



Constant Curvatures of Parallel Hypersurfaces in E_1^{n+1} Lorentz Space

Ayşe Yavuz¹, F. Nejat Ekmekci²

¹NecmettinErbakan University, Faculty of Education, Education of Mathematics, Konya, Turkey

²Ankara University, Faculty of Sciences, Department of Mathematics, Ankara, Turkey

Email address:

ayasar@konya.edu.tr (A. Yavuz), ekmekci@science.ankara.edu.tr (F. N. Ekmekci)

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Abstract: In this paper generalized Gaussian and mean curvatures of a parallel hypersurface in E^{n+1} Euclidean space will be denoted respectively by \bar{K} and \bar{H} , and Generalized Gaussian and mean curvatures of a parallel hypersurface in E_1^{n+1} Lorentz space will be denoted respectively by \bar{K} and \bar{H} . Generalized Gaussian curvature and mean curvatures, \bar{K} and \bar{H} of a parallel hypersurface in E^{n+1} Euclidean space are given in [2]. Before now we studied relations between curvatures of a hypersurface in Lorentzian space and we introduced higher order Gaussian curvatures of hypersurfaces in Lorentzian space. In this paper, by considering our last studies on higher order Gaussian and mean curvatures, we calculate the generalized \bar{K} and \bar{H} of a parallel hypersurface in E_1^{n+1} Lorentz space and we prove theorems about generalized \bar{K} and \bar{H} of a parallel hypersurface in E_1^{n+1} Lorentz space.

Keywords: Gaussian Curvatures, Mean Curvatures, Parallel Hypersurface, Higher Order Gaussian Curvatures

1. Introduction

Suppose that V is an n -dimensional vector space over the real numbers for $n = 1, 2, \dots$

A symmetric bilinear form $\beta: V \times V \rightarrow \mathbb{R}$ is

i) positive (resp. negative) definite if and only if $\bar{w} \neq 0$ implies $\beta(\bar{w}, \bar{w}) > 0$ (resp. $\beta(\bar{w}, \bar{w}) < 0$) for all \bar{w} in V ,

ii) non-degenerate if and only if $\beta(\bar{w}, \bar{z}) = 0$ for all \bar{z} in V implies that $\bar{w} = \bar{0}$, and

iii) indefinite if and only if there exist \bar{w} and \bar{z} in V with $\beta(\bar{w}, \bar{w}) > 0$ and $\beta(\bar{z}, \bar{z}) < 0$.

A non-degenerate, symmetric bilinear form β is called a scalar product. For an indefinite scalar product β on V , a vector $\bar{w} \neq \bar{0}$ is said to be (see [5], p. 4)

a) spacelike if and only if $\beta(\bar{w}, \bar{w}) > 0$,

b) timelike if and only if $\beta(\bar{w}, \bar{w}) < 0$, and

c) null if and only if $\beta(\bar{w}, \bar{w}) = 0$.

2. Basic Concepts

Definition 1.1.

Let U be a unit normal vector field on semi-Riemannian hypersurfaces $M \subset \bar{M}$. The $(1,1)$ tensor field S on

M such that

$$\langle S(V), W \rangle = \langle II(V, W), U \rangle \text{ for all } V, W \in \mathfrak{X}(M)$$

is called the shape operator of $M \subset \bar{M}$ derived from U . (see [1], p. 107)

Definition 1.2.

Let M and \bar{M} be two hypersurfaces in E_1^{n+1} with unit normal vectors N of M and \bar{N} of \bar{M} .

$$N = \sum_{i=1}^n \alpha_i \frac{\partial}{\partial x_i}$$

where each α_i is a C^∞ function of M . If there exists a function f , from M to \bar{M} such that

$$f: M \rightarrow \bar{M}$$

$$P \rightarrow f(P) = P + rN_P$$

Then \bar{M} is called parallel hypersurface of M , where $r \in \mathbb{R}$. (see [3])

Definition 1.3.

Let M be a hypersurface in E_1^{n+1} and $T_M(P)$ be a tangent space on M , at $P \in M$. If S_P denotes the shape operator on M , then

$$S_P: T_M(P) \rightarrow T_M(P)$$

is a linear mapping. If we denote the characteristic vectors by k_1, k_2, \dots, k_n and the corresponding characteristic vectors by x_1, x_2, \dots, x_n of S_P then k_1, k_2, \dots, k_n are the principal curvatures and x_1, x_2, \dots, x_n are the principal directions of M , at $P \in M$. On the other hand, if we use the notions $\varepsilon_{i \neq 1} = +1$ and $\varepsilon_1 = \pm 1$

$$\begin{aligned} K_1^{(n)}(k_1, k_2, \dots, k_n) &= \varepsilon_1 k_1 + \sum_{i=2}^n \varepsilon_i k_i \\ K_2^{(n)}(k_1, k_2, \dots, k_n) &= \sum_{i=1 < j}^n \varepsilon_i k_i k_j + \sum_{i \neq 1 < j}^n \varepsilon_i k_i k_j \\ K_3^{(n)}(k_1, k_2, \dots, k_n) &= \sum_{i=1 < j < t}^n \varepsilon_i k_i k_j k_t + \sum_{i \neq 1 < j < t}^n \varepsilon_i k_i k_j k_t \\ &\vdots \\ K_n^{(n)}(k_1, k_2, \dots, k_n) &= \varepsilon_1 \prod_{i=1}^n k_i \end{aligned}$$

then the characteristic polynomial of $S(P)$ becomes

$$P_{S(P)}(k) = k^n + (-1)K_1^{(n)}k^{n-1} + \dots + (-1)^n K_n^{(n)}$$

and K_1, K_2, \dots, K_n are uniquely determined, where the functions K_i are called the higher ordered Gaussian curvatures of the hypersurface M (see[3]).

Theorem 1.1.

Let \bar{M} be a parallel surface of the surface $M \subset E_1^3$. Let the Gaussian curvature and mean curvature of M be denoted by K and H at $P \in M$, respectively. Gaussian curvature and mean curvature of \bar{M} are denoted by \bar{K} and \bar{H} . Then we know that

i) N_P is timelike

$$\begin{aligned} \bar{K} &= \frac{K}{1 + 2rH - r^2K} \\ \bar{H} &= \frac{H - rK}{1 + 2rH - r^2K} \end{aligned}$$

ii) N_P is spacelike

$$\begin{aligned} \bar{K} &= \frac{K}{1 + 2rH + r^2K} \\ \bar{H} &= \frac{H + rK}{1 + 2rH + r^2K} \end{aligned}$$

[3].

Theorem 1.2.

Let M be a hypersurface in E_1^{n+1} , K_1, K_2, \dots, K_n these-called higher order Gaussian curvatures and k_1, k_2, \dots, k_n the principal curvatures at the point $P \in M$. Let us define a function

$$\varphi: M \rightarrow R$$

$$P \rightarrow \varphi(P) = \varphi(r, k_1, k_2, \dots, k_n)$$

$$= \prod_{i=1}^n (1 + \varepsilon_i r k_i)$$

such that $\varepsilon_{i \neq 1} = +1$ and $\varepsilon_1 = \pm 1$

$$\begin{aligned} &\varphi(r, k_1, k_2, \dots, k_n) \\ &= 1 + r \left(\varepsilon_1 k_1 + \sum_{i=2}^n \varepsilon_i k_i \right) \\ &+ r^2 \left(\sum_{i=1 < j}^n \varepsilon_i k_i k_j + \sum_{i \neq 1 < j}^n \varepsilon_i k_i k_j \right) \\ &+ r^3 \left(\sum_{i=1 < j < t}^n \varepsilon_i k_i k_j k_t + \sum_{i \neq 1 < j < t}^n \varepsilon_i k_i k_j k_t \right) \\ &+ \dots + r^n \left(\varepsilon_1 \prod_{i=1}^n k_i \right) \end{aligned}$$

or

$$\varphi(k_1, k_2, \dots, k_n) = rK_1 + r^2K_2 + \dots + r^n K_n$$

[4].

Theorem 1.3.

Let M be a hypersurface in E_1^{n+1} , K_1, K_2, \dots, K_n are the so-called higher order Gaussian curvatures and k_1, k_2, \dots, k_n are the principal curvatures at the point $P \in M$. \bar{K} and \bar{H} are generalized Gaussian and mean curvatures of \bar{M} at the point $f(P)$. Suppose that the function

$$\varphi: M \rightarrow R$$

$$P \rightarrow \varphi(P) = \varphi(r, k_1, k_2, \dots, k_n)$$

$$= \prod_{i=1}^n (1 + \varepsilon_i r k_i)$$

such that $\varepsilon_i = +1$ and $\varepsilon_1 = \pm 1$ ($i \neq 1$).

Then we have

$$\bar{K} = \varepsilon \frac{\frac{\partial^n \varphi(r, k_1, k_2, \dots, k_n)}{\partial r^n}}{n! \varphi(r, k_1, k_2, \dots, k_n)}$$

$$\bar{H} = \frac{\frac{\partial \varphi(r, k_1, k_2, \dots, k_n)}{\partial r}}{\varphi(r, k_1, k_2, \dots, k_n)}.$$

Proof

If k is principal curvatures of M at the point P in direction X , then $\frac{k}{1+rk}$ is the principal curvatures of \bar{M} at the point $f(P)$ in direction $f_*(X)$, that is, $\bar{S}(f_*(X)) = \frac{k}{1+rk} f_*(X)$ which means that f preserves principal directions, where f_* is the differential of f and we know that

$$\bar{S}(f_*(X_1)) = \frac{k_1}{1+rk_1} f_*(X_1)$$

$$\bar{S}(f_*(X_2)) = \frac{k_2}{1+rk_2} f_*(X_2)$$

$$\bar{S}(f_*(X_n)) = \frac{k_n}{1+rk_n} f_*$$

then we know that the shape operator of \bar{M} is

$$\bar{S} = \begin{bmatrix} \frac{\varepsilon_1 k_1}{1+r\varepsilon_1 k_1} & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \dots & \frac{\varepsilon_n k_n}{1+r\varepsilon_n k_n} \end{bmatrix}$$

and

$$\begin{aligned} \bar{K} &= \det S_r \\ &= \varepsilon \left(\frac{\varepsilon_1 k_1}{1+r\varepsilon_1 k_1} \dots \frac{\varepsilon_n k_n}{1+r\varepsilon_n k_n} \right) \\ &= \varepsilon \frac{\varepsilon_1 k_1 \varepsilon_2 k_2 \dots \varepsilon_n k_n}{\prod_{i=1}^n (1+\varepsilon_i r k_i)} \\ &= \varepsilon \frac{\prod_{i=1}^n \varepsilon_i k_i}{\prod_{i=1}^n (1+\varepsilon_i r k_i)} \end{aligned}$$

We multiply the right sides of the equation with $n!$

$$\begin{aligned} &= \varepsilon \frac{n! \prod_{i=1}^n \varepsilon_i k_i}{n! \prod_{i=1}^n (1+\varepsilon_i r k_i)} \\ &= \varepsilon \frac{n! K_n}{n! \varphi(r, k_1, k_2, \dots, k_n)} \end{aligned}$$

and we derivate to $\varphi(r, k_1, k_2, \dots, k_n)$ order n according to r

$$\begin{aligned} \frac{\partial \varphi(r, k_1, k_2, \dots, k_n)}{\partial r} &= \frac{\partial (1 + rK_1 + r^2 K_2 + \dots + r^n K_n)}{\partial r} \\ &= K_1 + 2rK_2 + \dots + nr^{n-1} K_n \\ \frac{\partial^2 \varphi(r, k_1, k_2, \dots, k_n)}{\partial r^2} &= \frac{\partial (K_1 + 2rK_2 + \dots + nr^{n-1} K_n)}{\partial r} \\ &= 2K_2 + \dots + n(n-1)r^{n-2} K_n \end{aligned}$$

and we continue to derivation, we have

$$\frac{\partial^n \varphi(r, k_1, k_2, \dots, k_n)}{\partial r^n} = n! K_n$$

and we obtain with implying equality

$$\bar{K} = \varepsilon \frac{\frac{\partial^n \varphi(r, k_1, k_2, \dots, k_n)}{\partial r^n}}{n! \varphi(r, k_1, k_2, \dots, k_n)}.$$

We proof the other equality

$$\begin{aligned} \bar{H} &= \frac{1}{n} I_Z S_r \\ &= \frac{1}{n} \left(\frac{\varepsilon_1 k_1}{1+r\varepsilon_1 k_1} + \dots + \frac{\varepsilon_n k_n}{1+r\varepsilon_n k_n} \right) \\ &= \frac{1}{n} \left(\frac{\varepsilon_1 k_1 \prod_{i=2}^n (1+\varepsilon_i r k_i) + \dots + \varepsilon_n k_n \prod_{i=1}^{n-1} (\varepsilon_i r k_i)}{\prod_{i=1}^n (1+\varepsilon_i r k_i)} \right) \end{aligned}$$

We derivate according to r

$$\begin{aligned} \frac{\partial \varphi(r, k_1, k_2, \dots, k_n)}{\partial r} &= \frac{\partial (\prod_{i=1}^n (1+\varepsilon_i r k_i))}{\partial r} \\ &= \frac{\partial ((1+\varepsilon_1 r k_1)(1+\varepsilon_2 r k_2) \dots (1+\varepsilon_n r k_n))}{\partial r} \\ &= \varepsilon_1 k_1 (1+\varepsilon_2 r k_2)(1+\varepsilon_3 r k_3) \dots (1+\varepsilon_n r k_n) \\ &\quad + (1+\varepsilon_1 r k_1) \varepsilon_2 k_2 (1+\varepsilon_3 r k_3) \dots (1+\varepsilon_n r k_n) \\ &\quad + (1+\varepsilon_1 r k_1)(1+\varepsilon_2 r k_2) \varepsilon_3 k_3 \dots (1+\varepsilon_n r k_n) \\ &\quad \dots \\ &\quad + (1+\varepsilon_1 r k_1)(1+\varepsilon_2 r k_2)(1+\varepsilon_3 r k_3) \dots (1+\varepsilon_{n-1} r k_{n-1}) \varepsilon_n k_n \\ &= \varepsilon_1 k_1 \prod_{i=2}^n (1+\varepsilon_i r k_i) + \varepsilon_2 k_2 (1+\varepsilon_1 r k_1) \prod_{i=3}^n (1+\varepsilon_i r k_i) \\ &\quad + \dots + \varepsilon_n k_n \prod_{i=1}^{n-1} (\varepsilon_i r k_i) \end{aligned}$$

So we have last equation and we obtain that

$$\bar{H} = \frac{1}{n} \frac{\frac{\partial \varphi(r, k_1, k_2, \dots, k_n)}{\partial r}}{\varphi(r, k_1, k_2, \dots, k_n)}.$$

3. Generalized Theorems

Theorem 2.1.

Let \bar{M} be a parallel hypersurface in E_1^{n+1} and K_1, K_2, \dots, K_n are the so-called higher order Gaussian curvatures of M at the point $P \in M$, and let

$$\sum_{i=1}^{n-1} r^i K_i = -1$$

then the generalized Gaussian curvature of \bar{M} is

$$\bar{K} = \varepsilon \frac{1}{r^n}.$$

Proof

We know that the generalized Gaussian curvature of a parallel hypersurface is given by

$$\begin{aligned} \bar{K} &= \varepsilon \frac{\frac{\partial^n \varphi(r, k_1, k_2, \dots, k_n)}{\partial r^n}}{n! \varphi(r, k_1, k_2, \dots, k_n)} \\ &= \varepsilon \frac{\prod_{i=1}^n \varepsilon_i k_i}{1 + rK_1 + r^2K_2 + \dots + r^nK_n} \end{aligned}$$

since we have,

$$\sum_{i=1}^{n-1} r^i K_i = -1$$

then

$$\sum_{i=1}^{n-1} r^i K_i = 1 + rK_1 + r^2K_2 + \dots + r^{n-1}K_{n-1} = -1$$

and finally we get

$$\begin{aligned} \bar{K} &= \varepsilon \frac{\prod_{i=1}^n \varepsilon_i k_i}{r^n K_n} \\ \bar{K} &= \varepsilon \frac{\prod_{i=1}^n \varepsilon_i k_i}{r^n \prod_{i=1}^n \varepsilon_i k_i} = \varepsilon \frac{1}{r^n}. \end{aligned}$$

Theorem 2.2.

Let \bar{M} be a parallel hypersurface in E_1^{n+1} and K_1, K_2, \dots, K_n so-called higher order Gaussian curvatures of M , at the point $P \in M$ and let

$$\sum_{i=1}^n (i-1) r^i K_i = 1$$

then generalized Gaussian curvature of \bar{M} is

$$\bar{H} = \frac{1}{r}.$$

Proof:

We know that the generalized mean curvature of a parallel hypersurface is given by

$$\begin{aligned} \bar{H} &= \frac{\frac{\partial \varphi(r, k_1, k_2, \dots, k_n)}{\partial r}}{\varphi(r, k_1, k_2, \dots, k_n)} \\ &= \frac{K_1 + 2rK_2 + \dots + nr^{n-1}K_n}{1 + rK_1 + r^2K_2 + \dots + r^nK_n} \end{aligned}$$

$$= \frac{1}{r} \frac{rK_1 + 2r^2K_2 + \dots + nr^nK_n}{1 + rK_1 + r^2K_2 + \dots + r^nK_n}$$

$$\sum_{i=1}^n r^i K_i = 1 + rK_1 + r^2K_2 + \dots + r^nK_n$$

since we have that

$$\bar{H} = \frac{1}{r} \frac{\sum_{i=1}^n i r^i K_i}{1 + \sum_{i=1}^n r^i K_i}$$

we can write that

$$\sum_{i=1}^n r^i K_i = \sum_{i=1}^n (i-1) r^i K_i + \sum_{i=1}^n r^i K_i$$

so we obtain that

$$\bar{H} = \frac{1}{r} \frac{\sum_{i=1}^n (i-1) r^i K_i + \sum_{i=1}^n r^i K_i}{1 + \sum_{i=1}^n r^i K_i}$$

If we add and subtract 1 in the numerator, the above equality does not change

$$\begin{aligned} \bar{H} &= \frac{1}{r} \frac{1 + \sum_{i=1}^n (i-1) r^i K_i + \sum_{i=1}^n r^i K_i - 1}{1 + \sum_{i=1}^n r^i K_i} \\ &= \frac{1}{r} \left(1 - \left(\frac{1 - \sum_{i=1}^n (i-1) r^i K_i}{1 + \sum_{i=1}^n r^i K_i} \right) \right) \\ &= \frac{1}{r} \left(1 - \left(\frac{1-1}{1 + \sum_{i=1}^n r^i K_i} \right) \right) \end{aligned}$$

and we have that

$$\bar{H} = \frac{1}{r}.$$

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