Gamma^*)Z'$, with

$$V = \begin{pmatrix} \sigma_{\varepsilon_1}^2 \Omega_{11} & 0 & \dots & 0 \\ 0 & \sigma_{\varepsilon_2}^2 \Omega_{22} & \ddots & \vdots \\ \vdots & \ddots & \ddots & 0 \\ 0 & \dots & 0 & \sigma_{\varepsilon_N}^2 \Omega_{NN} \end{pmatrix},$$

and

$$\Gamma^* = \left[\frac{1}{N-1} \left(\sum_{i=1}^N \beta_i^* \beta_i^{*'} - \frac{1}{N} \sum_{i=1}^N \beta_i^* \sum_{i=1}^N \beta_i^{*'} \right) \right] - \frac{1}{N} \sum_{i=1}^N \sigma_{\varepsilon_i}^2 (X_i' \Omega_{ii}^{-1} X_i)^{-1}, \quad (5)$$

where $\beta_i^* = (X_i' \Omega_{ii}^{-1} X_i)^{-1} X_i' \Omega_{ii}^{-1} y_i$, with

$$\Omega_{ii} = \frac{1}{1 - \phi_i^2} \begin{pmatrix} 1 & \phi_i & \phi_i^2 & \dots & \phi_i^{T-1} \\ \phi_i & 1 & \phi_i & \dots & \phi_i^{T-2} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \phi_i^{T-1} & \phi_i^{T-2} & \phi_i^{T-3} & \dots & 1 \end{pmatrix}.$$

Assumption 1: The errors have zero mean, i.e., $E(u_i) = 0$; $\forall i = 1, \dots, N$.

Assumption 2: The errors have a constant variance for each individual but they are cross-sectional heteroscedasticity as well as they are first-order serially correlated: $u_{it} = \phi_i u_{i,t-1} + \varepsilon_{it}$; $|\phi_i| < 1$, where ϕ_i for $i = 1, \dots, N$ are first-order serial correlation coefficients and are fixed. Where $E(\varepsilon_{it}) = 0$, $E(u_{i,t-1} \varepsilon_{jt}) = 0$; $\forall i, j$, and t . And

$$E(\mu_i) = 0; E(\mu_i \mu_j') = \begin{cases} \Gamma^* & \text{if } i = j \\ 0 & \text{if } i \neq j \end{cases} \quad i, j = 1, \dots, N,$$

where $\Gamma^* = \text{diag}\{\gamma_k^2\}$; for $k = 1, \dots, K$. And assume also that $E(\mu_i u_{jt}) = 0 \forall i$ and j .

Using assumption 4, the model in (2) can be rewritten as:

$$Y = X \bar{\beta} + e; e = Z \mu + u, \quad (3)$$

where $Y = (y_1', y_2', \dots, y_N')'$, $X = (X_1', X_2', \dots, X_N')'$, $u = (u_1', \dots, u_N')'$, $\mu = (\mu_1', \dots, \mu_N')'$, and $Z = \text{diag}\{X_i\}$; for $i = 1, \dots, N$. Under assumptions 1 to 4, the BLUE of $\bar{\beta}$ and the variance-covariance matrix of it are:

It is noted that the $\hat{\beta}_{SPRSC}$ can be rewrite as a weighted average of GLS estimator for each cross-sectional unit:

$$\hat{\beta}_{SPRSC} = \sum_{i=1}^N W_i^* \beta_i^*, \quad (6)$$

where

$$W_i^* = \left\{ \sum_{i=1}^N [\Gamma^* + \sigma_{\varepsilon_i}^2 (X_i' \Omega_{ii}^{-1} X_i)^{-1}]^{-1} \right\}^{-1} \left\{ \sum_{i=1}^N [\Gamma^* + \sigma_{\varepsilon_i}^2 (X_i' \Omega_{ii}^{-1} X_i)^{-1}]^{-1} \right\}.$$

To make the $\hat{\beta}_{SPRSC}$ estimator feasible, we suggest using the following consistent estimators for ϕ_i and $\sigma_{\varepsilon_i}^2$:

$$\hat{\phi}_i = \frac{\sum_{t=2}^T \hat{u}_{it} \hat{u}_{i,t-1}}{\sum_{t=2}^T \hat{u}_{i,t-1}^2}; \hat{\sigma}_{\varepsilon_i}^2 = \frac{\hat{\varepsilon}_i' \hat{\varepsilon}_i}{T-K}, \quad (7)$$

where $\hat{u}_i = (\hat{u}_{i1}, \dots, \hat{u}_{iT})' = y_i - X_i \hat{\beta}_i$; $\hat{\beta}_i = (X_i' X_i)^{-1} X_i' y_i$, while $\hat{\varepsilon}_i = (\hat{\varepsilon}_{i1}, \hat{\varepsilon}_{i2}, \dots, \hat{\varepsilon}_{iT})'$; $\hat{\varepsilon}_{i1} = \hat{u}_{i1} \sqrt{1 - \hat{\phi}_i^2}$, and

$$\hat{\varepsilon}_{it} = \hat{u}_{it} - \hat{\phi}_i \hat{u}_{i,t-1} \text{ for } t = 2, \dots, T. \quad ^1$$

By replacing ϕ_i by $\hat{\phi}_i$ in Ω_{ii} matrix, it gives consistent estimators of Ω_{ii} , say $\hat{\Omega}_{ii}$. Use of $\hat{\sigma}_{\varepsilon_i}^2$ and $\hat{\Omega}_{ii}$ to get consistent estimators of V and Γ^* , say \hat{V} and $\hat{\Gamma}^*$. By using consistent estimators ($\hat{\sigma}_{\varepsilon_i}^2$, $\hat{\Omega}_{ii}$, and $\hat{\Gamma}^*$), it gives a consistent estimator of Λ^* , say $\hat{\Lambda}^*$. And then use $\hat{\Lambda}^*$ to get a feasible estimator of $\hat{\beta}_{SPRSC}$.

Note that in non-stochastic parameter model, we assume that the errors are cross-sectional heteroskedasticity as well as they are first-order serially correlated. However, the individuals in the database are drawn from a population with a common regression parameter vector β , i.e., $\beta_1 = \dots = \beta_N = \beta$. Therefore the BLUE of β , under assumptions 1 to 3, is:

$$\hat{\beta}_{PLS} = (X'V^{-1}X)^{-1}(X'V^{-1}Y),$$

this estimator has been termed pooled least squares (PLS) estimator. Using \hat{V} that defined above, it gives the feasible (FPLS) estimator of PLS.

In standard stochastic parameter model that presented by Swamy [5], he assumed that the errors are cross-sectional heteroscedasticity and they are serially independently. As for the parameters, he assumed the same conditions in assumption 4. Therefore, the BLUE of β , under Swamy's [5] assumptions, is:

$$\hat{\beta}_{SPR} = (X'\Lambda^{-1}X)^{-1}X'\Lambda^{-1}Y,$$

where $\Lambda = (\Sigma_H \otimes I_T) + Z(I_N \otimes \Gamma)Z'$, with $\Sigma_H = \text{diag}\{\sigma_i^2\}$; for $i = 1, \dots, N$, $\sigma_i^2 = \text{var}(u_i)$, and

$$\Gamma = \left[\frac{1}{N-1} \left(\sum_{i=1}^N \beta_i \beta_i' - \frac{1}{N} \sum_{i=1}^N \beta_i \sum_{i=1}^N \beta_i' \right) - \left[\frac{1}{N} \sum_{i=1}^N \sigma_i^2 (X_i' X_i)^{-1} \right] \right]$$

To make the $\hat{\beta}_{SPR}$ estimator feasible, Swamy [27] used the following unbiased and consistent estimator for σ_i^2 :

$$\hat{\sigma}_i^2 = \frac{\hat{u}_i' \hat{u}_i}{T-K},$$

where \hat{u}_i is defined in (7). Swamy [6, 7] showed that $\hat{\beta}_{SPR}$ estimator, under Swamy's [5] assumptions, is consistent as both $N, T \rightarrow \infty$ and is asymptotically efficient as $T \rightarrow \infty$.

It is worth noting that, just as in the error-components model, the estimates values of Γ^* and Γ are not necessarily non-negative definite. So, expect to obtain the negative values of the estimated variances of $\hat{\beta}_{SPRSC}$ and $\hat{\beta}_{SPR}$. To avoid this problem, it can use the following consistent estimators for Γ^* and Γ :

$$\hat{\Gamma}^{**} = \frac{1}{N-1} \left(\sum_{i=1}^N \hat{\beta}_i \hat{\beta}_i' - \frac{1}{N} \sum_{i=1}^N \hat{\beta}_i \sum_{i=1}^N \hat{\beta}_i' \right),$$

$$\hat{\Gamma}^+ = \frac{1}{N-1} \left(\sum_{i=1}^N \hat{\beta}_i \hat{\beta}_i' - \frac{1}{N} \sum_{i=1}^N \hat{\beta}_i \sum_{i=1}^N \hat{\beta}_i' \right).$$

Swamy [5] suggested use $\hat{\Gamma}^+$ if one finds the estimated variance of $\hat{\beta}_{SPR}$ is negative.² Although that these estimators ($\hat{\Gamma}^{**}$ and $\hat{\Gamma}^+$) are biased but they are non-negative definite and consistent when $T \rightarrow \infty$, see [16, 28]. Moreover, these estimators may be suitable in case of moderate or large samples but they are not suitable for small samples.

3. The Model with Mixed-Stochastic Parameters

In this section, the GLS estimator for the model with mixed (stochastic and non-stochastic) parameters will be derived. In this case, the (mixed SPR) model can be written as:

$$y_i = X_{1i}\beta_{1i} + X_{2i}\beta_2 + u_i = D_i\alpha_i + u_i, \quad (8)$$

where y_i and u_i are defined in (2), $D_i = (X_{1i}, X_{2i})$ where X_{1i} and X_{2i} are $T \times K_1$ and $T \times K_2$ matrices of observations on K_1 and K_2 explanatory variables, respectively. $\alpha_i = (\beta_{1i}', \beta_2')'$, where β_{1i} is a $K_1 \times 1$ vector of parameters assumed to be stochastic with mean $\bar{\beta}_1$ and variance-covariance matrix Γ_{β_1} , and β_2 is a $K_2 \times 1$ vector of parameters assumed to be non-stochastic, where $K_1 + K_2 = K$. The model in (8) applies to each of N cross-sections. Under suppose that $\beta_{1i} = \bar{\beta}_1 + \mu_{\beta_1}$, these N individual equations can be combined as:

$$Y = D\bar{\alpha} + \tau, \quad (9)$$

where Y is defined in (3), $D = (D_1', \dots, D_N')'$, $\bar{\alpha} = (\bar{\beta}_1', \beta_2')'$, and $\tau = (\tau_1', \dots, \tau_N')'$, where $\tau_i = X_{1i}\mu_{\beta_1} + u_i$.

Under Swamy's [5] assumptions, this model has been examined by Swamy [27] and Rosenberg [30]. However, in this paper, this model under assumptions (1 to 4) will be examined, therefore the variance-covariance matrix of τ is:

$$E(\tau \tau') = V + Z_{\beta_1}(I_N \otimes \Gamma_{\beta_1})Z_{\beta_1}' = \Pi,$$

where

$$Z_{\beta_1} = \begin{pmatrix} X_{11} & 0 & \dots & 0 \\ 0 & X_{12} & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & X_{1N} \end{pmatrix}.$$

The GLS estimator of $\bar{\alpha}$ is:

$$\hat{\bar{\alpha}}_{MSPRSC} = (D'\Pi^{-1}D)^{-1}D'\Pi^{-1}Y = \begin{pmatrix} X_1'\Pi^{-1}X_1 & X_1'\Pi^{-1}X_2 \\ X_2'\Pi^{-1}X_1 & X_2'\Pi^{-1}X_2 \end{pmatrix}^{-1} \begin{pmatrix} X_1'\Pi^{-1}Y \\ X_2'\Pi^{-1}Y \end{pmatrix}, \quad (10)$$

Where $X_1 = (X_{11}', \dots, X_{1N}')'$ and $X_2 = (X_{21}', \dots, X_{2N}')'$.

Since the mixed SPR model is a special case of the SPR model when the variances of certain parameters are assumed to be equal to zero, therefore it can get the feasible estimator

¹ The estimator of ϕ_i in (7) is consistent, but it is not unbiased. See [26] for other suitable consistent estimators of it that are often used in practice.

² This suggestion was been used by Stata program, specifically in `xtcrhh` and `xtcrhh2` Stata's commands. See [14].

for $\hat{\alpha}$ by the following algorithm:

Step 1: Calculate $\hat{\Gamma}^*$ as in (5), by using consistent estimators of $\sigma_{\varepsilon_i}^2$ and Ω_{ii} as given in (7).

Step 2: Find the estimation of Γ_{β_1} , say $\hat{\Gamma}_{\beta_1}$, by removing the rows and columns for non-stochastic parameter (that within β_2 vector) from $\hat{\Gamma}^*$ matrix.

Step 3: Find the estimation of Π , say $\hat{\Pi}$, by using $\hat{\Gamma}_{\beta_1}$ and consistent estimators in (7).

Step 4: Finally, using $\hat{\Pi}$ in (10) to get the feasible estimator for $\hat{\alpha}$.

The main point in this algorithm is step 2, i.e., how determine the non-stochastic parameters in the model. It needs to a statistical test for randomness of parameters. In this paper, Swamy's [5] test will be used. The basic idea of this test; since μ_i is fixed for every i , as given in assumption 4, so it becomes possible to test of random variation indirectly by testing whether or not the non-stochastic parameters vectors β_i are all equal. That is, the null hypothesis is:

$$H_0: \beta_1 = \dots = \beta_N = \bar{\beta}.$$

The test statistic is:

$$S = \sum_{i=1}^N (\hat{\beta}_i - \hat{\beta}_s)' \frac{X_i' X_i}{\hat{\sigma}_i^2} (\hat{\beta}_i - \hat{\beta}_s), \quad (11)$$

where

$$\hat{\beta}_s = [X'(\hat{\Sigma}_H \otimes I_T)^{-1} X]^{-1} [X'(\hat{\Sigma}_H \otimes I_T)^{-1} Y],$$

where $\hat{\Sigma}_H$ is the estimated matrix of Σ_H . Swamy [5] showed that, under H_0 , the test statistic in (11) is asymptotically chi-square distributed, with $K(N-1)$ degrees of freedom, as $T \rightarrow \infty$ and N is fixed.

It can apply Swamy's [5] test on Mixed SPR model as in SPR model. Beginning, suppose that mixed SPR model in (8) can be rewritten as:³

$$y_i = Q_{1i} b_{1i} + Q_{2i} b_{2i} + X_{2i} \beta_2 + u_i, \quad (12)$$

where $\beta_{1i} = (b'_{1i}, b'_{2i})'$, where b_{1i} is a $h_1 \times 1$ vector of stochastic parameters to be included in a test of some hypotheses, and b_{2i} is a $h_2 \times 1$ vector of stochastic parameters, but these are to be excluded from the test; $X_{1i} = (Q'_{1i}, Q'_{2i})'$, where Q_{1i} and Q_{2i} are $T \times h_1$ and $T \times h_2$ matrices, respectively, of observations on independent variables; and all other terms were defined when discussing equation (8). As previously noted, the Mixed SPR model can be rewritten as:

$$Y = Q_1 \bar{b}_1 + Q_2 \bar{b}_2 + X_2 \beta_2 + \tau$$

where Y , X_2 , and τ are defined in (3), (10), and (9), respectively, $Q_1 = (Q'_{11}, \dots, Q'_{1N})'$, $Q_2 = (Q'_{21}, \dots, Q'_{2N})'$, and \bar{b}_1 and \bar{b}_2 are means of stochastic parameters b_{1i} and b_{2i} , respectively.

In the Mixed SPR model, procedures are available to

test the following hypothesis for randomness of parameters:

$$H_0: b_{11} = \dots = b_{1N} = \bar{b}_1.$$

This is analogous to the indirect test for randomness in the SPR model. In this case, there may be a subset of parameters which are initially assumed stochastic but which are to be tested for randomness. In this case, the test statistic that can be used to conduct the test is:

$$\sum_{i=1}^N (\hat{b}_{1i} - \hat{b}_1)' \frac{Q'_{1i} Q_{1i}}{\hat{\sigma}_i^2} (\hat{b}_{1i} - \hat{b}_1),$$

where \hat{b}_1 is the estimated vector of parameters assuming they are non-stochastic and \hat{b}_{1i} (for $i = 1, \dots, N$) are the separate estimates of the parameters. If the null hypothesis is accepted, the parameters are non-stochastic and should be treated in the manner of the β_2 vector of parameters in (12). But if the null hypothesis is rejected, the parameters b_{1i} are treated as stochastic.

4. An Alternative Estimator

Generally, It is easy to verify that under assumptions 1 to 4 the PLS and SPR are unbiased for β and with variance-covariance matrices:

$$\text{var}(\hat{\beta}_{SPR}) = F_2 \Lambda^* F_2'; \quad F_2 = (X' \Lambda^{-1} X)^{-1} X' \Lambda^{-1}. \quad (13)$$

$$\text{var}(\hat{\beta}_{PLS}) = F_1 \Lambda^* F_1'; \quad F_1 = (X' V^{-1} X)^{-1} X' V^{-1}, \quad (14)$$

The efficiency gains, from the use of SPRSC estimator, it can be summarized in the following equations:

$$\begin{aligned} EG_{SPR} &= \text{var}(\hat{\beta}_{SPR}) - \text{var}(\hat{\beta}_{SPRSC}) \\ &= (F_2 - F_0) \Lambda^* (F_2 - F_0)', \end{aligned}$$

$$\begin{aligned} EG_{PLS} &= \text{var}(\hat{\beta}_{PLS}) - \text{var}(\hat{\beta}_{SPRSC}) \\ &= (F_1 - F_0) \Lambda^* (F_1 - F_0)', \end{aligned}$$

where $F_0 = (X' \Lambda^{*-1} X)^{-1} X' \Lambda^{*-1}$. Since Λ, V and Λ^* are positive definite matrices, then EG_{PLS} and EG_{SPR} matrices are positive semi-definite matrices. In other words, the SPRSC estimator is more efficient than PLS and SPR estimators. These efficiency gains are increasing when $|\phi_i|$ and/or γ_k^2 are increasing. However, these efficiency gains may be not achieved in practice because Λ and Λ^* are not consistently positive definite matrices, especially in small samples, as explained above. Therefore, in the following, an alternative estimator will be proposed that more suitable for the model than SPRSC estimator when the sample size is small. Moreover, the properties of this estimator will be studied.

³ See [2] for more information about this test.

When Swamy [27] proving that $\hat{\beta}_{SPR}$ is consistent, he showed that:

$$\text{plim}_{T \rightarrow \infty} \hat{\beta}_{SPR} = \left\{ \sum_{i=1}^N \left[\text{plim}_{T \rightarrow \infty} \Gamma + \text{plim}_{T \rightarrow \infty} \frac{\sigma_{\varepsilon_i}^2}{T} \cdot \text{plim}_{T \rightarrow \infty} \left(\frac{X_i' X_i}{T} \right)^{-1} \right]^{-1} \right\}^{-1} \left\{ \sum_{i=1}^N \left[\text{plim}_{T \rightarrow \infty} \Gamma + \text{plim}_{T \rightarrow \infty} \frac{\sigma_{\varepsilon_i}^2}{T} \cdot \text{plim}_{T \rightarrow \infty} \left(\frac{X_i' X_i}{T} \right)^{-1} \right] \right\} \left\{ \beta_i + \text{plim}_{T \rightarrow \infty} \left(\frac{X_i' X_i}{T} \right)^{-1} \cdot \text{plim}_{T \rightarrow \infty} \frac{X_i' u_i}{T} \right\},$$

using this conclusion and under the assuming that $\text{plim}_{T \rightarrow \infty} T^{-1} X_i' X_i$ is finite and positive definite for all i , it can get:

$$\text{plim}_{T \rightarrow \infty} \hat{\beta}_{SPR} = \frac{1}{N} \sum_{i=1}^N \beta_i. \quad (15)$$

Similarly, assume that $\text{plim}_{T \rightarrow \infty} T^{-1} X_i' \hat{\Omega}_{ii}^{-1} X_i$ is finite and positive definite for all i and for $|\phi_i| < 1$ to get:

$$\text{plim}_{T \rightarrow \infty} \hat{\beta}_{SPRSC} = \left\{ \sum_{i=1}^N \left[\text{plim}_{T \rightarrow \infty} \hat{\Gamma}^* + \text{plim}_{T \rightarrow \infty} \frac{\hat{\sigma}_{\varepsilon_i}^2}{T} \cdot \text{plim}_{T \rightarrow \infty} \left(\frac{X_i' \hat{\Omega}_{ii}^{-1} X_i}{T} \right)^{-1} \right]^{-1} \right\}^{-1} \left\{ \sum_{i=1}^N \left[\text{plim}_{T \rightarrow \infty} \hat{\Gamma}^* + \text{plim}_{T \rightarrow \infty} \frac{\hat{\sigma}_{\varepsilon_i}^2}{T} \cdot \text{plim}_{T \rightarrow \infty} \left(\frac{X_i' \hat{\Omega}_{ii}^{-1} X_i}{T} \right)^{-1} \right] \right\} \left\{ \beta_i + \text{plim}_{T \rightarrow \infty} \left(\frac{X_i' \hat{\Omega}_{ii}^{-1} X_i}{T} \right)^{-1} \cdot \text{plim}_{T \rightarrow \infty} \frac{X_i' \hat{\Omega}_{ii}^{-1} u_i}{T} \right\} = \frac{1}{N} \sum_{i=1}^N \beta_i. \quad (16)$$

From (15), (16), and whereas $\hat{\beta}_i$ is an unbiased estimator for β_i , therefore we will suggest the following estimator as an alternative estimator for SPR and SPRSC:

$$\hat{\beta}_{SMG} = \frac{1}{N} \sum_{i=1}^N \hat{\beta}_i. \quad (17)$$

Note that this estimator is the simple average of ordinary least squares estimators ($\hat{\beta}_i$), so it is defined in econometric literature⁴ as the simple mean group (SMG) estimator. The SMG estimator is also used by Pesaran and Smith [31] for estimation of dynamic panel data (DPD) models with stochastic parameters.⁵ It is easy to verify that SMG estimator is consistent of $\bar{\beta}$ when both $N, T \rightarrow \infty$. Moreover, statistical properties of SMG estimator will be explained in the following lemma:

Lemma 1:

If assumptions 1 to 4 are satisfied, then the SMG is unbiased estimator of $\bar{\beta}$ and consistent estimator of the variance-covariance matrix of $\hat{\beta}_{SMG}$ is:

$$\widehat{var}(\hat{\beta}_{SMG}) = \frac{1}{N} \hat{\Gamma}^* + \frac{1}{N^2} \sum_{i=1}^N \hat{\sigma}_{\varepsilon_i}^2 (X_i' X_i)^{-1} X_i' \hat{\Omega}_{ii} X_i (X_i' X_i)^{-1}. \quad (18)$$

The next lemma explains the asymptotic variances (as $T \rightarrow \infty$ with N fixed) properties of SPRSC, SPR, and SMG estimators.

Lemma 2:

If assumptions 1 to 4 are satisfied and $\text{plim}_{T \rightarrow \infty} T^{-1} X_i' X_i$, $\text{plim}_{T \rightarrow \infty} T^{-1} X_i' \hat{\Omega}_{ii}^{-1} X_i$ are finite and positive definite for all i , then the estimated asymptotic variance-covariance matrices of SPRSC, SPR, and SMG estimators

are:

$$\text{plim}_{T \rightarrow \infty} \widehat{var}(\hat{\beta}_{SPRSC}) = \text{plim}_{T \rightarrow \infty} \widehat{var}(\hat{\beta}_{SPR}) = \text{plim}_{T \rightarrow \infty} \widehat{var}(\hat{\beta}_{SMG}) = \frac{1}{N} \Gamma^+.$$

Lemma 2 shows that the means and the variance-covariance matrices of the limiting distributions of SPRSC, SPR, and SMG estimators are the same and are equal to $\bar{\beta}$ and $\frac{1}{N} \Gamma^+$ respectively even if the errors are correlated as in assumption 2. Therefore, it is not expected to increase the asymptotic efficiency of SPRSC about SPR and SMG. This does not mean that the SPRSC estimator cannot be more efficient than SPR and SMG in small samples when the errors are correlated as in assumption 2, this will be examined in the following Monte Carlo simulation.

5. The Simulation Studies

In this section, two Monte Carlo simulation studies will be conducted. In first, examine the problem of negative variance estimates and the power of Swamy's test in different models (non-stochastic, stochastic, and mixed-stochastic) when the sample size is small and moderate. While in the second, make comparisons between the behavior of the pooled least squares ($\hat{\beta}_{PLS}$), simple mean group ($\hat{\beta}_{SMG}$), and stochastic parameter ($\hat{\beta}_{SPR}$, $\hat{\beta}_{SPRSC}$, and $\hat{\alpha}_{MSPRSC}$) estimators in small samples. The programs to set up the Monte Carlo simulation studies, written in R language, are available upon request.⁶ Monte Carlo experiments were carried out, in the two studies, based on the following data generating process:

⁴ Such as [12, 17].

⁵ For more information about the estimation methods for DPD models, see, e.g., [29, 32-36].

⁶ For information about how to create Monte Carlo studies using R, see [37].

$$y_{it} = \beta_{0i} + \beta_{1i}x_{1it} + u_{it} = x_{it}\bar{\beta} + x_{it}\mu_i + u_{it}, i = 1, \dots, N; t = 1, \dots, T, \quad (19)$$

where $x_{it} = (1, x_{1it})$, $\bar{\beta} = (\bar{\beta}_0, \bar{\beta}_1)'$, and $\mu_i = (\mu_{0i}, \mu_{1i})'$.

5.1. First Study: Negative Variance Estimates and the Power of Test

In this study, the model in (19) was generated as in the second simulation study below but after replacing the following: $\phi = 0$, $\gamma_k^2 = 5$, $L = 10000$, and $N = T = 5, 10, 20, 25$, and 50 . The simulation results are summarized in figures 1 and 2. Specifically, Figure 1 presents the percent of negative variance (PNV) estimates of \hat{F} . While the results for the power of Swamy's test are presented in Figure 2.

Figure 1 indicates that the values of PNV are not appearing when $N = T \geq 10$ if the parameters are stochastic. However, if one or more of the parameters is non-stochastic, the values of PNV are close to zero when $N = T \geq 50$. Moreover, the values of PNV are increasing when the value of σ_ε is increased.

Figure 2 indicates that when the parameters are stochastic the power of test is very high (close to one) when $N = T \geq 20$. However, if one or more of the parameters is non-stochastic, the power of test is still low even if $N = T \geq 50$. Moreover, the power of test is increasing when the value of σ_ε is decreased.

From figures 1 and 2, conclude that if the sample size (N and/or T) less than 20, the efficiency of stochastic parameter estimators ($\hat{\beta}_{SPR}$, $\hat{\beta}_{SPRSC}$, and $\hat{\alpha}_{MSPRSC}$) is very affected. Therefore, the efficiency of these estimators in small samples will be examined.

5.2. Second Study: The Performance of Estimators in Small Samples

In this study, the model in (19) was generated as follows:

1. The values of the independent variable, x_{1it} , were generated as independent normally distributed random variable with mean 5 and standard deviation 10. The values of x_{1it} were allowed to differ for each cross-sectional unit. However, once generated for all N cross-sectional units the values were held fixed over all Monte Carlo trials.
2. The parameters, β_{0i} and β_{1i} , were generated as in assumption 4: $\beta_i = (\beta_{0i}, \beta_{1i})' = \bar{\beta} + \mu_i$, where the vector of $\bar{\beta} = (5, 5)'$, and μ_i were generated as multivariate normal distributed with mean zero vector and a variance-covariance matrix $\Gamma^* = \text{diag}\{\gamma_k^2; k = 0, 1\}$. The values of γ_k were chosen to be fixed for all k and equal to 0 or 25. Note that when $\gamma_k = 0$, the parameters are non-stochastic.
3. The errors, u_{it} , were generated as in assumption 2: $u_{it} = \phi u_{i,t-1} + \varepsilon_{it}$, where the values of $\varepsilon_i = (\varepsilon_{i1}, \dots, \varepsilon_{iT})' \forall i = 1, 2, \dots, N$ were generated as multivariate normal distributed with mean zero vector and a constant variance-covariance matrix $\sigma_\varepsilon^2 I_T$ for all i . The values of σ_ε and ϕ were chosen to be: σ_ε equal

to 1 or 10, and ϕ equal to 0.35 or 0.95. The initial values of u_{it} are generated as $u_{i1} = \varepsilon_{i1}/\sqrt{1-\phi^2} \forall i = 1, 2, \dots, N$. The errors were allowed to differ for each cross-sectional unit on a given Monte Carlo trial and were allowed to differ between trials. The errors are independent with all independent variable.

4. The values of $N = 5$ and T were chosen to be 4, 6, ..., or 20 to represent small samples for the number of the cross-sectional units and time dimension.
5. The number of replications (L) is 5000 for each experiment, and all the results of all separate experiments are obtained by precisely the same series of random numbers.

To compare the small samples performance for the different estimators, the three different types of regression parameters (non-stochastic, stochastic, and mixed-stochastic) have been designed in this simulation study. To raise the efficiency of the comparison between these estimators, the relative efficiency ratio (RER) for each estimator has been calculated. The RER of any estimator, for a Monte Carlo experiment, is calculated by:

$$\text{RER}(\hat{\beta}_{k(e)}) = M. \widehat{\text{var}}(\hat{\beta}_{k(e)}) / M. \widehat{\text{var}}(\hat{\beta}_{k(p)}); k = 0, 1,$$

where

$$M. \widehat{\text{var}}(\hat{\beta}_{k(a)}) = \frac{1}{L} \sum_{l=1}^L \widehat{\text{var}}(\hat{\beta}_{k(a)}^l), \text{ for } a = e, p,$$

where the subscript e indicates the estimator that it calculated the ratio, while p indicates the appropriate estimator in each model in this simulation study. For example, The RER value of FPLS estimate of $\hat{\beta}_0$ when the all regression parameters are stochastic is calculated as:

Step 1: Calculate the mean of variance for L Monte Carlo trials for FPLS and SPRSC estimators:

$$M. \widehat{\text{var}}(\hat{\beta}_{0(FPLS)}) = \frac{1}{L} \sum_{l=1}^L \widehat{\text{var}}(\hat{\beta}_{0(FPLS)}^l),$$

$$M. \widehat{\text{var}}(\hat{\beta}_{0(SPRSC)}) = \frac{1}{L} \sum_{l=1}^L \widehat{\text{var}}(\hat{\beta}_{0(SPRSC)}^l),$$

where $\widehat{\text{var}}(\hat{\beta}_{0(PLS)})$ and $\widehat{\text{var}}(\hat{\beta}_{0(SPRSC)})$ are obtained using feasible formulas for (13) and (4), respectively.

Step 2: Find the RER value: $\text{RER}(\hat{\beta}_{0(FPLS)}) = M. \widehat{\text{var}}(\hat{\beta}_{0(FPLS)}) / M. \widehat{\text{var}}(\hat{\beta}_{0(SPRSC)})$.

The simulation results are summarized in figures 3 to 6. Specifically, Figure 3 presents the natural logarithm of the RER (LRER) values of intercept and slope estimates for FPLS, SPR, and SMG estimators when the all regression parameters are stochastic (stochastic parameter model). While the results in case of the all regression parameters are non-stochastic (non-stochastic parameter model) are presented in Figure 4. This Figure displays the LRER values of intercept and slope estimates for SPR, SPRSC, and SMG estimators. Finally, figures 5 and 6 present the log (RER) values of intercept and slope estimates for FPLS, SPR,

SPRSC, MSPRSC, and SMG estimators when the vector of regression parameters contains both stochastic and non-stochastic parameter (mixed-stochastic parameter model). Specifically, Figure 5 displays the results when the intercept parameter is stochastic and the slope parameter is non-stochastic, we refer to this model as Mixed-stochastic type-I

model. Figure 6 displays the inverse case; when the intercept parameter is non-stochastic and the slope parameter is stochastic, also we refer to this model as Mixed-stochastic type-II model. The different formulas of variances of estimators that used in this study are summarized in Table 1.

Table 1. The formulas of variances that used in the simulation study.

Model type	No. Figure	Appropriate estimator	Other estimators	The formula of variance
Stochastic	3	SPRSC	FPLS SPR SMG	Equation (4)
				Equation (13)
				Equation (14)
				Equation (18)
Non-stochastic	4	FPLS	SPR SPRSC SMG	$(X' \hat{V}^{-1} X)^{-1}$
				$(X' \hat{\Lambda}^{-1} X)^{-1} X' \hat{\Lambda}^{-1} \hat{V} \hat{\Lambda}^{-1} X (X' \hat{\Lambda}^{-1} X)^{-1}$
				$(X' \hat{\Lambda}^{*-1} X)^{-1} X' \hat{\Lambda}^{*-1} \hat{V} \hat{\Lambda}^{*-1} X (X' \hat{\Lambda}^{*-1} X)^{-1}$
				$\frac{1}{N^2} \sum_{i=1}^N \hat{\sigma}_{\varepsilon_i}^2 (X_i' X_i)^{-1} X_i' \hat{\Omega}_{ii} X_i (X_i' X_i)^{-1}$
Mixed-stochastic type-I	5	MSPRSC	FPLS SPR SPRSC SMG	$(D' \hat{\Pi}^{-1} D)^{-1}$
				$(X' \hat{V}^{-1} X)^{-1} X' \hat{V}^{-1} \hat{\Pi} \hat{V}^{-1} X (X' \hat{V}^{-1} X)^{-1}$
				$(X' \hat{\Lambda}^{-1} X)^{-1} X' \hat{\Lambda}^{-1} \hat{\Pi} \hat{\Lambda}^{-1} X (X' \hat{\Lambda}^{-1} X)^{-1}$
				$(X' \hat{\Lambda}^{*-1} X)^{-1} X' \hat{\Lambda}^{*-1} \hat{\Pi} \hat{\Lambda}^{*-1} X (X' \hat{\Lambda}^{*-1} X)^{-1}$
Mixed-stochastic type-II	6			$\frac{1}{N} \hat{\Gamma}_{\beta 1} + \frac{1}{N^2} \sum_{i=1}^N \hat{\sigma}_{\varepsilon_i}^2 (X_i' X_i)^{-1} X_i' \hat{\Omega}_{ii} X_i (X_i' X_i)^{-1}$

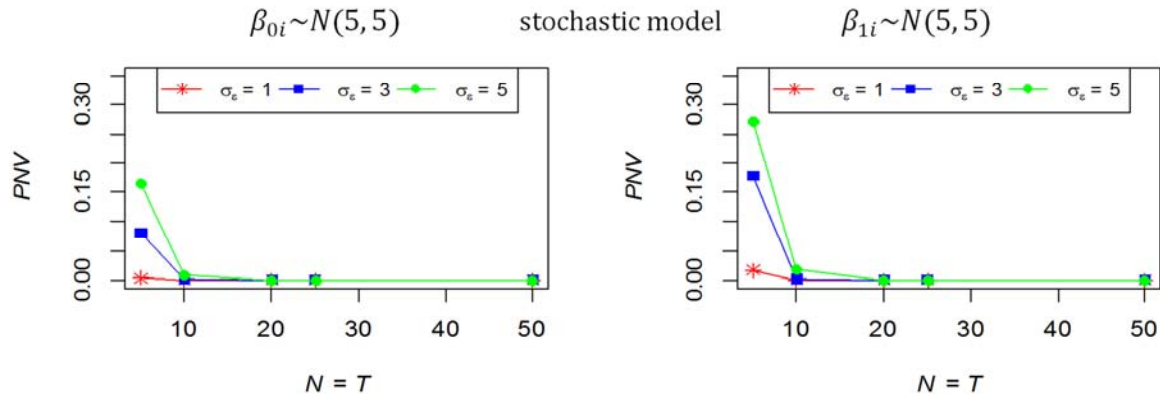
Figure 3 indicates that the values of LRER for SPR and SMG are very close and almost equal zero for all simulation situations (for every value of σ_ε and ϕ), this means that the efficiency of SPR and SMG is close to the efficiency of SPRSC estimator even if $\sigma_\varepsilon = 10$ and $\phi = .95$, then SPR and SMG are good alternatives estimators for SPRSC in stochastic parameter models. But FPLS is inefficient estimator (highest LRER) for this model even if $\sigma_\varepsilon = 1$ and $\phi = .35$.

Figure 4 indicates that SPR and SPRSC estimators are greater in LRER than SMG for every value of σ_ε and ϕ , this means that SMG estimator is more efficient than SPR and SPRSC estimators and it is a good alternative estimator for FPLS in non-stochastic parameter models.

Figures 5 and 6 indicate that FPLS is inefficient estimator (highest LRER) for this model for every value of σ_ε and ϕ . Also, SPR and SPRSC estimators are greater in LRER than SMG in most situations, especially the parameter is non-stochastic. Then SMG estimator is more efficient than SPR and SPRSC estimators and it is a good alternative estimator for MSPRSC in mixed-stochastic parameter models.

6. Conclusion

In this paper, GLS (FPLS, SPR, SPRSC, and MSPRSC) and SMG estimators of panel data models are examined when the errors are first-order serially correlated and the regression parameters are stochastic, non-stochastic, or mixed-stochastic. Efficiency comparisons for these estimators indicate that the SMG and stochastic parameter estimators (SPR, SPRSC, and MSPRSC) are equivalent when T sufficiently large. Moreover, the performance of all estimators above has been investigated by Monte Carlo simulations. The Monte Carlo results suggest that, in non-stochastic parameter model, the SMG estimator is more efficient than SPR and SPRSC estimators and then it is a good alternative estimator for FPLS. In stochastic parameter model, the FPLS estimator is not suitable for this model but SPR and SMG are good alternatives estimators for SPRSC in this model. While in mixed-stochastic parameter model, the SMG only is a good alternative estimator for MSPRSC. Consequently, it concludes that the SMG estimator is suitable to the three models, especially in small samples and the model includes one or more non-stochastic parameter.



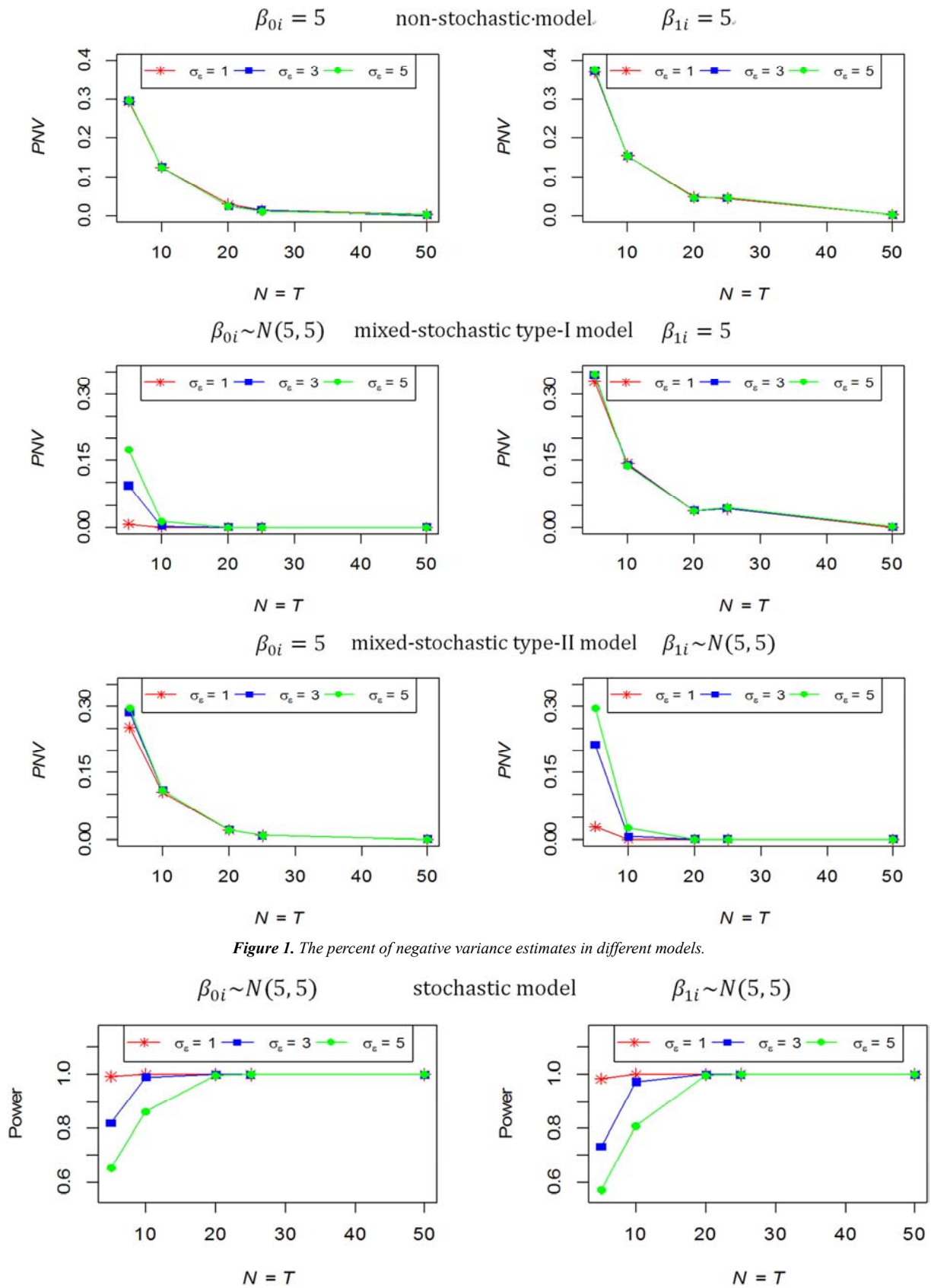


Figure 1. The percent of negative variance estimates in different models.

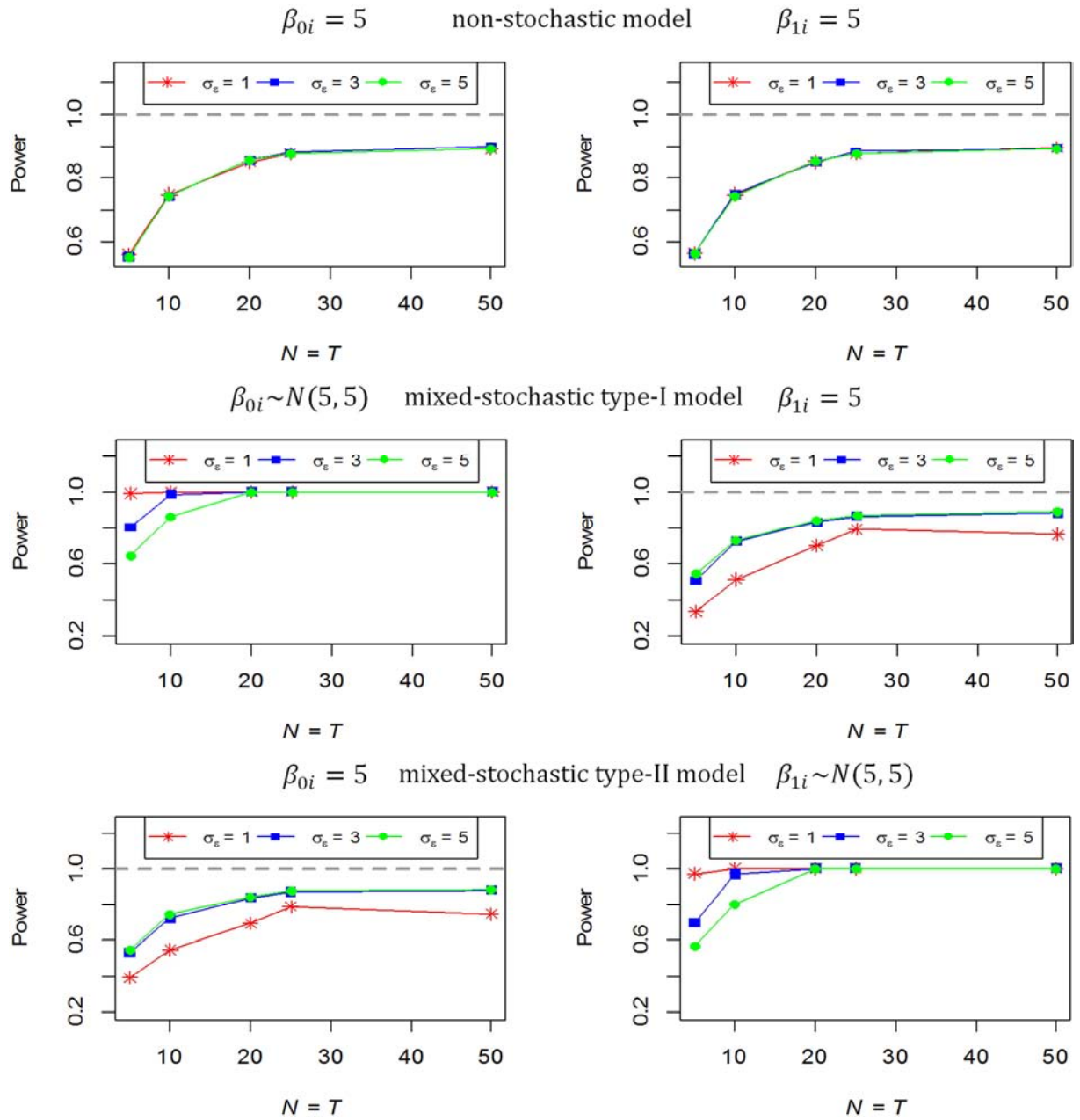
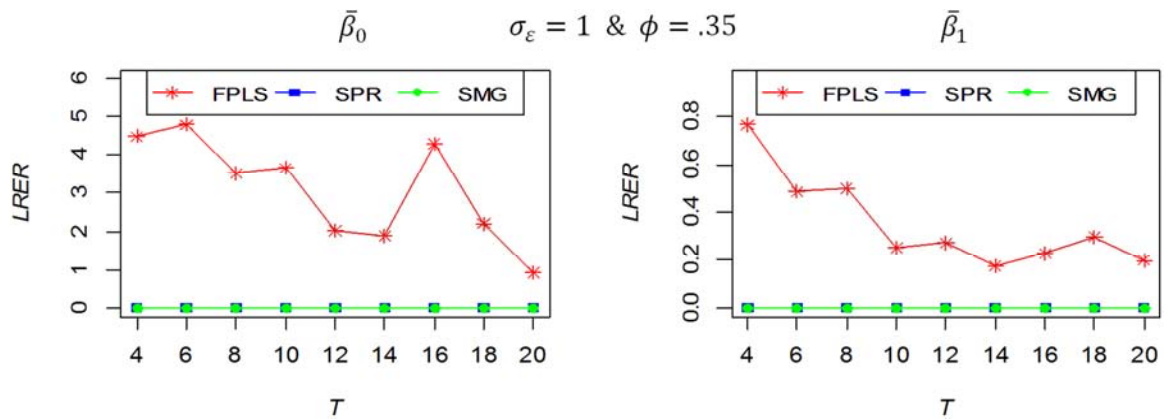


Figure 2. The power of Swamy's test for parameter homogeneity in different models.



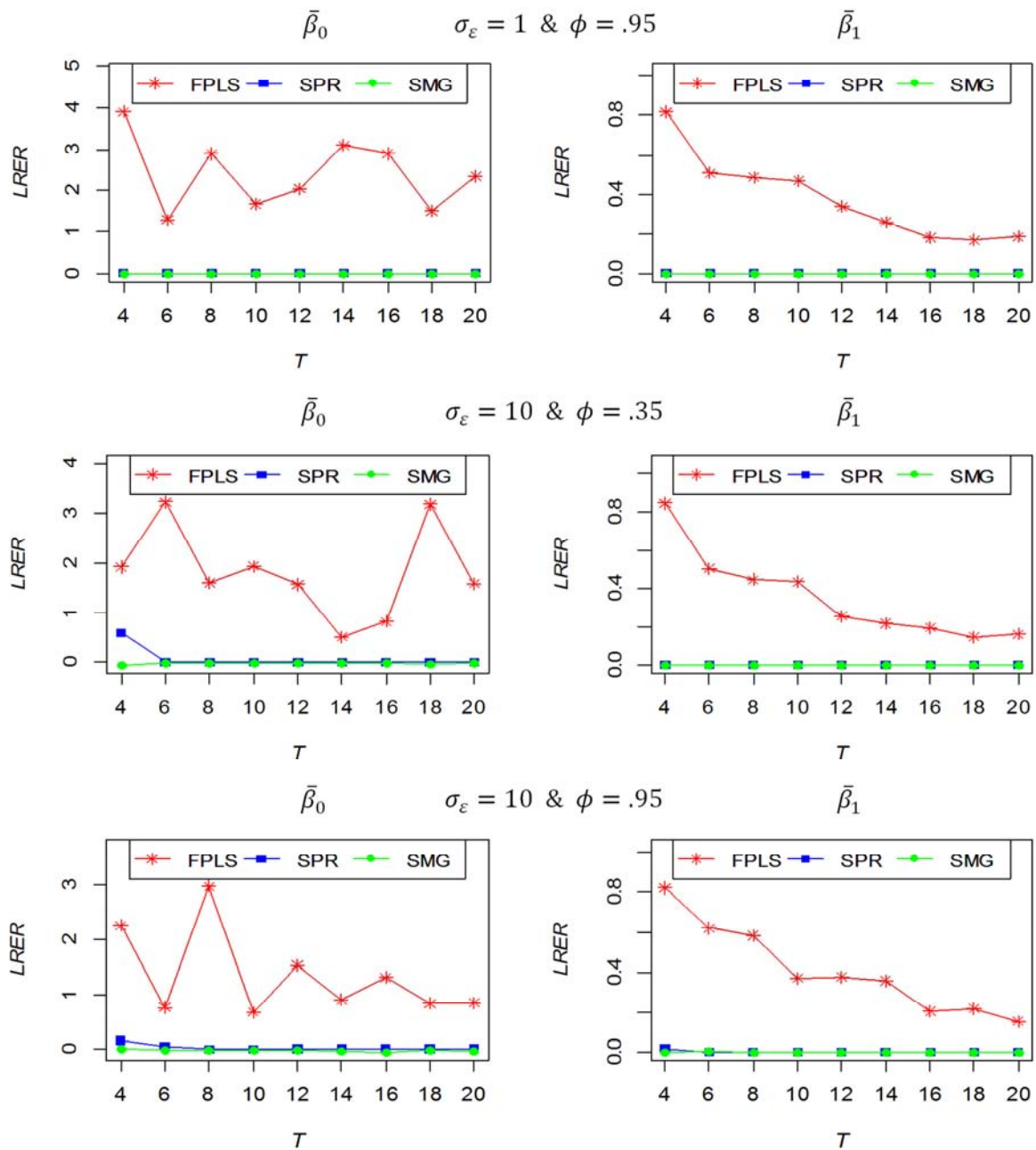
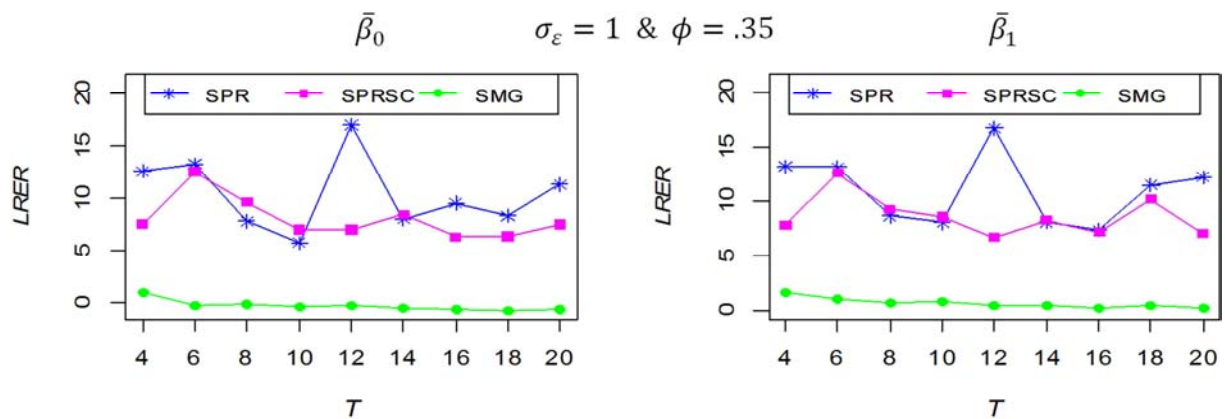


Figure 3. The relative efficiency for different estimators in stochastic parameter models.



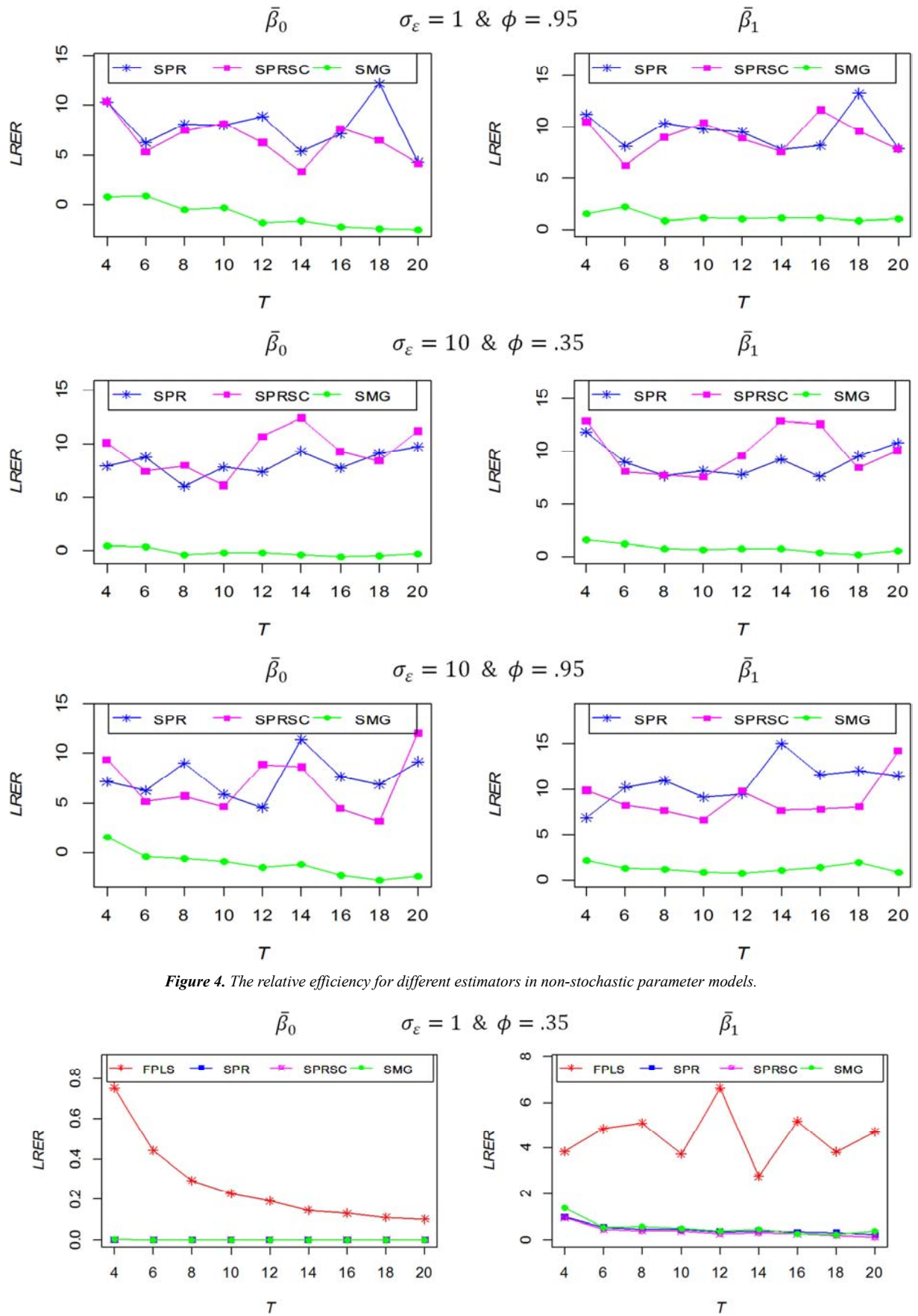


Figure 4. The relative efficiency for different estimators in non-stochastic parameter models.

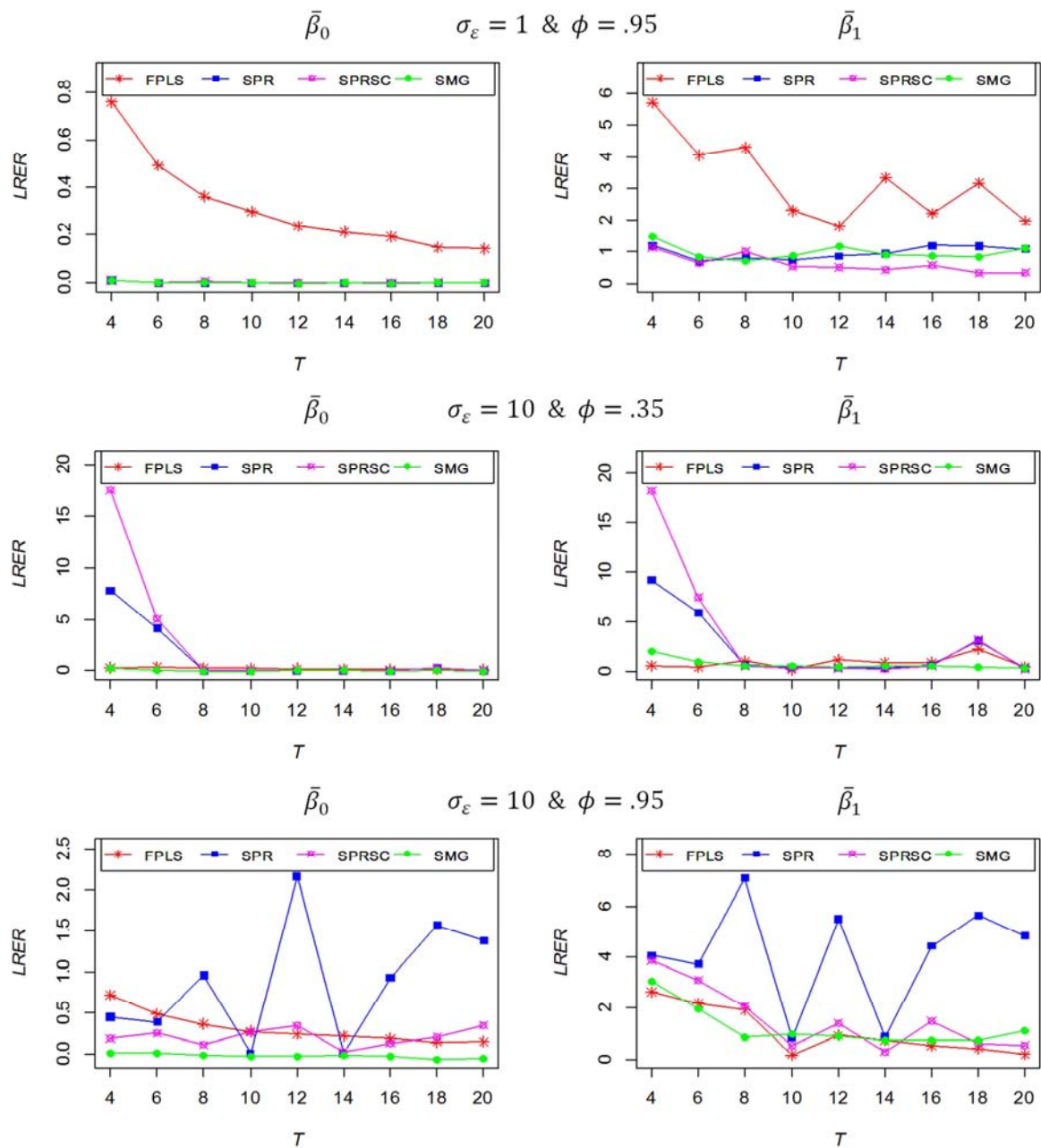
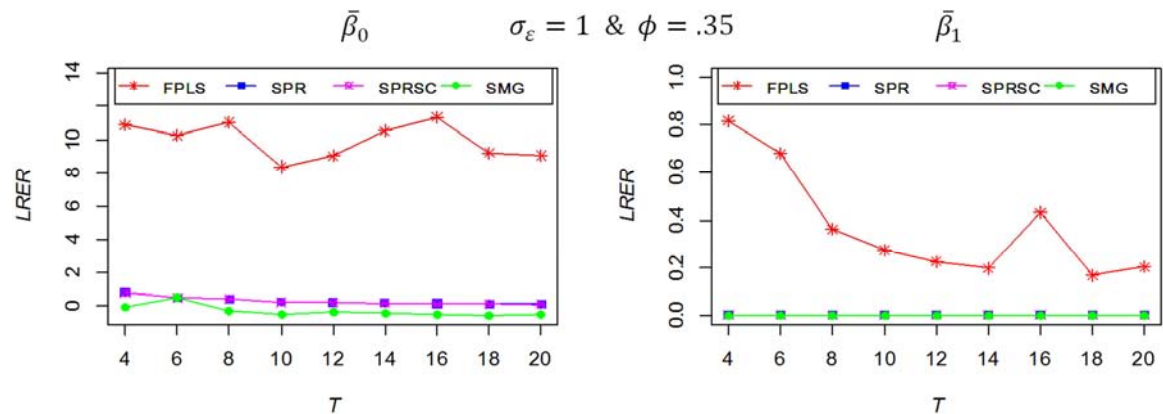


Figure 5. The relative efficiency for different estimators in mixed-stochastic parameter type-I models.



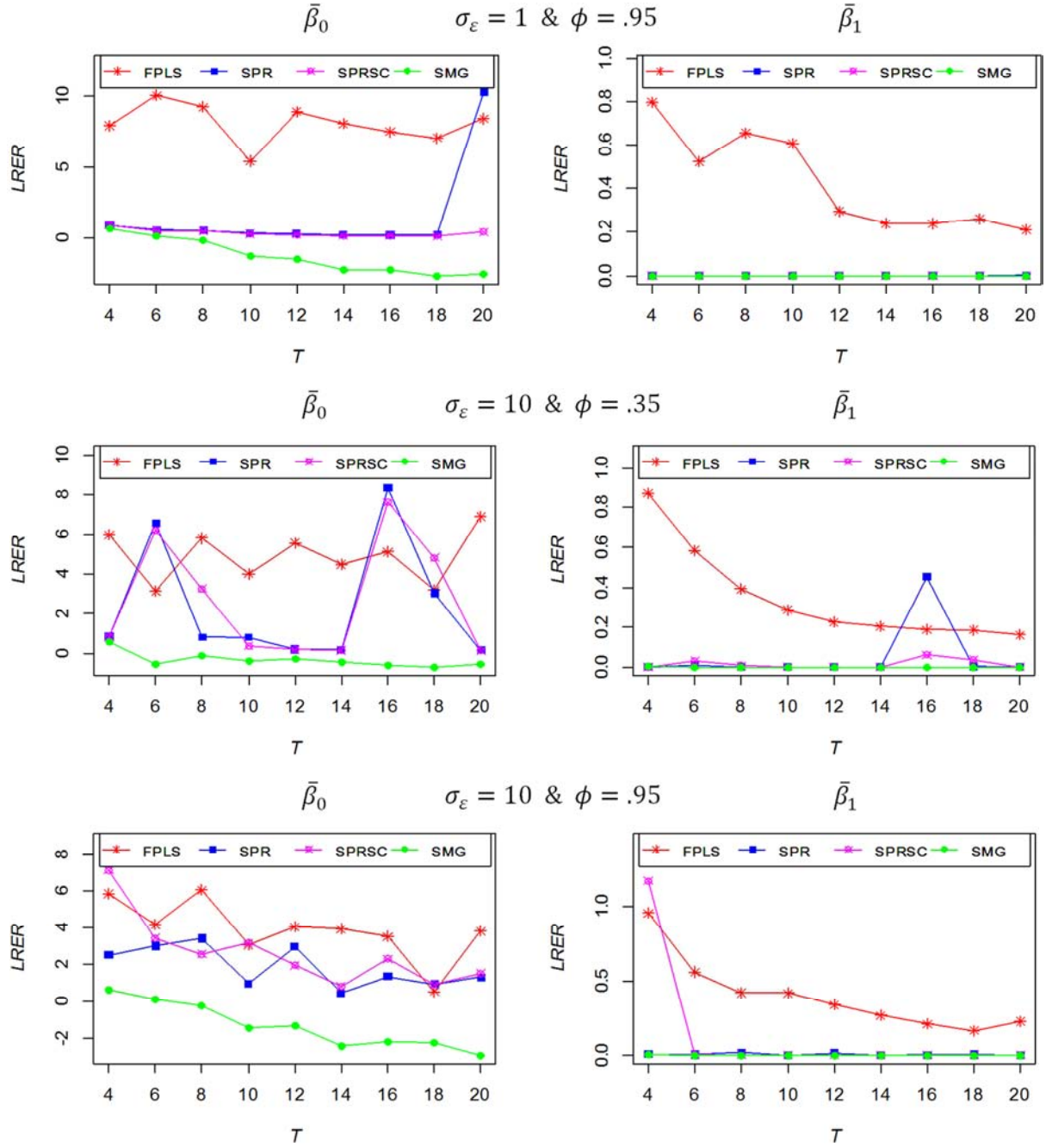


Figure 6. The relative efficiency for different estimators in mixed-stochastic parameter type-II models.

Appendix

A. 1 Proof of Lemma 1

a. Show that $E(\hat{\beta}_{SMG}) = \bar{\beta}$:

By substituting $\hat{\beta}_i = (X_i'X_i)^{-1}X_i'y_i$ into (17), it can get:

$$\hat{\beta}_{SMG} = \frac{1}{N} \sum_{i=1}^N (X_i'X_i)^{-1}X_i'y_i = \frac{1}{N} \sum_{i=1}^N (X_i'X_i)^{-1}X_i'(X_i\beta_i + u_i) = \frac{1}{N} \sum_{i=1}^N [\beta_i + (X_i'X_i)^{-1}X_i'u_i]. \quad (20)$$

Taking the expectation for (20) and using assumption 1, it can get:

$$E(\hat{\beta}_{SMG}) = \frac{1}{N} \sum_{i=1}^N \beta_i = \bar{\beta}.$$

b. Derive the variance-covariance matrix of $\hat{\beta}_{SMG}$:

Under assumption 4: $\beta_i = \bar{\beta} + \mu_i$. By adding $\hat{\beta}_i$ to the both sides:

$$\hat{\beta}_i = \bar{\beta} + \mu_i + \lambda_i, \quad (21)$$

where $\lambda_i = \hat{\beta}_i - \beta_i = (X_i' X_i)^{-1} X_i' u_i$. From (21), it can get:

$$\begin{aligned} \frac{1}{N} \sum_{i=1}^N \hat{\beta}_i &= \bar{\beta} + \frac{1}{N} \sum_{i=1}^N \mu_i + \frac{1}{N} \sum_{i=1}^N \lambda_i, \\ \hat{\beta}_{SMG} &= \bar{\beta} + \bar{\mu} + \bar{\lambda}, \end{aligned} \quad (22)$$

where $\bar{\mu} = \frac{1}{N} \sum_{i=1}^N \mu_i$ and $\bar{\lambda} = \frac{1}{N} \sum_{i=1}^N \lambda_i$. From (22) and using assumptions 1 to 4, it can get:

$$var(\hat{\beta}_{SMG}) = var(\bar{\mu}) + var(\bar{\lambda}) = \frac{1}{N} \Gamma + \frac{1}{N^2} \sum_{i=1}^N \sigma_{\varepsilon_i}^2 (X_i' X_i)^{-1} X_i' \Omega_{ii} X_i (X_i' X_i)^{-1}.$$

By using consistent estimators of Γ , $\sigma_{\varepsilon_i}^2$, and Ω_{ii} that defined above, it can get:

$$\widehat{var}(\hat{\beta}_{SMG}) = \frac{1}{N} \hat{\Gamma}^* + \frac{1}{N^2} \sum_{i=1}^N \hat{\sigma}_{\varepsilon_i}^2 (X_i' X_i)^{-1} X_i' \hat{\Omega}_{ii} X_i (X_i' X_i)^{-1}. \quad (23)$$

A. 2 Proof of Lemma 2:

Since $\text{plim}_{T \rightarrow \infty} T^{-1} X_i' X_i$ and $\text{plim}_{T \rightarrow \infty} T^{-1} X_i' \hat{\Omega}_{ii}^{-1} X_i$ are finite and positive definite for all i , therefore:

$$\text{plim}_{T \rightarrow \infty} \hat{\beta}_i = \text{plim}_{T \rightarrow \infty} \hat{\beta}_i^* = \beta_i, \text{plim}_{T \rightarrow \infty} \hat{\phi}_i = \phi_i, \text{plim}_{T \rightarrow \infty} \hat{\sigma}_{\varepsilon_i}^2 = \sigma_{\varepsilon_i}^2, \text{ and } \text{plim}_{T \rightarrow \infty} \hat{\Omega}_{ii} = \Omega_{ii}, \quad (24)$$

and then:

$$\text{plim}_{T \rightarrow \infty} \frac{1}{T} \hat{\sigma}_{\varepsilon_i}^2 T (X_i' \hat{\Omega}_{ii}^{-1} X_i)^{-1} = \text{plim}_{T \rightarrow \infty} \frac{1}{T} \hat{\sigma}_{\varepsilon_i}^2 T (X_i' X_i)^{-1} X_i' \hat{\Omega}_{ii} X_i (X_i' X_i)^{-1} = 0. \quad (25)$$

Using (24) and (25) in (5), it can get:

$$\text{plim}_{T \rightarrow \infty} \hat{\Gamma}^* = \frac{1}{N-1} \left(\sum_{i=1}^N \beta_i \beta_i' - \frac{1}{N} \sum_{i=1}^N \beta_i \sum_{i=1}^N \beta_i' \right) = \Gamma^+. \quad (26)$$

Using (24)-(26) in (23) and (4), it can get:

$$\text{plim}_{T \rightarrow \infty} \widehat{var}(\hat{\beta}_{SMG}) = \frac{1}{N} \text{plim}_{T \rightarrow \infty} \hat{\Gamma}^* + \frac{1}{N^2} \sum_{i=1}^N \text{plim}_{T \rightarrow \infty} \frac{1}{T} \hat{\sigma}_{\varepsilon_i}^2 T (X_i' X_i)^{-1} X_i' \hat{\Omega}_{ii} X_i (X_i' X_i)^{-1} = \frac{1}{N} \Gamma^+, \quad (27)$$

$$\text{plim}_{T \rightarrow \infty} \widehat{var}(\hat{\beta}_{SPRSC}) = \text{plim}_{T \rightarrow \infty} (X' \hat{\Lambda}^{*-1} X)^{-1} = [\sum_{i=1}^N \Gamma^{+ -1}]^{-1} = \frac{1}{N} \Gamma^+. \quad (28)$$

Similarly, using the results in (24)-(26) in case of SPR estimator:

$$\text{plim}_{T \rightarrow \infty} \widehat{var}(\hat{\beta}_{SPR}) = \text{plim}_{T \rightarrow \infty} \left[(X' \hat{\Lambda}^{-1} X)^{-1} X' \hat{\Lambda}^{-1} \hat{\Lambda}^* \hat{\Lambda}^{-1} X (X' \hat{\Lambda}^{-1} X)^{-1} \right] = \frac{1}{N} \Gamma^+. \quad (29)$$

From (27)-(29), it concludes that:

$$\text{plim}_{T \rightarrow \infty} \widehat{var}(\hat{\beta}_{SPRSC}) = \text{plim}_{T \rightarrow \infty} \widehat{var}(\hat{\beta}_{SPR}) = \text{plim}_{T \rightarrow \infty} \widehat{var}(\hat{\beta}_{SMG}) = \frac{1}{N} \Gamma^+.$$

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